# TECHNICAL SPECIFICATION

## ISO/TS 16610-22

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## Geometrical product specifications (GPS) — Filtration —

Part 22:

Linear profile filters: Spline filters

Spécification géométrique des produits (GPS) — Filtrage — Partie 22: Filtres de profil linéaires: Filtres splines



Reference number ISO/TS 16610-22:2006(E)

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#### **Foreword**

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ISO/TS 16610-22 was prepared by Technical Committee ISO/TC 213, Dimensional and geometrical product specifications and verification.

ISO/TS 16610 consists of the following parts, under the general title *Geometrical product specifications* (GPS) — Filtration:

- Part 1: Overview and basic concepts
- Part 20: Linear profile filters: Basic concepts
- Part 22: Linear profile filters: Spline filters
- Part 29: Linear profile filters: Spline wavelets
- Part 31: Robust profile filters: Gaussian regression filters
- Part 32: Robust profile filters: Spline filters
- Part 40: Morphological profile filters: Basic concepts

— Part 41: Morphological profile filters: Disk and horizontal line-segment filters Part 49: Morphological profile filters: Scale space techniques The following parts are under preparation: Part 21: Linear profile filters: Gaussian filters — Part 26: Linear profile filters: Filtration on nominally orthogonal grid planar data sets — Part 27: Linear profile filters: Filtration on nominally orthogonal grid cylindrical data sets — Part 30: Robust profile filters: Basic concepts Part 42: Morphological profile filters: Motif filters Part 60: Linear areal filters: Basic concepts — Part 61: Linear areal filters: Gaussian filters — Part 62: Linear areal filters: Spline filters — Part 69: Linear areal filters: Spline wavelets Part 70: Robust areal filters: Basic concepts Part 71: Robust areal filters: Gaussian regression filters Part 72: Robust areal filters: Spline filters Part 80: Morphological areal filters: Basic concepts — Part 81: Morphological areal filters: Sphere and horizontal planar segment filters

— Part 82: Morphological areal filters: Motif filters

Part 89: Morphological areal filters: Scale space techniques

#### Introduction

This part of ISO/TS 16610 is a geometrical product specification (GPS) Technical Specification and is to be regarded as a global GPS Technical Report (see ISO/TR 14638). It influences the chain links 3 and 5 of all chains of standards.

For more detailed information about the relation of this part of ISO/TS 16610 to the GPS matrix model, see Annex F.

This part of ISO/TS 16610 develops the terminology and concepts of spline filters.

The spline filter has an advantage over a conventional phase correct filter in that for open profiles, the ends of the measured profile are still usable.

## Geometrical product specifications (GPS) — Filtration —

#### **Part 22:**

**Linear profile filters: Spline filters** 

#### 1 Scope

This part of ISO/TS 16610 specifies spline filters for the filtration of profiles. It specifies in particular how to separate the long and short wave component of a profile.

#### 2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO/TS 16610-1:2006, Geometrical product specifications (GPS) — Filtration — Part 1: Overview and basic terminology

ISO/TS 16610-20:2006, Geometrical product specifications (GPS) — Filtration — Part 20: Linear profile filters: Basic concepts

International vocabulary of basic and general terms in metrology (VIM). BIPM, IEC, IFCC, ISO, IUPAC, IUPAP, OIML, 2nd ed., 1993

#### 3 Terms and definitions

For the purposes of this document, the terms and definitions given in VIM, ISO/TS 16610-1 and ISO/TS 16610-20, and the following apply.

#### 3.1

#### spline

linear combination of piecewise polynomials, with a smooth fit between the pieces

NOTE The degree of the spline is equal to the degree of the polynomial of the highest degree used, e.g. a cubic spline is made of cubic polynomials.

#### 3.2

#### cardinal spline

basic function of the space of splines (3.1) with infinite support

#### 3.3

#### natural spline

**spline** (3.1) which is a straight line beyond the end points

#### 3.4

#### spline profile filter

linear profile filter based on **splines** (3.1)

NOTE For the purposes of this part of ISO/TS 16610, the result of the low-pass filtering is a spline.

#### Spline profile filters

#### General

For a spline filter to conform with this part of ISO/TS 16610, it shall satisfy the filter equations given in 4.3.2, for open profiles, and 4.3.3, for closed profiles.

A comparison with Gaussian filters is given in Annex B, and illustrative examples are given in Annex C. A concept diagram for the concepts of spline filters is given in Annex D, and the relationship to the filtration matrix model is given in Annex E.

#### 4.2 Weighting function

The weighting function of a spline profile filter cannot be given by a simple closed formula. Filter equations are therefore used instead of weighting functions to describe the spline profile filters. However, where necessary, a numerical calculation of the weighting function for a spline profile filter is always possible. If the sampling interval  $\Delta x$  is small enough, and the spline profile filter is based on cardinal cubic splines, the weighting function s(x), with a default value of  $\beta = 0$ , can be approximated by the continuous function

$$s(x) = \frac{\pi}{\lambda_{c}} \sin\left(\sqrt{2} \frac{\pi}{\lambda_{c}} |x| + \frac{\pi}{4}\right) \exp\left(-\sqrt{2} \frac{\pi}{\lambda_{c}} |x|\right)$$
 (1)

This is the weighting function of the ideal spline profile filter, based on cardinal cubic splines. A graph of this function is shown in Figure 1.

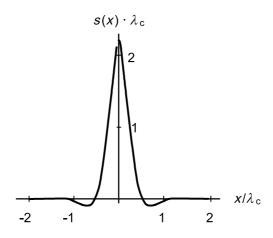


Figure 1 — Weighting function of the ideal spline profile filter, based on cardinal cubic splines

#### 4.3 Filter equations

#### 4.3.1 General

The following filter equations for spline profile filters are based on cardinal cubic splines (for more details, see [1] and [2]).

#### 4.3.2 Filter equation for the non-periodic spline profile filter

Non-periodic spline profile filters should be used in cases of filtering open profiles. The filter equation for the non-periodic spline profile filter is given by

$$\left[1+\beta\alpha^{2}P+(1-\beta)\alpha^{4}Q\right]w=z$$
(2)

with the matrix

$$P = \begin{pmatrix} 1 & -1 & & & & \\ -1 & 2 & -1 & & & & \\ & -1 & 2 & -1 & & & \\ & & \ddots & \ddots & \ddots & & \\ & & -1 & 2 & -1 & & \\ & & & -1 & 2 & -1 & \\ & & & & -1 & 1 & \end{pmatrix} \quad Q = \begin{pmatrix} 1 & -2 & 1 & & & \\ -2 & 5 & -4 & 1 & & & \\ 1 & -4 & 6 & -4 & 1 & & \\ & & \ddots & \ddots & \ddots & \ddots & \ddots & \\ & & 1 & -4 & 6 & -4 & 1 \\ & & & 1 & -4 & 5 & -2 \\ & & & & 1 & -2 & 1 \end{pmatrix}$$
(3)

with n rows, n columns and the parameters

$$\alpha = \frac{1}{2\sin\frac{\pi\Delta x}{\lambda_{c}}} \text{ and } 0 \leqslant \beta \leqslant 1$$
 (4)

where

- *n* is the number of extracted data values of the profile;
- z is the vector of dimension n of the profile values before filtering;
- w is the vector of dimension n of the profile values in the filtered profile;
- $\lambda_{c}$  is the cut-off wavelength of the profile filter;
- $\Delta x$  is the sampling interval.
- NOTE 1 The vector w gives the profile values of the long wave component. The short wave component r can be obtained by the difference vector r = z w, i.e. by subtracting the long wave component values obtained by the filtering process from the extracted data values of the profile.
- NOTE 2  $\beta$  is called the tension parameter, and controls how tightly the spline curve fits through the data points.
- NOTE 3 Algorithms to solve matrix equations can be found in [6].

#### Filter equation for the periodic spline profile filter

Periodic spline profile filters should be used in cases of filtering closed profiles. The filter equation for the periodic spline profile filter is given by

$$\left[1 + \beta \alpha^2 \tilde{P} + (1 - \beta) \alpha^4 \tilde{Q}\right] \tilde{w} = \tilde{z}$$
(5)

with the matrix

$$\tilde{P} = \begin{pmatrix}
2 & -1 & & & -1 \\
-1 & 2 & -1 & & & \\
& -1 & 2 & -1 & & \\
& & \ddots & \ddots & \ddots & \ddots & \\
& & -1 & 2 & -1 & \\
& & & -1 & 2 & -1 \\
-1 & & & & -1 & 2
\end{pmatrix}
\qquad
\tilde{Q} = \begin{pmatrix}
6 & -4 & 1 & & 1 & -4 \\
-4 & 6 & -4 & 1 & & 1 \\
1 & -4 & 6 & -4 & 1 & & \\
& & \ddots & \ddots & \ddots & \ddots & \\
& & & 1 & -4 & 6 & -4 & 1 \\
1 & & & & 1 & -4 & 6 & -4 \\
-4 & 1 & & & 1 & -4 & 6
\end{pmatrix}$$
(6)

with n rows, n columns and the parameters

$$\alpha = \frac{1}{2\sin\frac{\pi\Delta x}{\lambda_c}} \text{ and } 0 \leqslant \beta \leqslant 1$$
 (7)

where

- is the number of extracted data values of the profile;
- $\tilde{z}$ is the vector of dimension n of the profile values before filtering;
- is the vector of dimension n of the profile values in the filtered profile;
- is the cut-off wavelength of the profile filter;
- $\Delta x$  is the sampling interval.
- The vector  $\tilde{w}$  gives the profile values of the long wave component. The short wave component  $\tilde{r}$  can be obtained by the difference vector  $\tilde{r}=\tilde{z}-\tilde{w}$ , i.e. by subtracting the long wave component values obtained by the filtering process from the extracted data values of the profile.
- NOTE 2  $\beta$  is called the tension parameter, and controls how tightly the spline curve fits through the data points.
- NOTE 3 Algorithms to solve matrix equations can be found in [6].

#### **Transmission characteristics**

#### 4.4.1 General

The following transmission characteristics for spline profile filters are based on cardinal cubic splines. For more details, see [3]. For the influence of the sampling interval, see Annex A.

#### 4.4.2 Transmission characteristic of the long wave profile component

The filter characteristic (see Figure 2) is determined from the filter equations of the spline profile filter by means of the Fourier transformation. The filter characteristic for the long wave component is approximated (for very small  $\Delta x$ ) by the following equation:

$$\frac{a_1}{a_0} = \left[ 1 + \beta \alpha^2 \sin^2 \frac{\pi \Delta x}{\lambda} + 16 \left( 1 - \beta \right) \alpha^4 \sin^4 \frac{\pi \Delta x}{\lambda} \right]^{-1}$$
 (8)

where

 $a_0$  is the amplitude of the sinusoidal profile before filtering;

a<sub>1</sub> is the amplitude of the sinusoidal profile in the long wave component;

 $\lambda$  is the wavelength of the sine profile  $(\lambda \ge 2\Delta x)$ ;

 $\Delta x$  is the sampling interval.

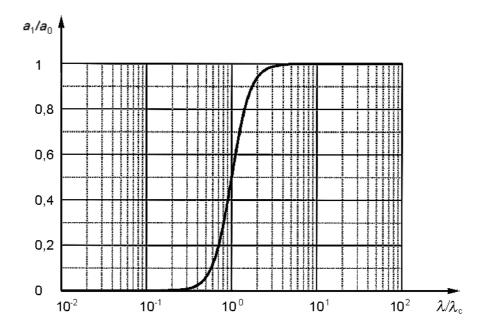


Figure 2 — Transmission characteristic for the long wave profile component  $(\beta = 0; \Delta x = \lambda_c/200)$ 

#### 4.4.3 Transmission characteristic of the short wave profile component

The transmission characteristic of the short wave profile component is complementary to the transmission characteristic of the long wave profile component. The short wave profile component is the difference between the surface profile and the long wave profile component. The filter characteristic for the short wave profile component (see Figure 3) has the following equation:

$$\frac{a_2}{a_0} = 1 - \frac{a_1}{a_0} = \left[ 4\beta\alpha^2 \sin^2\frac{\pi\Delta x}{\lambda} + 16(1-\beta)\alpha^4 \sin^4\frac{\pi\Delta x}{\lambda} \right] \left[ 1 + \beta\alpha^2 \sin^2\frac{\pi\Delta x}{\lambda} + 16(1-\beta)\alpha^4 \sin^4\frac{\pi\Delta x}{\lambda} \right]^{-1}$$
(9)

where

 $a_2$  is the amplitude of the sinusoidal profile short wave component.

NOTE The sum of the transmission characteristics of the short wave profile component and the long wave profile component equals one.

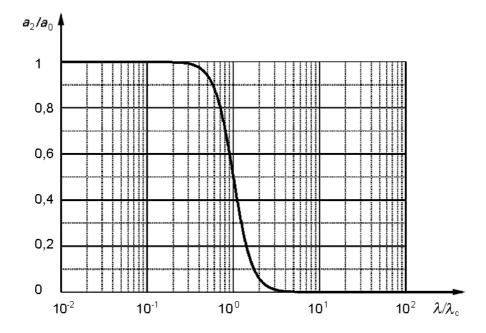


Figure 3 — Transmission characteristic for the short wave profile component  $(\beta = 0; \Delta x = \lambda_c/200)$ 

#### 5 Recommendations

#### 5.1 Nesting Index (cut-off values)

It is recommended that the nesting index (the cut-off value  $\lambda_c$ ) be chosen from a logarithmic series (constant ratio) of values. Experience has shown that a constant ratio of approximately the square root of ten between successive scale values is optimum. The nesting index should be chosen from the following series of values:

... 2,5 μm; 8 μm; 25 μm; 80 μm; 250 μm; 0,8 mm; 2,5 mm; 8 mm; 25 mm;

#### 5.2 Tension parameter ( $\beta$ )

If not otherwise specified, the tension parameter  $\beta$  takes the value zero.

#### 5.3 Implementation

It is strongly recommended that the matrix equations given in 4.3.2 and 4.3.3 be used to implement the spline filter.

#### 6 Filter designation

Spline filters in accordance with this part of ISO/TS 16610 are designated

#### **FPLS**

See also ISO/TS 16610-1:2006, Clause 5.

## Annex A (informative)

### Influence of the sampling interval

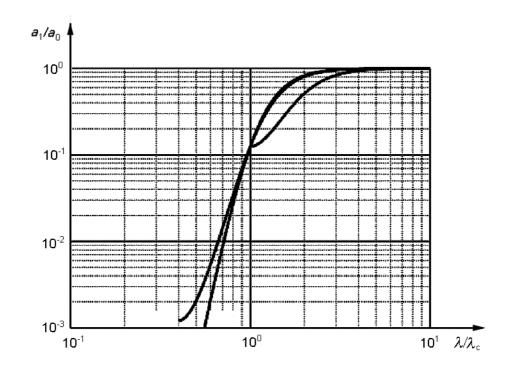
The transfer characteristic of the spline profile filter, as for every digital filter, depends on the sampling interval  $\Delta x$  (see Figure A.1). If  $\Delta x$  is small enough, the sine in all equations may be replaced by its argument.

EXAMPLE The error for  $\Delta x = 0.01 \lambda_c$  is  $\varepsilon < 5.2 \times 10^{-6}$ 

Consequently, the equation for the parameter  $\alpha$  in 4.2.3 simplifies to

$$\frac{a_1}{a_0} = \left[1 + \beta \left(\frac{\lambda_c}{\lambda}\right)^2 + (1 - \beta)\left(\frac{\lambda_c}{\lambda}\right)^4\right]^{-1} \tag{A.1}$$

i.e. it no longer depends on  $\Delta x$  . However, according to the sampling theorem (see ISO/TS 14406), this is only valid for  $\lambda \geqslant 2\Delta x$  .



NOTE According to the sampling theorem,  $\lambda / \lambda_c \geqslant 2\Delta x / \lambda_c$  is valid.

Figure A.1 — Influence of the sampling interval  $\Delta x$  on the transfer function of the spline profile filter for the parameters  $\beta = 0$ ;  $\Delta x/\lambda_{\rm C}$ : 0,1; 0,2 and 0,5

### **Annex B** (informative)

## Comparison of spline profile filter and Gaussian filter

In order to compare the transmission characteristics of the spline profiler filter and the Gaussian filter, a graphical representation of the deviation, in accordance with ISO 11562:1996, is given (see Figure B.1).

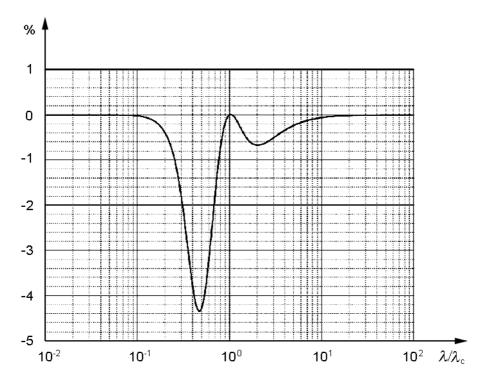


Figure B.1 — Deviation of the transmission characteristic of the spline profile filter from the Gaussian filter ( $\beta = 0.625242$ ;  $\Delta x = \lambda_c / 200$ )

## Annex C (informative)

### Illustrative examples

The following examples for the application of the spline profile filter and the Gaussian filter (currently standardized profile filter) are given for information purposes.

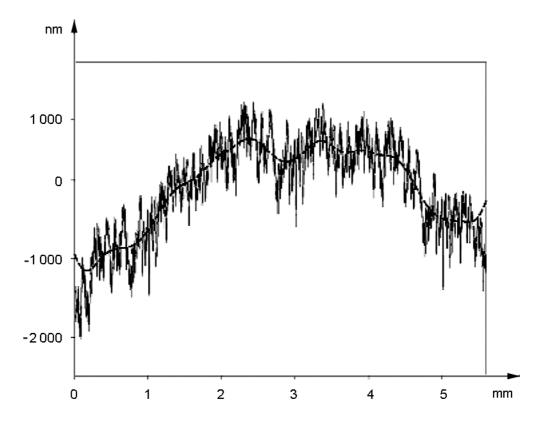


Figure C.1 — Gaussian filter with  $\,\lambda_{\text{C}}=$  0,8 mm, in accordance with ISO 11562:1996

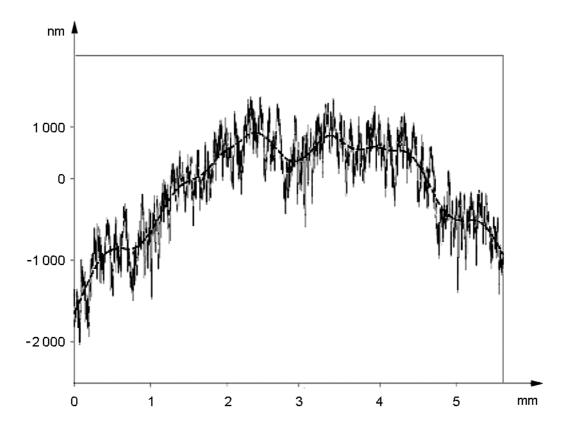


Figure C.2 — Spline profile filter with  $\lambda_{\rm C}=0.8~{\rm mm}$  and  $\beta=0$ 

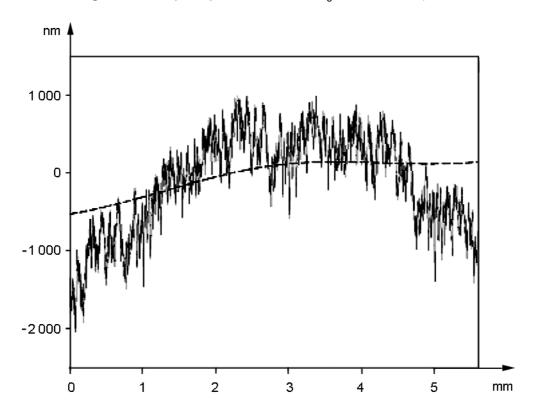


Figure C.3 — Gaussian filter with  $\, \lambda_{\text{C}} = 8$  mm, in accordance with ISO 11562:1996

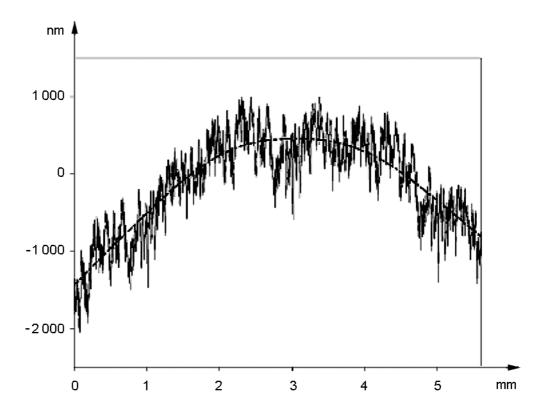
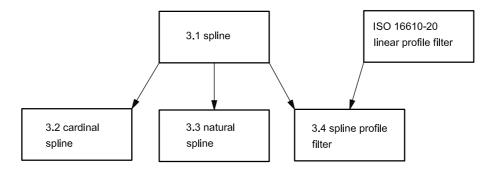


Figure C.4 — Spline profile filter with  $\, \lambda_{\rm C} = 8 \, \, {\rm mm}$  and  $\beta = 0$ 

## **Annex D** (informative)

## **Concept diagram**

The following is a concept diagram for this part of ISO/TS 16610.



## **Annex E** (informative)

## Relationship to the filtration matrix model

For full details about the filtration matrix model see ISO/TS 16610-1.

#### E.1 Position in the filtration matrix model

This part of ISO/TS 16610 is a basic concept document that influences all filtration standards in the column: Profile filters, Linear (see Figure E.1).

General	Filters: ISO/TS 16610 series									
	Part 1									
Fundamental	Profile filters			Areal filters						
	Part 11 <sup>a</sup>			Part 12 <sup>a</sup>						
	Linear	Robust	Morphological	Linear	Robust	Morphological				
Basic concepts	Part 20	Part 30	Part 40	Part 60	Part 70	Part 80				
Particular filters	Parts 21-25	Parts 31-35	Parts 41-45	Parts 61-65	Parts 71-75	Parts 81-85				
How to Filter	Parts 26-28	Parts 36-38	Parts 46-48	Parts 66-68	Parts 76-78	Parts 86-88				
Multiresolution	Part 29	Part 39	Part 49	Part 69	Part 79	Part 89				
a At present include	ed in Part 1.									

Figure E.1 — Relationship to the filtration matrix model

# Annex F (informative) Relationship to the GPS matrix model

For full details about the GPS matrix model, see ISO/TR 14638.

#### F.1 Information about this Technical Specification and its use

This part of ISO/TS 16610 specifies the characteristics of cardinal cubic spline filters for the filtration of profiles. It specifies in particular how to separate the long and short wave component of a profile.

#### F.2 Position in the GPS matrix model

This part of ISO/TS 16610 is a global GPS Technical Specification, which influences chain links 3 and 5 of all chains of standards in the GPS matrix structure, as graphically illustrated in Figure F.1.

	Global GPS standards										
Fundamental GPS	General GPS standards										
	Chain link number	1	2	3	4	5	6				
	Size			$\times$	1	$\times$					
	Distance			$\times$	1	$\times$					
	Radius			X		$\times$					
	Angle			$\times$		$\times$					
	Form of line independent of datum			$\times$		$\times$					
	Form of line dependent of datum			$\times$		$\times$					
	Form of surface independent of datum			$\times$		$\times$					
	Form of surface dependent of datum			$\times$		$\times$					
standards	Orientation			$\times$		$\times$					
	Location			$\times$		$\times$					
	Circular run-out			$\times$		$\times$					
	Total run-out			X		X					
	Datums			$\times$		$\times$					
	Roughness profile			X		X					
	Waviness profile			$\times$		X					
	Primary profile			$\times$		X					
	Surface imperfections			$\times$		X					
	Edges			$\times$		X					

Figure F.1 — Position in the GPS matrix model

#### F.3 Related International Standards

The related International Standards are those of the chains of standards indicated in Figure F.1.

### **Bibliography**

- [1] ISO 11562:1996, Geometrical Product Specifications (GPS) Surface texture: Profile method Metrological characteristics of phase correct filters
- [2] ISO/TS 14406<sup>1)</sup>, Geometrical product specifications (GPS) State-of-the-art of dimensional and associated tolerancing
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<sup>1)</sup> Under preparation.



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