International Standard



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Nuclear power plants — Reliability data exchange — General guidelines

Centrales nucléaires — Échange de données de fiabilité — Critères généraux

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Foreword

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Draft International Standards adopted by the technical committees are circulated to the member bodies for approval before their acceptance as International Standards by the ISO Council.

International Standard ISO 6527 was developed by Technical Committee ISO/TC 85, Nuclear energy, and was circulated to the member bodies in October 1980.

It has been approved by the member bodies of the following countries:

Austria Belgium Hungary Italy Japan

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The member body of the following country expressed disapproval of the document on technical grounds:

France

Nuclear power plants — Reliability data exchange — General guidelines

1 Scope and field of application

This International Standard identifies the typical parameters of a component that permit it to be characterized unequivocally and to allow the corresponding reliability data to be associated with those of other components having equivalent typical parameters. This International Standard deals in particular with exchange of reliability data collected on field. Laboratory reliability test data exchange may require additional information.

For the determination of the equivalence of components, the components shall be characterized as a function of the following parameters:

- technical characteristics including, the physical principle of operation and quality level;
- $-\,\,$ actual operating conditions and maintenance and test intervals.

In particular, the operating conditions shall have been taken into consideration when selecting the components and, it is considered useful to refer to them as they may affect the performance of the components.

The reliability data may be presented both in a historical and in a statistical form. In order to facilitate their utilization together with the data from other sources, it seems convenient to have them in historical form. However, presentation of reliability data in a processed form is also discussed.

If reliability information is required on a detailed basis, it is necessary to define the failure mode.

2 Definitions¹⁾

For the purpose of this International Standard the following definitions apply.

2.1 nuclear power unit: Nuclear steam-supply system, its associated turbine generator(s) and auxiliaries.

- **2.2 system**: Integral part of a nuclear power unit comprising electrical, electronic, or mechanical components (or combinations of them) that may be operated as a separate entity to perform a particular process function.
- **2.3 line/train**: Part of a system which by itself can perform the type of process function.

 ${\sf NOTE}-{\sf One}$ line on its own may or may not meet full system capacity.

- **2.4 sub-system**: Part of a system which participates in the operation of the latter (for example, electric power supply, controls, mechanical devices, etc.).
- **2.5 component**: Element of a sub-system, having its own defined performance characteristics and forming a whole that can be removed from the process and replaced with a spare.
- **2.6 failure (of a component)**: Termination of the ability of a component to perform any one of its designed functions.
- **2.7 failure (of a system)**: Termination of the ability of a system to perform any one of its designed functions. Failure of a line within a system may occur in such a way that the system retains its ability to perform all its required functions; in this case the system has not failed.
- **2.8 failure mode**: Effect by which the failure is observed.
- **2.9 failure rate**: Number of failures per unit time in a given time interval. The failure rate may be specified for different failure modes.
- **2.10 failure probability on demand**: Failure probability expressed as a number of failures per number of type of actions requested (i.e. start, stop, open, close etc.).
- **2.11** reliability: Ability of a component or a system expressed as the probability to perform a required function under stated conditions for a stated period of time.

¹⁾ Definitions in IEC Publication 271 have been used as a basis for these definitions.

- **2.12 operating time**: Total time during which components or systems are performing their designed functions.
- **2.13** availability time: Total time during which components or systems are capable of performing their designed functions.
- **2.14** unavailability time: Total time during which components or systems are incapable of performing their designed functions.
- **2.15** mean time between failure (MTBF): Arithmetic average of calender times between failures of components or a system.

 ${\sf NOTE}-{\sf MTBF}$ is the reciprocal of failure rate when an exponential failure distribution can be assumed.

- **2.16** mean time to failure (MTTF): Average time to failure of a new item or a repaired item assumed as new.
- **2.17** mean time to repair (MTTR): Arithmetic average of times required to perform a repair activity on the actual item.
- **2.18 preventive maintenance**: Activity performed on a system or component in order to reduce the probability of failures due to known wear-out failure modes.
- **2.19 corrective maintenance**: Activity performed on a system or component in order to eliminate the causes of failures that happened or were revealed by scheduled tests.

3 Component characteristics

This clause identifies the main characteristics of components so as to establish a comparative basis. The characteristics are separated into technical characteristics and quality characteristics.

3.1 Technical characteristics

The following characteristics shall be given wherever applicable.

a) Technical generic description

The technical term designating the component in question shall be specified; as far as possible reference shall be made to existing pertinent regulations, codes, manuals, etc.

b) Definition of the component in question

The definition of the component in question described under a) shall be specified including the interface points with adjacent components.

c) Physical principle of operation

For the individual functions that may be associated with the component in question, the principle of operation by which the function is achieved shall be stated.

d) Component design characteristics

The key design characteristics shall be specified, for example, nominal (connection) dimensions, rated pressure and temperature, materials, design class, rated voltage, etc.

Table 5 (see the annex) gives detailed examples of the design characteristics deemed important for a group of components. Similar tables may be drawn for other components, on the basis of their manufacturing data. Other data may be added to those listed in table 5 according to particular needs.

In addition the following information shall be given, if possible

- e) Manufacturer
- f) Manufacturer type designation and fabrication date

The manufacturer's reference is requested in particular cases to allow the user to find another source of data if necessary. Of course, components of the same type made by different manufacturers very seldom have the same characteristics. As a consequence engineering judgement will very often be required to decide whether the component may be considered to have equivalent characteristics or not. In general, it will be necessary for the values of the major parameters to fall within certain ranges.

3.2 Quality characteristics

The quality of a component is an essential characteristic for establishing its equivalence with others. Components having the same technical characteristics may be designed and manufactured, tested and controlled at different quality levels and thus they might not be equivalent. As an example of such a difference in quality, circuit breakers for safety-related systems and for normal loads may be mentioned. The former are subjected to a series of type qualifications, aging, and seismic tests that are not required for the latter. Furthermore, the quality of the safety-related equipment is verified with a quality assurance programme having well-defined characteristics.

For the equivalence of components, it should be adequate to refer to their quality level and, if applicable, to their safety classification.

4 Operation characteristics

While the preceding clause gives guidance to determining the technical equivalence of components, this clause gives guidance to determining whether the operating conditions are comparable or not. A different operating mode and the exposure to different environmental conditions are factors which may affect the behaviour of a single component and thus the reliability data. As a consequence, an engineering judgement

on the effects of the following parameters is also necessary before utilizing data from other components.

4.1 Normal operating conditions

The following aspects of the normal operating conditions shall be examined.

4.1.1 Operational stress, load factor

Components or systems are often used below their rated design characteristics power levels. This results in lower wear of the components. For instance, the lifetime of a ball bearing depends on the number of revolutions per minute and on the load whilst the lifetime of insulation depends on the operating temperature and voltage. The data to be recorded depend on the type of component. As an example, the following data are considered to be useful for pumps:

- operating pressure head;
- operating temperature;
- operating flow or velocity;
- driven fluid;
- rotational frequency.

4.1.2 Conditions of use

A component may be operated continuously or in standby with cyclical or random demands. In the first case, time of operation is necessary to assess the component's behaviour. In the other case, the number of demands (including those for test purposes) is the parameter to be considered.

4.1.3 Type of working load

A component may be utilized with different loading conditions. The variation in loading conditions causes additional stresses

on the component. The working load shall be described at least as follows:

- steady state operation;
- changing load operation;
- controlled load operation.

4.2 Maintenance and test intervals

The type of maintenance carried out on each component is a parameter that may influence the performance of a component.

The type of maintenance performed on a component may be preventive (periodic), on condition or corrective (break down). The preventive maintenance intervals may be as shown in table 1.

Also the test programme carried out on the component may influence the performance and shall thus be defined.

Test intervals may be classified in a manner similar to that given in table 1.

4.3 Environmental conditions

Environmental conditions as well as all other parameters covered in clause 4 shall be foreseen during the component selection phase and shall then as a consequence influence the choice of a component having adequate technical characteristics.

However it is expected that they may still have an influence on the components behaviour.

Table 2 shows the main parameters that shall be subject to engineering judgement in order to define the equivalence.

Table 1 — Example of preventive maintenance interval

Table 1 — Example of preventive maintenance interval		
	Daily	
	Weekly	
	Fortnightly	
	Monthly	
	Two-monthly	
	Three-monthly	
	Four-monthly	
	Six-monthly	
	Nine-monthly	
	Yearly	
	Two-yearly	

Table 2 — Some environmental conditions to be considered

Condition	Range	
Temperature	Normal or inside specification Cycle Shock Outside normal range or outside specification Maximum operating temperature	
Humidity	Normal Dry (humidity control) Damp or wet conditions	
Vibration	Not present or insignificant Intermittent Continuous or long periods Shock present	
Nuclear radiation	High (over 10 R/h) Medium (between 0,1 and 10 R/h) Low (below 0,1 R/h)	
Corrosive atmosphere	Not present or insignificant Salt spray Chemical Industrial (sulphur compounds) sand/dust present	
Fungus, etc.	Not present Fungus or mould growth Pests	

NOTE — For certain components, reference may be made to standardized environmental classes described in IEC Publication 68.

5 Failure data presentation

Presentation of the reliability data may be made in two ways:

- presentation in historical form;
- presentation in statistical form.

Presentation of the data in the historical form is considered more appropriate for the purposes of this International Standard. However, presentation in the statistical form will also be discussed.

In both cases the data supplied shall be based on the following assumptions :

- All the data shall relate to the performance after the early failure period has elapsed i.e. after onset of commercial plant operation. It is, however, of interest to collect failure information prior to commercial operation on a separate basis.
- For corrective maintenance after failures, the actual time required for repair of the component and the manhours used shall be recorded. The additional time necessary, for example, for decontamination or for construction of special bridges (should they be required by the components particular location) shall be indicated separately.

In case the environmental conditions are different from those indicated in the request of data, it would be advisable, if possible, to indicate by what factor the performance parameters would change if the component was utilized in a different environment.

5.1 Presentation of the data in the historical form

With regard to the exchange of information on components, presentation of the performance data in the historical form leaves the user free to carry out his own statistical processing.

For this purpose, it will be necessary to provide all the successive operating times before failures and/or number of demands and the failure information (raw data).

It is recommended that the following information be included in the historical report:

- failure mode;
- failure cause:
- failure description;
- method of failure detection;
- corrective action taken;
- repair time.

5.2 Presentation of the data in the statistical form

The first form of presentation in statistical terms might be as shown in table 3. Table 3, case a) shows a minimum data presentation scheme that may be employed where the different failure modes require the same repair time. Table 3, case b) shows a data presentation scheme for failure modes or maintenance times markedly different.

For instance, table 3, case a) should be used for a pump the outages of which are caused only by physical-displacement or excessive-leak failure. Table 3, case b) should be used for a

circuit breaker that experiences both failures to close and failures to open.

For the presentation of the performance data of a single component in mathematical form, the following information (expressed in millions of hours of operations) shall be supplied for each type of failure:

- observed failure rate;
- lower limit;
- upper limit.

The observed failure rate shall be the mathematical mean of whatever probability density function is chosen to represent the performance of the particular component.

The lower and upper confidence limits form an interval that contains the true value with a probability equal to the confidence level. The preferred confidence level is 90 %.

If, within the context of the preceding paragraphs, the failure rate of the component remains constant throughout the observation period (i.e., an exponential distribution) the observed failure rate may be obtained by the formula

$$\lambda = \frac{r}{T}$$

and the confidence interval with the formula

$$\frac{\chi^2_{\frac{\alpha}{2}; 2r}}{2T} \le \lambda \le \frac{\chi^2_{\left(1 - \frac{\alpha}{2}\right); 2r + 2}}{2T}$$

where

- λ is the observed failure rate;
- χ^2 is the chi-squared distribution;
- r is the number of failures of the same mode;
- T is the operating time;
- (1α) is the confidence level.

It is worth noting that an upper limit of λ may be computed even though no failure has occurred, that is :

$$0 \leq \lambda \leq \frac{\chi^2_{(1-\alpha);2}}{2T}$$

This is called the one-sided confidence interval.

Table 3 — Example of data presentation in a statistical form

Data presentation

Case a)

- calender time;
- total number of components;
- operation time expressed in millions of hours
- total number of failures;
- failure rate (observed, lower and upper limit);
- average unavailability time expressed in hours;
- mean time to repair expressed in hours (observed, lower and upper limits);
- number of failures for the different failure modes.

Case b)

- calender time;
- total number of components;
- total operation time expressed in millions of hours
- number of failures for a certain failure mode;
- failure rate (observed, lower and upper limit);
- average unavailability time expressed in hours;
- mean time to repair expressed in hours (observed, lower and upper limit).

6 Mode-of-failure classification

As already observed in the preceding paragraphs the failures shall be linked to their mode of failure.

Table 4 lists some possible modes of failure.

Table 4 — Examples of modes of failure

Failure modes

Leak

Crack

Rupture

Displacement

Failure to start

Failure to stop

Failure to close Failure to open

Failure to function

Degraded performance

Disconnection

Destruction

Short circuit

Earth fault, insulation fault

Zero point drift

etc...

Annex

Table 5 — Examples of component design characteristics¹⁾

	Component characteristics	Units
Sta	bilized power supply	
01	Manufacturer reference	i
02	Output : continuous, one phase, three-phase	w
1	Input voltage : continuous, one-phase, three-phase	V
	Output voltage: stability	%
05	Output current : stability	%
06	Output frequency: stability	%
07	Ripple	%
08	Built-in electric protections	
09	Indoor, outdoor, flameproof, tropical type of construction	
An	plifiers	
01	Manufacturer reference	
02	Magnetic, electric	
03	Rating	
04	Input signal range and type	ļ
05	Input impedance	Ω
06	Gain	dB
	Output signal range and type	
	Load impedance	Ω
	Supply voltage: continuous, alternate	
	Valves; solid-state components	
11	Built-in electric protections	
12	Indoor, outdoor, flameproof, tropical type	
01	Manufacturer reference	
	Alkaline, lead, dry	A·h
ı	Capacity Rated voltage	
05	Electrolyte density at 15 °C	kg/m³
06	Number of elements per cell : number of cells	""
ı	Full-charge current	A
08	Normal steady-state current	A
09	Full-discharge current	A
10	Electrolyte quantity per cell	dm ³
Ele	ctronic regulators	
01	Manufacturer reference	
02	Type of input	
	Input range	
04	Output signal range	Ì
05	Regulating action : on — off, P; I; D.	1
06	Local or remote set points	1 ~
	Set point range	%
08	Proportional band	% s-1
09	Integral time (repetition per minute)	l .
10	Derivative time range	s A
11	Number and type of contacts, rating	V
12	Supply voltage : continuous, alternating Load impedance	Ω
13	Load Impedance	ļ

¹⁾ These examples are given for guidance only and are not expected to be exhaustive.

Table 5 (continued)

	Component characteristics	Units
Sol	enoid valves	
01	Manufacturer reference	
	Number of ways	•
03	Endfittings type	mm
04	Simple, double solenoid	1
05	Control circuit voltage : continuous, alternating	V
06	Normal or corrosive fluid; steam	
07	Maximum static pressure	MPa
80	Maximum-minimum differential pressure	MPa
09	Net flow section	mm ²
10	Pulse or continuous command signal	İ
11	Reset : electric, manual, automatic	
12	Possibility of manual control	l
13	Indoor, outdoor, flameproof, tropical type	
14	Operating temperature of fluid	
Lim	it switches	
01	Manufacturer reference	
02	Linear, rotary drive	
03	Number and type of contacts	
04	Type of link	
05	Indoor, outdoor, flameproof, tropical type	
C) -	w switches	
01	Manufacturer reference	1
02	On-line, bypass	
03	Flow range	dm ³ /s
04	Normal, corrosive fluid	
05	Differential: adjustable, fixed	
06 07	Number and type of contacts	mm
08	Endfitting type and size Maximum static pressure	MPa
09	Mechanical magnetic coupling	'V'' 8
10	Indicator type	
11	Indoor, outdoor, flameproof, tropical type	
12	Type of electrical connection	
HV	Air operated circuit breaker	
	Manufacturer reference	
01		kV
02 03	Rated voltage Rated power	kA
04	•	\ \^
05	Rated break capacity Unipolar, tripole control	
06	Normal, saline insulator type	
07	Feed pressure	MPa
08	Control circuit voltage: continuous, alternating	V
09	Plate caps, connections diameter	mm
10	Number and type of auxiliary contacts	1
11	Rated cycle : normal, heavy	
12	Closing time	ms
13	Opening time	ms
14	Total weight per pole	kg
МТ	Air circuit breakers with magnetic deionization; MT oil circuit breaker	
01	Manufacturer reference	
02	Rated voltage	V
03	Rated power	kA
04	Rated break capacity	, kA
05	Fixed, extractable type	
06	Manual, spring, solenoid actuation	
07	Remote, local actuation	
08	Control circuit voltage : continuous; alternating	V
09	Number and type of aux. contacts	
10	Rated cycle: normal, heavy	1

Table 5 (continued)

Component characteristics	Units
Hexafluoride circuit breakers	
01 Manufacturer reference	1
02 Rated voltage 03 Rated power	kV
03 Rated power 04 Rated break capacity	kA
05 Unipolar, tripole control	
06 Normal, saline insulator type	
07 Feed pressure	MPa V
08 Control circuit voltage : continuous, alternating 09 Plate caps, connections diameter	mm
10 Number and type of auxiliary contacts	1
11 Rated cycle: normal, heavy	
12 Closing time	ms
13 Opening time	ms
14 Total weight per pole	kg
Low-voltage circuit breaker	
01 Manufacturer reference 02 AC/Rated voltage	l v
03 Rated power	
04 Break capacity at 380 V ac	kA
05 Number of poles	
06 Fixed, extractable type 07 Frontal, back caps	
08 Manual, spring, solenoid actuation	
09 Actuation circuit voltage : continuous, alternating	V
10 Magnetic, thermal, compensated protections	
11 Magnetic protection field; delay : adjustable, fixed	A/s A
12 Thermal protection control range 13 Number and type of aux. contacts	^
14 Electromagnetic maximum current relay : number and type	
15 Minimum voltage protection	
LV asynchronous, three-phase electric motors	
01 Type	1
02 Rated power	kW V
03 Rated voltage 04 Rated current	l Å
05 Number of poles	1 "
06 Connection type	
07 Isolation class	
08 Construction type 09 Protection type	
09 Protection type 10 Frequency	
11 Power factor	
12 Temperature class	
MV asynchronous three-phase motors	
01 Type	
02 Rated power 03 Rated voltage	kW V
03 Rated voltage 04 Rated current	l Å
05 Number of poles	
06 Connection type	
07 Isolation class 08 Construction type	
09 Protection type	
10 Cooling type 11 Power factor	
12 Inrush current	A
13 Rotor PD2 mass-moment of inertia	kg⋅m²
14 Temperature class	
Electronic relays	
01 Manufacturer reference	
02 Relay functions 03 Direct connection, transformers, converters	
TO ENDOUGH FRANCISCHOOL CONTROL OF CONTROL O	V, A
04 Rated voltage current 05 Converters; signal range; measuring unit	V, A

Table 5 (continued)

	Component char	racteristics	Units
The	ermal relays		
01	Manufacturer reference		
02	Number of poles		
03	Current range		A
04	Automatic, manual reclosing	•	
05	Normal, micrometric locked setting		
06	Number and type of contacts		
07	Indoor, outdoor, flameproof, tropical type		
80	Normal, ambient temperature compensation		
Ele	ctrical actuators		
01	Manufacturer reference		
02	Rotary, linear movement		
03	Maximum torque		Nm
04	Maximum strength		N
05	Maximum angle		(°)
06	Maximum stroke		mm
07	Absorbed power : continuous, three-phase, single-phase		W
80	Supply voltage		V
09	Positioning signal range; measuring unit		
10	Opening, closing-torque limiter		
11	Position transmitter, built-in indicator		
12	Number and type of limit switches		
13	Indoor, outdoor, flameproof, tropical type		
Ga	te valves		
01	Manufacturer reference		
02	Rated pressure		MPa
03	Rated diameter	•	mm
	Actuation type		
05	Endfittings type		
06	Body material		
07	Steam and plug material		
80	By-pass diameter		mm
09	Rated temperature		
Bal	l valves		
	Manufacturer reference		
	Rated pressure		MPa
03	Rated diameter		mm
04	Actuation type manual, pneumatic, electrical		
05	Endfittings type		
06	Body and seat material		
07	Plug and steam material		
80	Rated temperature		
Ch	eck valves		
01	Manufacturer reference		
02	Rated pressure		MPa
03	Rated diameter		mm
04	Pneumatic drive		
05	Balanced		
06	Rated temperature		I

Table 5 (concluded)

	Component characteristics	Units
Saf	ety relief valves	
01	Manufacturer reference	
02	Rated inlet, outlet pressure	MPa
03	Rated inlet, outlet diameter	mm
04	Self-actuated, controlled drive	
05	Orifice area	mm ²
06	Endfittings type	
07	Body and seat material	
80	Steam and plug material	
09	Spring material	
10	Rated temperature	
Ro	ary pumps	
01	Manufacturer reference	
02	Driven fluid	
03	Axial, centrifugal	
04	Rated flow	m³/h
05	Rated head	m
06	Rated power	kW
07	Rotational frequency	r/min
80	Number of stages	
09	Mechanical, labyrinth, packing seals	
10	NPSH	
11	Shut-off head	
12	Maximum pumping temperature	°C
13	Vertical, horizontal shaft	
He	at exchangers	
01	Manufacturer reference	
02	(Single, double pass)	
03	Heater, coolant fluid	
04	Horizontal, vertical	
05	Fluid on tube side; number of pass	
06	Fluid on shell side	MPa
07	Pressure tube/shell side	
80	Exchange surface	m ²
09	Number of tubes; diameter, thickness	mm
10	Tube material	
11	Shell material	
12	Desuperheater, saturated, sub-cooling section	<u> </u>