

WORK AND KINETIC ENERGY

6



? When a shotgun fires, the expanding gases in the barrel push the shell out. According to Newton's third law, the shell exerts as much force on the gases as the gases exert on the shell. Would it be correct to say that the *shell* does work on the *gases*?

Suppose you try to find the speed of an arrow that has been shot from a bow. You apply Newton's laws and all the problem-solving techniques that we've learned, but you run across a major stumbling block: After the archer releases the arrow, the bow string exerts a *varying* force that depends on the arrow's position. As a result, the simple methods that we've learned aren't enough to calculate the speed. Never fear; we aren't by any means finished with mechanics, and there are other methods for dealing with such problems.

The new method that we're about to introduce uses the ideas of *work* and *energy*. The importance of the energy idea stems from the *principle of conservation of energy*: Energy is a quantity that can be converted from one form to another but cannot be created or destroyed. In an automobile engine, chemical energy stored in the fuel is converted partially to the energy of the automobile's motion and partially to thermal energy. In a microwave oven, electromagnetic energy obtained from your power company is converted to thermal energy of the food being cooked. In these and all other processes, the *total* energy—the sum of all energy present in all different forms—remains the same. No exception has ever been found.

We'll use the energy idea throughout the rest of this book to study a tremendous range of physical phenomena. This idea will help you understand why a sweater keeps you warm, how a camera's flash unit can produce a short burst of light, and the meaning of Einstein's famous equation $E = mc^2$.

In this chapter, though, our concentration will be on mechanics. We'll learn about one important form of energy called *kinetic energy*, or energy of motion, and how it relates to the concept of *work*. We'll also consider *power*, which is the time rate of doing work. In Chapter 7 we'll expand the ideas of work and kinetic energy into a deeper understanding of the concepts of energy and the conservation of energy.

LEARNING GOALS

By studying this chapter, you will learn:

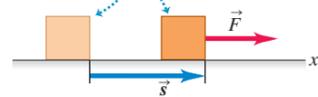
- What it means for a force to do work on a body, and how to calculate the amount of work done.
- The definition of the kinetic energy (energy of motion) of a body, and what it means physically.
- How the total work done on a body changes the body's kinetic energy, and how to use this principle to solve problems in mechanics.
- How to use the relationship between total work and change in kinetic energy when the forces are not constant, the body follows a curved path, or both.
- How to solve problems involving power (the rate of doing work).

6.1 These people are doing work as they push on the stalled car because they exert a force on the car as it moves.



6.2 The work done by a constant force acting in the same direction as the displacement.

If a body moves through a displacement \vec{s} while a constant force \vec{F} acts on it in the same direction ...



... the work done by the force on the body is $W = Fs$.

6.1 Work

You'd probably agree that it's hard work to pull a heavy sofa across the room, to lift a stack of encyclopedias from the floor to a high shelf, or to push a stalled car off the road. Indeed, all of these examples agree with the everyday meaning of *work*—any activity that requires muscular or mental effort.

In physics, work has a much more precise definition. By making use of this definition we'll find that in any motion, no matter how complicated, the total work done on a particle by all forces that act on it equals the change in its *kinetic energy*—a quantity that's related to the particle's speed. This relationship holds even when the forces acting on the particle aren't constant, a situation that can be difficult or impossible to handle with the techniques you learned in Chapters 4 and 5. The ideas of work and kinetic energy enable us to solve problems in mechanics that we could not have attempted before.

In this section we'll see how work is defined and how to calculate work in a variety of situations involving *constant* forces. Even though we already know how to solve problems in which the forces are constant, the idea of work is still useful in such problems. Later in this chapter we'll relate work and kinetic energy, and then apply these ideas to problems in which the forces are *not* constant.

The three examples of work described above—pulling a sofa, lifting encyclopedias, and pushing a car—have something in common. In each case you do work by exerting a *force* on a body while that body *moves* from one place to another—that is, undergoes a *displacement* (Fig. 6.1). You do more work if the force is greater (you push harder on the car) or if the displacement is greater (you push the car farther down the road).

The physicist's definition of work is based on these observations. Consider a body that undergoes a displacement of magnitude s along a straight line. (For now, we'll assume that any body we discuss can be treated as a particle so that we can ignore any rotation or changes in shape of the body.) While the body moves, a constant force \vec{F} acts on it in the same direction as the displacement \vec{s} (Fig. 6.2). We define the **work** W done by this constant force under these circumstances as the product of the force magnitude F and the displacement magnitude s :

$$W = Fs \quad (\text{constant force in direction of straight-line displacement}) \quad (6.1)$$

The work done on the body is greater if either the force F or the displacement s is greater, in agreement with our observations above.

CAUTION **Work = W , weight = w** Don't confuse W (work) with w (weight). Though the symbols are similar, work and weight are different quantities. ■

The SI unit of work is the **joule** (abbreviated J, pronounced “jewel,” and named in honor of the 19th-century English physicist James Prescott Joule). From Eq. (6.1) we see that in any system of units, the unit of work is the unit of force multiplied by the unit of distance. In SI units the unit of force is the newton and the unit of distance is the meter, so 1 joule is equivalent to 1 *newton-meter* ($\text{N} \cdot \text{m}$):

$$1 \text{ joule} = (1 \text{ newton})(1 \text{ meter}) \quad \text{or} \quad 1 \text{ J} = 1 \text{ N} \cdot \text{m}$$

In the British system the unit of force is the pound (lb), the unit of distance is the foot (ft), and the unit of work is the *foot-pound* ($\text{ft} \cdot \text{lb}$). The following conversions are useful:

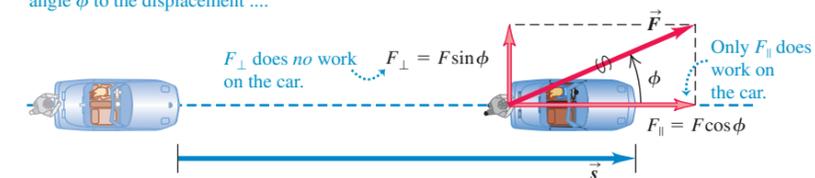
$$1 \text{ J} = 0.7376 \text{ ft} \cdot \text{lb} \quad 1 \text{ ft} \cdot \text{lb} = 1.356 \text{ J}$$

As an illustration of Eq. (6.1), think of a person pushing a stalled car. If he pushes the car through a displacement \vec{s} with a constant force \vec{F} in the direction of motion, the amount of work he does on the car is given by Eq. (6.1): $W = Fs$. But what if the person pushes at an angle ϕ with the car's displacement (Fig. 6.3)? Then \vec{F} has a component $F_{\parallel} = F \cos \phi$ in the direction of the displacement and a component $F_{\perp} = F \sin \phi$ that acts perpendicular to the displacement. (Other

6.3 The work done by a constant force acting at an angle to the displacement.

If a car moves through a displacement \vec{s} while a constant force \vec{F} acts on it at an angle ϕ to the displacement ...

... the work done by the force on the car is $W = F_{\parallel}s = (F \cos \phi)s = Fs \cos \phi$.



forces must act on the car so that it moves along \vec{s} , not in the direction of \vec{F} . We're interested only in the work that the person does, however, so we'll consider only the force he exerts.) In this case only the parallel component F_{\parallel} is effective in moving the car, so we define the work as the product of this force component and the magnitude of the displacement. Hence $W = F_{\parallel}s = (F \cos \phi)s$, or

$$W = Fs \cos \phi \quad (\text{constant force, straight-line displacement}) \quad (6.2)$$

We are assuming that F and ϕ are constant during the displacement. If $\phi = 0$, so that \vec{F} and \vec{s} are in the same direction, then $\cos \phi = 1$ and we are back to Eq. (6.1).

Equation (6.2) has the form of the *scalar product* of two vectors, which we introduced in Section 1.10: $\vec{A} \cdot \vec{B} = AB \cos \phi$. You may want to review that definition. Hence we can write Eq. (6.2) more compactly as

$$W = \vec{F} \cdot \vec{s} \quad (\text{constant force, straight-line displacement}) \quad (6.3)$$

CAUTION **Work is a scalar** Here's an essential point: Work is a *scalar* quantity, even though it's calculated by using two vector quantities (force and displacement). A 5-N force toward the east acting on a body that moves 6 m to the east does exactly the same amount of work as a 5-N force toward the north acting on a body that moves 6 m to the north. ■

Example 6.1 Work done by a constant force

(a) Steve exerts a steady force of magnitude 210 N (about 47 lb) on the stalled car in Fig. 6.3 as he pushes it a distance of 18 m. The car also has a flat tire, so to make the car track straight Steve must push at an angle of 30° to the direction of motion. How much work does Steve do? (b) In a helpful mood, Steve pushes a second stalled car with a steady force $\vec{F} = (160 \text{ N})\hat{i} - (40 \text{ N})\hat{j}$. The displacement of the car is $\vec{s} = (14 \text{ m})\hat{i} + (11 \text{ m})\hat{j}$. How much work does Steve do in this case?

SOLUTION

IDENTIFY: In both parts (a) and (b), the target variable is the work W done by Steve. In each case the force is constant and the displacement is along a straight line, so we can use Eq. (6.2) or (6.3).

SET UP: The angle between \vec{F} and \vec{s} is given explicitly in part (a), so we can apply Eq. (6.2) directly. In part (b) the angle isn't given,

so we're better off calculating the scalar product in Eq. (6.3) from the components of \vec{F} and \vec{s} , as in Eq. (1.21): $\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$.

EXECUTE: (a) From Eq. (6.2),

$$W = Fs \cos \phi = (210 \text{ N})(18 \text{ m}) \cos 30^\circ = 3.3 \times 10^3 \text{ J}$$

(b) The components of \vec{F} are $F_x = 160 \text{ N}$ and $F_y = -40 \text{ N}$, and the components of \vec{s} are $x = 14 \text{ m}$ and $y = 11 \text{ m}$. (There are no z -components for either vector.) Hence, using Eqs. (1.21) and (6.3),

$$\begin{aligned} W &= \vec{F} \cdot \vec{s} = F_x x + F_y y \\ &= (160 \text{ N})(14 \text{ m}) + (-40 \text{ N})(11 \text{ m}) \\ &= 1.8 \times 10^3 \text{ J} \end{aligned}$$

EVALUATE: In each case the work that Steve does is more than 1000 J. This shows that 1 joule is a rather small amount of work.

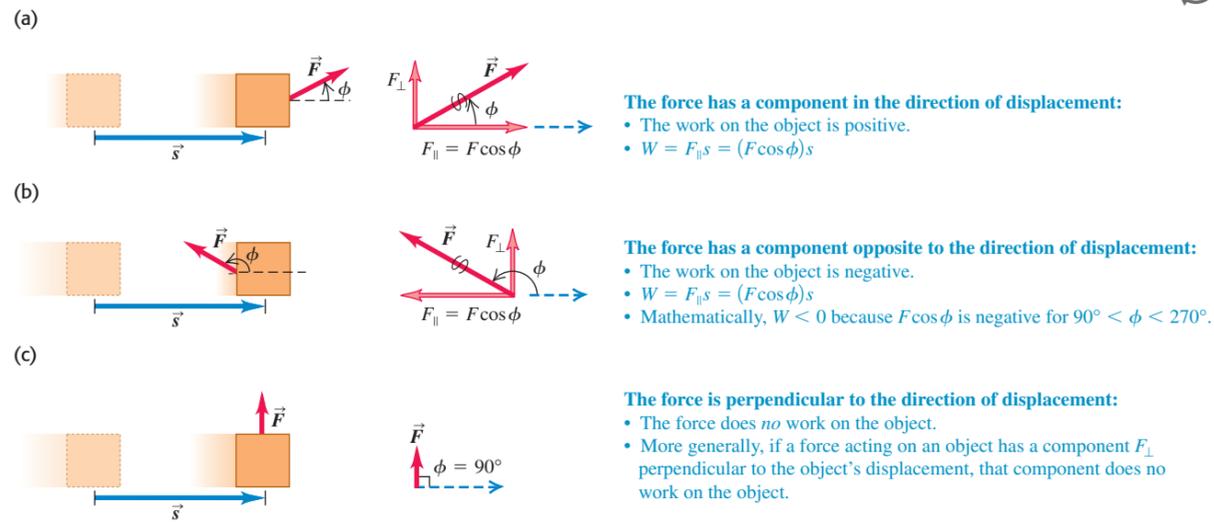
Work: Positive, Negative, or Zero

In Example 6.1 the work done in pushing the cars was positive. But it's important to understand that work can also be negative or zero. This is the essential way in which work as defined in physics differs from the “everyday” definition of work. When the force has a component in the *same direction* as the displacement



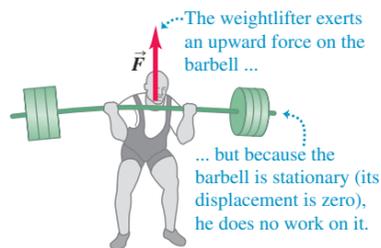
5.1 Work Calculations

6.4 A constant force \vec{F} can do positive, negative, or zero work depending on the angle between \vec{F} and the displacement \vec{s} .



(ϕ between zero and 90°), $\cos \phi$ in Eq. (6.2) is positive and the work W is *positive* (Fig. 6.4a). When the force has a component *opposite* to the displacement (ϕ between 90° and 180°), $\cos \phi$ is negative and the work is *negative* (Fig. 6.4b). When the force is *perpendicular* to the displacement, $\phi = 90^\circ$ and the work done by the force is *zero* (Fig. 6.4c). The cases of zero work and negative work bear closer examination, so let's look at some examples.

6.5 A weightlifter does no work on a barbell as long as he holds it stationary.

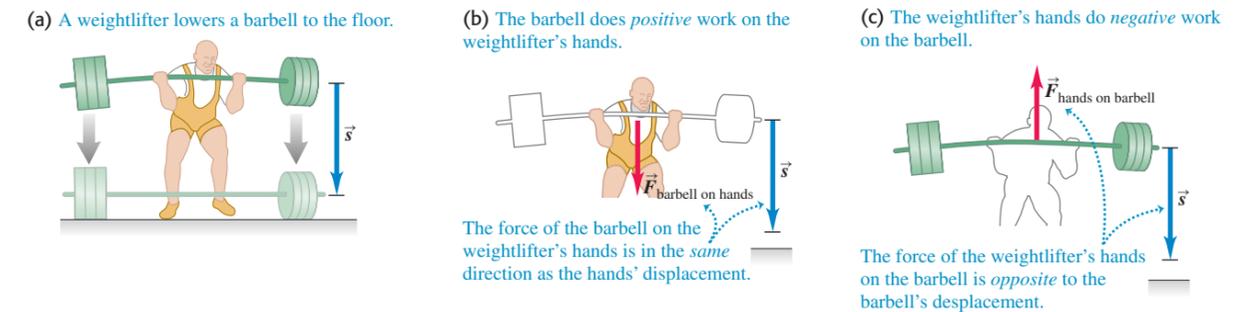


There are many situations in which forces act but do zero work. You might think it's "hard work" to hold a barbell motionless in the air for 5 minutes (Fig. 6.5). But in fact, you aren't doing any work at all on the barbell because there is no displacement. You get tired because the components of muscle fibers in your arm do work as they continually contract and relax. This is work done by one part of the arm exerting force on another part, however, *not* on the barbell. (We'll say more in Section 6.2 about work done by one part of a body on another part.) Even when you walk with constant velocity on a level floor while carrying a book, you still do no work on it. The book has a displacement, but the (vertical) supporting force that you exert on the book has no component in the direction of the (horizontal) motion. Then $\phi = 90^\circ$ in Eq. (6.2), and $\cos \phi = 0$. When a body slides along a surface, the work done on the body by the normal force is zero; and when a ball on a string moves in uniform circular motion, the work done on the ball by the tension in the string is also zero. In both cases the work is zero because the force has no component in the direction of motion.

What does it really mean to do *negative* work? The answer comes from Newton's third law of motion. When a weightlifter lowers a barbell as in Fig. 6.6a, his hands and the barbell move together with the same displacement \vec{s} . The barbell exerts a force $\vec{F}_{\text{barbell on hands}}$ on his hands in the same direction as the hands' displacement, so the work done by the *barbell* on his *hands* is positive. (Fig. 6.6b). But by Newton's third law the weightlifter's hands exert an equal and opposite force $\vec{F}_{\text{hands on barbell}} = -\vec{F}_{\text{barbell on hands}}$ on the barbell (Fig. 6.6c). This force, which keeps the barbell from crashing to the floor, acts opposite to the barbell's displacement. Thus the work done by his *hands* on the *barbell* is negative. Because the weightlifter's hands and the barbell have the same displacement, the work that his hands do on the barbell is just the negative of the work that the barbell does on his hands. In general, when one body does negative work on a second body, the second body does an equal amount of *positive* work on the first body.

CAUTION Keep track of who's doing the work We always speak of work done *on* a particular body *by* a specific force. Always be sure to specify exactly what force is doing the

6.6 This weightlifter's hands do negative work on a barbell as the barbell does positive work on his hands.



work you are talking about. When you lift a book, you exert an upward force on the book and the book's displacement is upward, so the work done by the lifting force on the book is positive. But the work done by the *gravitational* force (weight) on a book being lifted is *negative* because the downward gravitational force is opposite to the upward displacement. ■

Total Work

How do we calculate work when *several* forces act on a body? One way is to use Eq. (6.2) or (6.3) to compute the work done by each separate force. Then, because work is a scalar quantity, the *total* work W_{tot} done on the body by all the forces is the algebraic sum of the quantities of work done by the individual forces. An alternative way to find the total work W_{tot} is to compute the vector sum of the forces (that is, the net force) and then use this vector sum as \vec{F} in Eq. (6.2) or (6.3). The following example illustrates both of these techniques.

Example 6.2 Work done by several forces

A farmer hitches her tractor to a sled loaded with firewood and pulls it a distance of 20 m along level ground (Fig. 6.7a). The total weight of sled and load is 14,700 N. The tractor exerts a constant 5000-N force at an angle of 36.9° above the horizontal, as shown in Fig. 6.7b. There is a 3500-N friction force opposing the sled's motion. Find the work done by each force acting on the sled and the total work done by all the forces.

SOLUTION

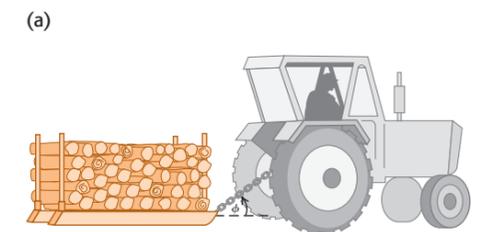
IDENTIFY: Each force is constant and the displacement is along a straight line, so we can calculate the work using the ideas of this section. We'll find the total work in two ways: (1) by adding together the work done on the sled by each force and (2) by finding the amount of work done by the net force on the sled.

SET UP: Since we're working with forces, we first draw a free-body diagram showing all of the forces acting on the sled and we choose a coordinate system (Fig. 6.7b). For each force—weight, normal force, force of the tractor, and friction force—we know the angle between the displacement (in the positive x -direction) and the force. Hence we can calculate the work each force does using Eq. (6.2).

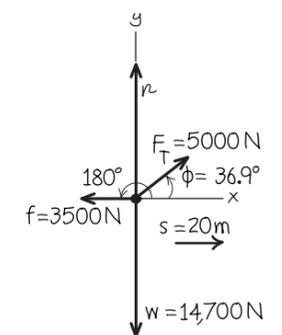
As we did in Chapter 5, we'll find the net force by adding the components of the four forces. Newton's second law tells us that because the sled's motion is purely horizontal, the net force has only a horizontal component.

EXECUTE: The work W_w done by the weight is zero because its direction is perpendicular to the displacement (compare Fig. 6.4c). For the same reason, the work W_n done by the normal force is

6.7 Calculating the work done on a sled of firewood being pulled by a tractor.



(b) Free-body diagram for sled



Continued

also zero. So $W_w = W_n = 0$. (Incidentally, can you see that the magnitude of the normal force is less than the weight? Compare Example 5.15 in Section 5.3, which has a very similar free-body diagram.)

That leaves the force F_T exerted by the tractor and the friction force f . From Eq. (6.2) the work W_T done by the tractor is

$$W_T = F_T s \cos \phi = (5000 \text{ N})(20 \text{ m})(0.800) = 80,000 \text{ N} \cdot \text{m} = 80 \text{ kJ}$$

The friction force \vec{f} is opposite to the displacement, so for this force $\phi = 180^\circ$ and $\cos \phi = -1$. The work W_f done by the friction force is

$$W_f = f s \cos 180^\circ = (3500 \text{ N})(20 \text{ m})(-1) = -70,000 \text{ N} \cdot \text{m} = -70 \text{ kJ}$$

The total work W_{tot} done on the sled by all forces is the algebraic sum of the work done by the individual forces:

$$W_{\text{tot}} = W_w + W_n + W_T + W_f = 0 + 0 + 80 \text{ kJ} + (-70 \text{ kJ}) = 10 \text{ kJ}$$

In the alternative approach, we first find the vector sum of all the forces (the net force) and then use it to compute the total work.

The vector sum is best found by using components. From Fig. 6.7b,

$$\sum F_x = F_T \cos \phi + (-f) = (5000 \text{ N}) \cos 36.9^\circ - 3500 \text{ N} = 500 \text{ N}$$

$$\sum F_y = F_T \sin \phi + n + (-w) = (5000 \text{ N}) \sin 36.9^\circ + n - 14,700 \text{ N}$$

We don't really need the second equation; we know that the y-component of force is perpendicular to the displacement, so it does no work. Besides, there is no y-component of acceleration, so $\sum F_y$ has to be zero anyway. The total work is therefore the work done by the total x-component:

$$W_{\text{tot}} = (\sum \vec{F}) \cdot \vec{s} = (\sum F_x) s = (500 \text{ N})(20 \text{ m}) = 10,000 \text{ J} = 10 \text{ kJ}$$

EVALUATE: We get the same result for W_{tot} with either method, as we should.

Note that the net force in the x-direction is *not* zero, and so the sled must accelerate as it moves. In Section 6.2 we'll return to this example and see how to use the concept of work to explore the sled's motion.

Test Your Understanding of Section 6.1 An electron moves in a straight line toward the east with a constant speed of $8 \times 10^7 \text{ m/s}$. It has electric, magnetic, and gravitational forces acting on it. During a 1-m displacement, the total work done on the electron is (i) positive; (ii) negative; (iii) zero; (iv) not enough information given to decide.

6.2 Kinetic Energy and the Work–Energy Theorem

The total work done on a body by external forces is related to the body's displacement—that is, to changes in its position. But the total work is also related to changes in the *speed* of the body. To see this, consider Fig. 6.8, which shows

6.8 The relationship between the total work done on a body and how the body's speed changes.

(a) A block slides to the right on a frictionless surface. If you push to the right on the moving block, the net force on the block is to the right.

(b) If you push to the left on the moving block, the net force on the block is to the left.

(c) If you push straight down on the moving block, the net force on the block is zero.

- The total work done on the block during a displacement \vec{s} is positive: $W_{\text{tot}} > 0$.
- The block speeds up.
- The total work done on the block during a displacement \vec{s} is negative: $W_{\text{tot}} < 0$.
- The block slows down.
- The total work done on the block during a displacement \vec{s} is zero: $W_{\text{tot}} = 0$.
- The block's speed stays the same.

three examples of a block sliding on a frictionless table. The forces acting on the block are its weight \vec{w} , the normal force \vec{n} , and the force \vec{F} exerted on it by the hand.

In Fig. 6.8a the net force on the block is in the direction of its motion. From Newton's second law, this means that the block speeds up; from Eq. (6.1), this also means that the total work W_{tot} done on the block is positive. The total work is *negative* in Fig. 6.8b because the net force opposes the displacement; in this case the block slows down. The net force is zero in Fig. 6.8c, so the speed of the block stays the same and the total work done on the block is zero. We can conclude that *when a particle undergoes a displacement, it speeds up if $W_{\text{tot}} > 0$, slows down if $W_{\text{tot}} < 0$, and maintains the same speed if $W_{\text{tot}} = 0$.*

Let's make these observations more quantitative. Consider a particle with mass m moving along the x-axis under the action of a constant net force with magnitude F directed along the positive x-axis (Fig. 6.9). The particle's acceleration is constant and given by Newton's second law, $F = ma_x$. Suppose the speed changes from v_1 to v_2 while the particle undergoes a displacement $s = x_2 - x_1$ from point x_1 to x_2 . Using a constant-acceleration equation, Eq. (2.13), and replacing v_{0x} by v_1 , v_x by v_2 , and $(x - x_0)$ by s , we have

$$v_2^2 = v_1^2 + 2a_x s$$

$$a_x = \frac{v_2^2 - v_1^2}{2s}$$

When we multiply this equation by m and equate ma_x to the net force F , we find

$$F = ma_x = m \frac{v_2^2 - v_1^2}{2s} \quad \text{and} \quad (6.4)$$

$$Fs = \frac{1}{2} m v_2^2 - \frac{1}{2} m v_1^2$$

The product Fs is the work done by the net force F and thus is equal to the total work W_{tot} done by all the forces acting on the particle. The quantity $\frac{1}{2} m v^2$ is called the **kinetic energy** K of the particle:

$$K = \frac{1}{2} m v^2 \quad (\text{definition of kinetic energy}) \quad (6.5)$$

Like work, the kinetic energy of a particle is a scalar quantity; it depends on only the particle's mass and speed, not its direction of motion (Fig. 6.10). A car (viewed as a particle) has the same kinetic energy when going north at 10 m/s as when going east at 10 m/s. Kinetic energy can never be negative, and it is zero only when the particle is at rest.

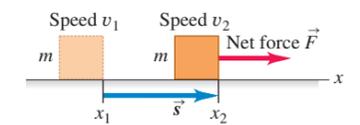
We can now interpret Eq. (6.4) in terms of work and kinetic energy. The first term on the right side of Eq. (6.4) is $K_2 = \frac{1}{2} m v_2^2$, the final kinetic energy of the particle (that is, after the displacement). The second term is the initial kinetic energy, $K_1 = \frac{1}{2} m v_1^2$, and the difference between these terms is the *change* in kinetic energy. So Eq. (6.4) says:

The work done by the net force on a particle equals the change in the particle's kinetic energy:

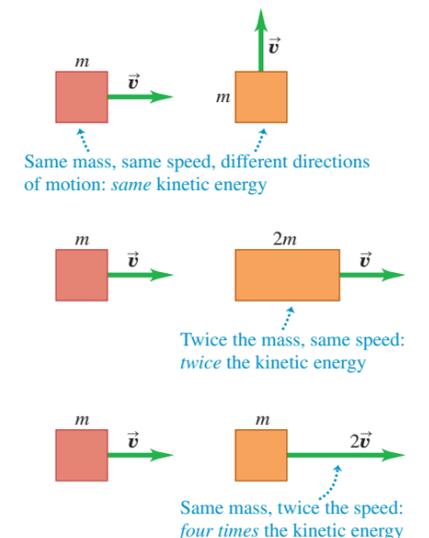
$$W_{\text{tot}} = K_2 - K_1 = \Delta K \quad (\text{work–energy theorem}) \quad (6.6)$$

This result is the **work–energy theorem**.

6.9 A constant net force \vec{F} does work on a moving body.



6.10 Comparing the kinetic energy $K = \frac{1}{2} m v^2$ of different bodies.



The work–energy theorem agrees with our observations about the block in Fig. 6.8. When W_{tot} is *positive*, the kinetic energy *increases* (the final kinetic energy K_2 is greater than the initial kinetic energy K_1) and the particle is going faster at the end of the displacement than at the beginning. When W_{tot} is *negative*, the kinetic energy *decreases* (K_2 is less than K_1) and the speed is less after the displacement. When $W_{\text{tot}} = 0$, the kinetic energy stays the same ($K_1 = K_2$) and the speed is unchanged. Note that the work–energy theorem by itself tells us only about changes in *speed*, not *velocity*, since the kinetic energy doesn't depend on the direction of motion.

From Eq. (6.4) or (6.6), kinetic energy and work must have the same units. Hence the joule is the SI unit of both work and kinetic energy (and, as we will see later, of all kinds of energy). To verify this, note that in SI units the quantity $K = \frac{1}{2}mv^2$ has units $\text{kg} \cdot (\text{m/s})^2$ or $\text{kg} \cdot \text{m}^2/\text{s}^2$; we recall that $1 \text{ N} = 1 \text{ kg} \cdot \text{m}/\text{s}^2$, so

$$1 \text{ J} = 1 \text{ N} \cdot \text{m} = 1 (\text{kg} \cdot \text{m}/\text{s}^2) \cdot \text{m} = 1 \text{ kg} \cdot \text{m}^2/\text{s}^2$$

In the British system the unit of kinetic energy and of work is

$$1 \text{ ft} \cdot \text{lb} = 1 \text{ ft} \cdot \text{slug} \cdot \text{ft}/\text{s}^2 = 1 \text{ slug} \cdot \text{ft}^2/\text{s}^2$$

Because we used Newton's laws in deriving the work–energy theorem, we can use this theorem only in an inertial frame of reference. Note also that the work–energy theorem is valid in *any* inertial frame, but the values of W_{tot} and $K_2 - K_1$ may differ from one inertial frame to another (because the displacement and speed of a body may be different in different frames).

We have derived the work–energy theorem for the special case of straight-line motion with constant forces, and in the following examples we'll apply it to this special case only. We'll find in the next section that the theorem is valid in general, even when the forces are not constant and the particle's trajectory is curved.

Problem-Solving Strategy 6.1 Work and Kinetic Energy



IDENTIFY *the relevant concepts:* The work–energy theorem, $W_{\text{tot}} = K_2 - K_1$, is extremely useful when you want to relate a body's speed v_1 at one point in its motion to its speed v_2 at a different point. (It's less useful for problems that involve the *time* it takes a body to go from point 1 to point 2, because the work–energy theorem doesn't involve time at all. For such problems it's usually best to use the relationships among time, position, velocity, and acceleration described in Chapters 2 and 3.)

SET UP *the problem* using the following steps:

1. Choose the initial and final positions of the body, and draw a free-body diagram showing all the forces that act on the body.
2. Choose a coordinate system. (If the motion is along a straight line, it's usually easiest to have both the initial and final positions lie along the x -axis.)
3. List the unknown and known quantities, and decide which unknowns are your target variables. The target variable may be the body's initial or final speed, the magnitude of one of the forces acting on the body, or the body's displacement.

EXECUTE *the solution:* Calculate the work W done by each force. If the force is constant and the displacement is a straight line, you can use Eq. (6.2) or (6.3). (Later in this chapter we'll see how to handle varying forces and curved trajectories.) Be sure to check

signs; W must be positive if the force has a component in the direction of the displacement, negative if the force has a component opposite to the displacement, and zero if the force and displacement are perpendicular.

Add the amounts of work done by each force to find the total work W_{tot} . Sometimes it's easier to calculate the vector sum of the forces (the net force) and then find the work done by the net force; this value is also equal to W_{tot} .

Write expressions for the initial and final kinetic energies, K_1 and K_2 . Note that kinetic energy involves *mass*, not *weight*; if you are given the body's weight, you'll need to use the relationship $w = mg$ to find the mass.

Finally, use $W_{\text{tot}} = K_2 - K_1$ to solve for the target variable. Remember that the right-hand side of this equation is the *final* kinetic energy minus the *initial* kinetic energy, never the other way around.

EVALUATE *your answer:* Check whether your answer makes physical sense. A key point to remember is that kinetic energy $K = \frac{1}{2}mv^2$ can never be negative. If you come up with a negative value of K , perhaps you interchanged the initial and final kinetic energies in $W_{\text{tot}} = K_2 - K_1$ or made a sign error in one of the work calculations.

Example 6.3 Using work and energy to calculate speed

Let's look again at the sled in Fig. 6.7 and the numbers at the end of Example 6.2. Suppose the initial speed v_1 is 2.0 m/s. What is the speed of the sled after it moves 20 m?

SOLUTION

IDENTIFY: We'll use the work–energy theorem, Eq. (6.6) ($W_{\text{tot}} = K_2 - K_1$), since we are given the initial speed $v_1 = 2.0 \text{ m/s}$ and want to find the final speed.

SET UP: Figure 6.11 shows our sketch of the situation. The motion is in the positive x -direction.

EXECUTE: In Example 6.2 we calculated the total work done by all the forces: $W_{\text{tot}} = 10 \text{ kJ}$. Hence the kinetic energy of the sled and its load must increase by 10 kJ.

To write expressions for the initial and final kinetic energies, we need the mass of the sled and load. We are given that the *weight* is 14,700 N, so the mass is

$$m = \frac{w}{g} = \frac{14,700 \text{ N}}{9.8 \text{ m/s}^2} = 1500 \text{ kg}$$

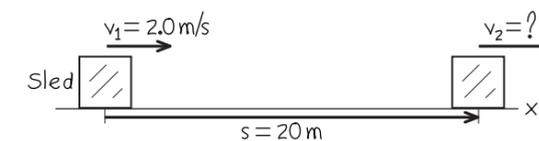
Then the initial kinetic energy K_1 is

$$\begin{aligned} K_1 &= \frac{1}{2}mv_1^2 = \frac{1}{2}(1500 \text{ kg})(2.0 \text{ m/s})^2 = 3000 \text{ kg} \cdot \text{m}^2/\text{s}^2 \\ &= 3000 \text{ J} \end{aligned}$$

The final kinetic energy K_2 is

$$K_2 = \frac{1}{2}mv_2^2 = \frac{1}{2}(1500 \text{ kg})v_2^2$$

6.11 Our sketch for this problem.



where v_2 is the unknown speed we want to find. Equation (6.6) gives

$$K_2 = K_1 + W_{\text{tot}} = 3000 \text{ J} + 10,000 \text{ J} = 13,000 \text{ J}$$

Setting these two expressions for K_2 equal, substituting $1 \text{ J} = 1 \text{ kg} \cdot \text{m}^2/\text{s}^2$, and solving for v_2 , we find

$$v_2 = 4.2 \text{ m/s}$$

EVALUATE: The total work is positive, so the kinetic energy increases ($K_2 > K_1$) and the speed increases ($v_2 > v_1$).

This problem can also be done without the work–energy theorem. We can find the acceleration from $\sum \vec{F} = m\vec{a}$ and then use the equations of motion for constant acceleration to find v_2 . Since the acceleration is along the x -axis,

$$\begin{aligned} a = a_x &= \frac{\sum F_x}{m} = \frac{(5000 \text{ N}) \cos 36.9^\circ - 3500 \text{ N}}{1500 \text{ kg}} \\ &= 0.333 \text{ m/s}^2 \end{aligned}$$

Then, using Eq. (2.13),

$$\begin{aligned} v_2^2 &= v_1^2 + 2as = (2.0 \text{ m/s})^2 + 2(0.333 \text{ m/s}^2)(20 \text{ m}) \\ &= 17.3 \text{ m}^2/\text{s}^2 \\ v_2 &= 4.2 \text{ m/s} \end{aligned}$$

This is the same result we obtained with the work–energy approach, but there we avoided the intermediate step of finding the acceleration. You will find several other examples in this chapter and the next that *can* be done without using energy considerations but that are easier when energy methods are used. When a problem can be done by two different methods, doing it by both methods (as we did in this example) is a very good way to check your work.

Example 6.4 Forces on a hammerhead

In a pile driver, a steel hammerhead with mass 200 kg is lifted 3.00 m above the top of a vertical I-beam being driven into the ground (Fig. 6.12a). The hammer is then dropped, driving the I-beam 7.4 cm farther into the ground. The vertical rails that guide the hammerhead exert a constant 60-N friction force on the hammerhead. Use the work–energy theorem to find (a) the speed of the hammerhead just as it hits the I-beam and (b) the average force the hammerhead exerts on the I-beam. Ignore the effects of the air.

SOLUTION

IDENTIFY: We'll use the work–energy theorem to relate the hammerhead's speed at different locations and the forces acting on it. There are *three* locations of interest: point 1, where the hammerhead starts from rest; point 2, where it first contacts the I-beam; and

point 3, where the hammerhead comes to a halt (see Fig. 6.12a). The two unknowns are the hammerhead's speed at point 2 and the force the hammerhead exerts between points 2 and 3. Hence we'll apply the work–energy theorem twice: once for the motion from 1 to 2, and once for the motion from 2 to 3.

SET UP: Figure 6.12b shows the vertical forces on the hammerhead as it falls from point 1 to point 2. (We can ignore any horizontal forces that may be present because they do no work as the hammerhead moves vertically.) For this part of the motion, our target variable is the hammerhead's speed v_2 .

Figure 6.12c shows the vertical forces on the hammerhead during the motion from point 2 to point 3. In addition to the forces shown in Fig. 6.12b, the I-beam exerts an upward normal force of magnitude n on the hammerhead. This force actually varies as the hammerhead comes to a halt, but for simplicity we'll treat n as a

Continued

constant. Hence n represents the *average* value of this upward force during the motion. Our target variable for this part of the motion is the force that the *hammerhead* exerts on the I-beam; it is the reaction force to the normal force exerted by the I-beam, so by Newton’s third law its magnitude is also n .

EXECUTE: (a) From point 1 to point 2, the vertical forces are the downward weight $w = mg = (200 \text{ kg})(9.8 \text{ m/s}^2) = 1960 \text{ N}$ and the upward friction force $f = 60 \text{ N}$. Thus the net downward force is $w - f = 1900 \text{ N}$. The displacement of the hammerhead from point 1 to point 2 is downward and equal to $s_{12} = 3.00 \text{ m}$. The total work done on the hammerhead as it moves from point 1 to point 2 is then

$$W_{\text{tot}} = (w - f)s_{12} = (1900 \text{ N})(3.00 \text{ m}) = 5700 \text{ J}$$

At point 1 the hammerhead is at rest, so its initial kinetic energy K_1 is zero. Hence the kinetic energy K_2 at point 2 equals the total work done on the hammerhead between points 1 and 2:

$$W_{\text{tot}} = K_2 - K_1 = K_2 - 0 = \frac{1}{2}mv_2^2 - 0$$

$$v_2 = \sqrt{\frac{2W_{\text{tot}}}{m}} = \sqrt{\frac{2(5700 \text{ J})}{200 \text{ kg}}} = 7.55 \text{ m/s}$$

This is the hammerhead’s speed at point 2, just as it hits the I-beam.

(b) As the hammerhead moves downward between points 2 and 3, the net downward force acting on it is $w - f - n$ (see

Fig. 6.12c). The total work done on the hammerhead during this displacement is

$$W_{\text{tot}} = (w - f - n)s_{23}$$

The initial kinetic energy for this part of the motion is K_2 , which from part (a) equals 5700 J. The final kinetic energy is $K_3 = 0$, since the hammerhead ends at rest. Then, from the work–energy theorem,

$$W_{\text{tot}} = (w - f - n)s_{23} = K_3 - K_2$$

$$n = w - f - \frac{K_3 - K_2}{s_{23}}$$

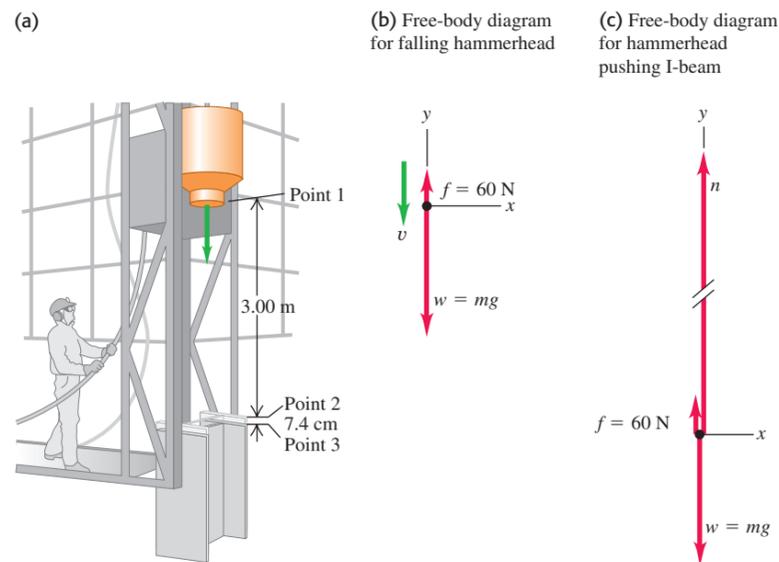
$$= 1960 \text{ N} - 60 \text{ N} - \frac{0 \text{ J} - 5700 \text{ J}}{0.074 \text{ m}}$$

$$= 79,000 \text{ N}$$

The downward force that the hammerhead exerts on the I-beam has this same magnitude, 79,000 N (about 9 tons)—more than 40 times the weight of the hammerhead.

EVALUATE: The net change in the hammerhead’s kinetic energy from point 1 to point 3 is zero; a relatively small net force does positive work over a large distance, and then a much larger net force does negative work over a much smaller distance. The same thing happens if you speed up your car gradually and then drive it into a brick wall. The very large force needed to reduce the kinetic energy to zero over a short distance is what does the damage to your car—and possibly to you.

6.12 (a) A pile driver pounds an I-beam into the ground. (b), (c) Free-body diagrams. Vector lengths are not to scale.



The Meaning of Kinetic Energy

Example 6.4 gives insight into the physical meaning of kinetic energy. The hammerhead is dropped from rest, and its kinetic energy when it hits the I-beam equals the total work done on it up to that point by the net force. This result is true in general: To accelerate a particle of mass m from rest (zero kinetic energy)

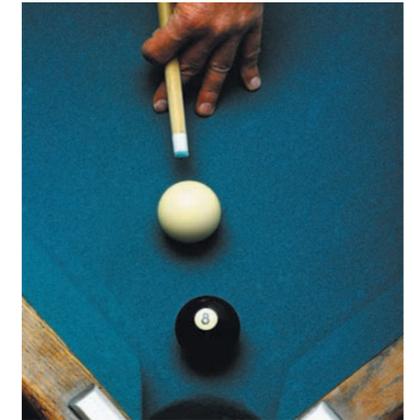
up to a speed v , the total work done on it must equal the change in kinetic energy from zero to $K = \frac{1}{2}mv^2$:

$$W_{\text{tot}} = K - 0 = K$$

So *the kinetic energy of a particle is equal to the total work that was done to accelerate it from rest to its present speed* (Fig. 6.13). The definition $K = \frac{1}{2}mv^2$, Eq. (6.5), wasn’t chosen at random; it’s the *only* definition that agrees with this interpretation of kinetic energy.

In the second part of Example 6.4 the kinetic energy of the hammerhead did work on the I-beam and drove it into the ground. This gives us another interpretation of kinetic energy: *The kinetic energy of a particle is equal to the total work that particle can do in the process of being brought to rest.* This is why you pull your hand and arm backward when you catch a ball. As the ball comes to rest, it does an amount of work (force times distance) on your hand equal to the ball’s initial kinetic energy. By pulling your hand back, you maximize the distance over which the force acts and so minimize the force on your hand.

6.13 When a billiards player hits a cue ball at rest, the ball’s kinetic energy after being hit is equal to the work that was done on it by the cue. The greater the force exerted by the cue and the greater the distance the ball moves while in contact with it, the greater the ball’s kinetic energy.



Conceptual Example 6.5 Comparing kinetic energies

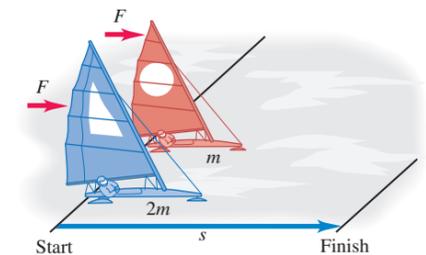
Two iceboats like the one in Example 5.6 (Section 5.2) hold a race on a frictionless horizontal lake (Fig. 6.14). The two iceboats have masses m and $2m$. Each iceboat has an identical sail, so the wind exerts the same constant force \vec{F} on each iceboat. The two iceboats start from rest and cross the finish line a distance s away. Which iceboat crosses the finish line with greater kinetic energy?

SOLUTION

If you use the mathematical definition of kinetic energy, $K = \frac{1}{2}mv^2$, Eq. (6.5), the answer to this problem isn’t immediately obvious. The iceboat of mass $2m$ has greater mass, so you might guess that the larger iceboat attains a greater kinetic energy at the finish line. But the smaller iceboat, of mass m , crosses the finish line with a greater speed, and you might guess that *this* iceboat has the greater kinetic energy. How can we decide?

The correct way to approach this problem is to remember that *the kinetic energy of a particle is equal to the total work done to accelerate it from rest.* Both iceboats travel the same distance s , and only the horizontal force F in the direction of motion does work on either iceboat. Hence the total work done between the starting line and the finish line is the *same* for each iceboat, $W_{\text{tot}} = Fs$. At the finish line, each iceboat has a kinetic energy equal to the work W_{tot} done on it, because each iceboat started from rest. So both iceboats have the *same* kinetic energy at the finish line!

6.14 A race between iceboats.



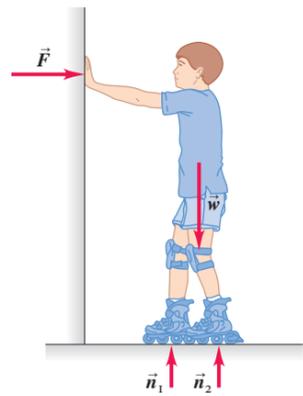
You might think this is a “trick” question, but it isn’t. If you really understand the physical meanings of quantities such as kinetic energy, you can solve problems more easily and with better insight into the physics.

Notice that we didn’t need to say anything about how much time each iceboat took to reach the finish line. This is because the work–energy theorem makes no direct reference to time, only to displacement. In fact, the iceboat of mass m takes less time to reach the finish line than does the larger iceboat of mass $2m$ because it has a greater acceleration.

Work and Kinetic Energy in Composite Systems

In this section we’ve been careful to apply the work–energy theorem only to bodies that we can represent as *particles*—that is, as moving point masses. New subtleties appear for more complex systems that have to be represented as many particles with different motions. We can’t go into these subtleties in detail in this chapter, but here’s an example.

6.15 The external forces acting on a skater pushing off a wall. The work done by these forces is zero, but the skater's kinetic energy changes nonetheless.



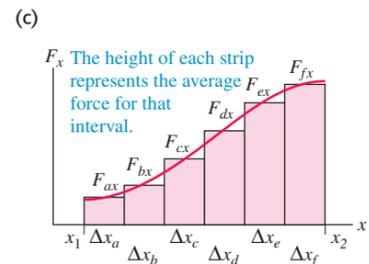
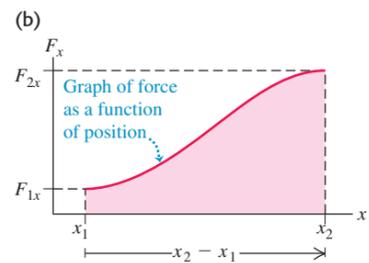
Suppose a boy stands on frictionless roller skates on a level surface, facing a rigid wall (Fig. 6.15). He pushes against the wall, which makes him move to the right. The forces acting on him are his weight \vec{w} , the upward normal forces \vec{n}_1 and \vec{n}_2 exerted by the ground on his skates, and the horizontal force \vec{F} exerted on him by the wall. There is no vertical displacement, so \vec{w} , \vec{n}_1 , and \vec{n}_2 do no work. Force \vec{F} accelerates him to the right, but the parts of his body where that force is applied (the man's hands) do not move while the force acts. Thus the force \vec{F} also does no work. Where, then, does the boy's kinetic energy come from?

The explanation is that it's not adequate to represent the boy as a single point mass. Different parts of the boy's body have different motions; his hands remain stationary against the wall while his torso is moving away from the wall. The various parts of his body interact with each other, and one part can exert forces and do work on another part. Therefore the *total* kinetic energy of this *composite* system of body parts can change, even though no work is done by forces applied by bodies (such as the wall) that are outside the system. In Chapter 8 we'll consider further the motion of a collection of particles that interact with each other. We'll discover that just as for the boy in this example, the total kinetic energy of such a system can change even when no work is done on any part of the system by anything outside it.

Test Your Understanding of Section 6.2 Rank the following bodies in order of their kinetic energy, from least to greatest. (i) a 2.0-kg body moving at 5.0 m/s; (ii) a 1.0 kg body that initially was at rest and then had 30 J of work done on it; (iii) a 1.0-kg body that initially was moving at 4.0 m/s and then had 20 J of work done on it; (iv) a 2.0 kg body that initially was moving at 10 m/s and then did 80 J of work on another body.

6.16 Calculating the work done by a varying force F_x in the x -direction as a particle moves from x_1 to x_2 .

(a) Particle moving from x_1 to x_2 in response to a changing force in the x -direction



6.3 Work and Energy with Varying Forces

So far in this chapter we've considered work done by *constant forces* only. But what happens when you stretch a spring? The more you stretch it, the harder you have to pull, so the force you exert is *not* constant as the spring is stretched. We've also restricted our discussion to *straight-line* motion. There are many situations in which a body moves along a curved path and is acted on by a force that varies in magnitude, direction, or both. We need to be able to compute the work done by the force in these more general cases. Fortunately, we'll find that the work-energy theorem holds true even when varying forces are considered and when the body's path is not straight.

Work Done by a Varying Force, Straight-Line Motion

To add only one complication at a time, let's consider straight-line motion along the x -axis with a force whose x -component F_x may change as the body moves. (A real-life example is driving a car along a straight road with stop signs, so the driver has to alternately step on the gas and apply the brakes.) Suppose a particle moves along the x -axis from point x_1 to x_2 (Fig. 6.16a). Figure 6.16b is a graph of the x -component of force as a function of the particle's coordinate x . To find the work done by this force, we divide the total displacement into small segments Δx_a , Δx_b , and so on (Fig. 6.16c). We approximate the work done by the force during segment Δx_a as the average x -component of force F_{ax} in that segment multiplied by the x -displacement Δx_a . We do this for each segment and then add the results for all the segments. The work done by the force in the total displacement from x_1 to x_2 is approximately

$$W = F_{ax}\Delta x_a + F_{bx}\Delta x_b + \dots$$

In the limit that the number of segments becomes very large and the width of each becomes very small, this sum becomes the *integral* of F_x from x_1 to x_2 :

$$W = \int_{x_1}^{x_2} F_x dx \quad (\text{varying } x\text{-component of force, straight-line displacement}) \quad (6.7)$$

Note that $F_{ax}\Delta x_a$ represents the *area* of the first vertical strip in Fig. 6.16c and that the integral in Eq. (6.7) represents the area under the curve of Fig. 6.16b between x_1 and x_2 . *On a graph of force as a function of position, the total work done by the force is represented by the area under the curve between the initial and final positions.* An alternative interpretation of Eq. (6.7) is that the work W equals the average force that acts over the entire displacement, multiplied by the displacement.

In the special case that F_x , the x -component of the force, is constant, it may be taken outside the integral in Eq. (6.7):

$$W = \int_{x_1}^{x_2} F_x dx = F_x \int_{x_1}^{x_2} dx = F_x(x_2 - x_1) \quad (\text{constant force})$$

But $x_2 - x_1 = s$, the total displacement of the particle. So in the case of a constant force F , Eq. (6.7) says that $W = Fs$, in agreement with Eq. (6.1). The interpretation of work as the area under the curve of F_x as a function of x also holds for a constant force; $W = Fs$ is the area of a rectangle of height F and width s (Fig. 6.17).

Now let's apply these ideas to the stretched spring. To keep a spring stretched beyond its unstretched length by an amount x , we have to apply a force of equal magnitude at each end (Fig. 6.18). If the elongation x is not too great, the force we apply to the right-hand end has an x -component directly proportional to x :

$$F_x = kx \quad (\text{force required to stretch a spring}) \quad (6.8)$$

where k is a constant called the **force constant** (or spring constant) of the spring. The units of k are force divided by distance: N/m in SI units and lb/ft in British units. A floppy toy spring such as a Slinky™ has a force constant of about 1 N/m; for the much stiffer springs in an automobile's suspension, k is about 10^5 N/m. The observation that force is directly proportional to elongation for elongations that are not too great was made by Robert Hooke in 1678 and is known as **Hooke's law**. It really shouldn't be called a "law," since it's a statement about a specific device and not a fundamental law of nature. Real springs don't always obey Eq. (6.8) precisely, but it's still a useful idealized model. We'll discuss Hooke's law more fully in Chapter 11.

To stretch a spring, we must do work. We apply equal and opposite forces to the ends of the spring and gradually increase the forces. We hold the left end stationary, so the force we apply at this end does no work. The force at the moving end *does* do work. Figure 6.19 is a graph of F_x as a function of x , the elongation of the spring. The work done by this force when the elongation goes from zero to a maximum value X is

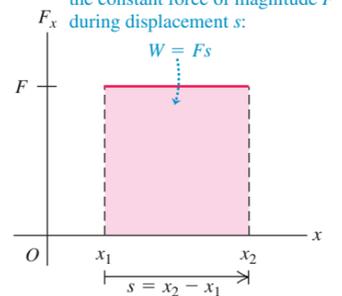
$$W = \int_0^X F_x dx = \int_0^X kx dx = \frac{1}{2}kX^2 \quad (6.9)$$

We can also obtain this result graphically. The area of the shaded triangle in Fig. 6.19, representing the total work done by the force, is equal to half the product of the base and altitude, or

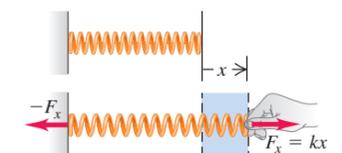
$$W = \frac{1}{2}(X)(kX) = \frac{1}{2}kX^2$$

6.17 The work done by a constant force F in the x -direction as a particle moves from x_1 to x_2 .

The rectangular area under the graph represents the work done by the constant force of magnitude F during displacement s :

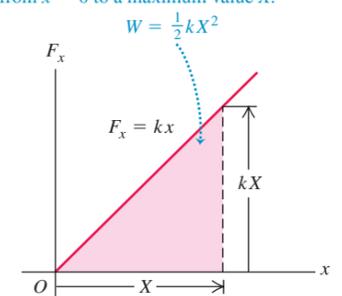


6.18 The force needed to stretch an ideal spring is proportional to the spring's elongation: $F_x = kx$.



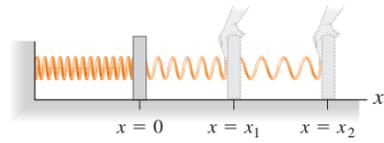
6.19 Calculating the work done to stretch a spring by a length X .

The area under the graph represents the work done on the spring as the spring is stretched from $x = 0$ to a maximum value X :



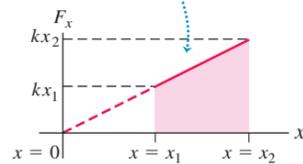
6.20 Calculating the work done to stretch a spring from one extension to a greater one.

(a) Stretching a spring from elongation x_1 to elongation x_2



(b) Force-versus-distance graph

The trapezoidal area under the graph represents the work done on the spring to stretch it from $x = x_1$ to $x = x_2$: $W = \frac{1}{2}kx_2^2 - \frac{1}{2}kx_1^2$



This equation also says that the work is the *average* force $kX/2$ multiplied by the total displacement X . We see that the total work is proportional to the *square* of the final elongation X . To stretch an ideal spring by 2 cm, you must do four times as much work as is needed to stretch it by 1 cm.

Equation (6.9) assumes that the spring was originally unstretched. If initially the spring is already stretched a distance x_1 , the work we must do to stretch it to a greater elongation x_2 (Fig. 6.20a) is

$$W = \int_{x_1}^{x_2} F_x dx = \int_{x_1}^{x_2} kx dx = \frac{1}{2}kx_2^2 - \frac{1}{2}kx_1^2 \quad (6.10)$$

You should use your knowledge of geometry to convince yourself that the trapezoidal area under the graph in Fig. 6.20b is given by the expression in Eq. (6.10).

If the spring has spaces between the coils when it is unstretched, then it can also be compressed, and Hooke's law holds for compression as well as stretching. In this case the force and displacement are in the opposite directions from those shown in Fig. 6.18, and so F_x and x in Eq. (6.8) are both negative. Since both F_x and x are reversed, the force again is in the same direction as the displacement, and the work done by F_x is again positive. So the total work is still given by Eq. (6.9) or (6.10), even when X is negative or either or both of x_1 and x_2 are negative.

CAUTION **Work done on a spring vs. work done by a spring** Note that Eq. (6.10) gives the work that *you* must do *on* a spring to change its length. For example, if you stretch a spring that's originally relaxed, then $x_1 = 0$, $x_2 > 0$, and $W > 0$: The force you apply to one end of the spring is in the same direction as the displacement, and the work you do is positive. By contrast, the work that the *spring* does on whatever it's attached to is given by the *negative* of Eq. (6.10). Thus, as you pull on the spring, the spring does negative work on you. Paying careful attention to the sign of work will eliminate confusion later on! ■

Example 6.6 Work done on a spring scale

A woman weighing 600 N steps on a bathroom scale containing a stiff spring (Fig. 6.21). In equilibrium the spring is compressed 1.0 cm under her weight. Find the force constant of the spring and the total work done on it during the compression.

SOLUTION

IDENTIFY: In equilibrium the upward force exerted by the spring balances the downward force of the woman's weight. We'll use this principle and Eq. (6.8) to determine the force constant k , and

we'll use Eq. (6.10) to calculate the work W that the woman does on the spring to compress it.

SET UP: We take positive values of x to correspond to elongation (upward in Fig. 6.21), so that the displacement of the spring (x) and the x -component of the force that the woman exerts on it (F_x) are both negative.

EXECUTE: The top of the spring is displaced by $x = -1.0 \text{ cm} = -0.010 \text{ m}$, and the woman exerts a force $F_x = -600 \text{ N}$ on the spring. From Eq. (6.8) the force constant is

$$k = \frac{F_x}{x} = \frac{-600 \text{ N}}{-0.010 \text{ m}} = 6.0 \times 10^4 \text{ N/m}$$

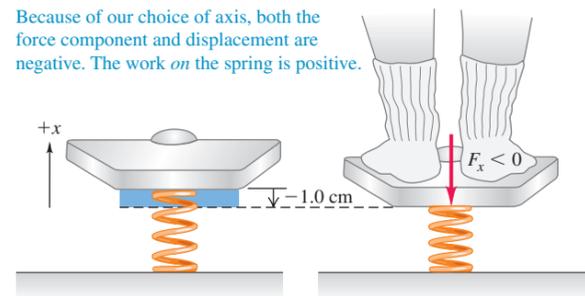
Then, using $x_1 = 0$ and $x_2 = -0.010 \text{ m}$ in Eq. (6.10),

$$\begin{aligned} W &= \frac{1}{2}kx_2^2 - \frac{1}{2}kx_1^2 \\ &= \frac{1}{2}(6.0 \times 10^4 \text{ N/m})(-0.010 \text{ m})^2 - 0 = 3.0 \text{ J} \end{aligned}$$

EVALUATE: The applied force and the displacement of the end of the spring were in the same direction, so the work done must have been positive—just as we found. Our arbitrary choice of the positive direction has no effect on the answer for W . (You can test this by taking the positive x -direction to be downward, corresponding to compression. You'll get the same values for k and W .)

6.21 Compressing a spring in a bathroom scale.

Because of our choice of axis, both the force component and displacement are negative. The work *on* the spring is positive.



Work–Energy Theorem for Straight-Line Motion, Varying Forces

In Section 6.2 we derived the work–energy theorem, $W_{\text{tot}} = K_2 - K_1$, for the special case of straight-line motion with a constant net force. We can now prove that this theorem is true even when the force varies with position. As in Section 6.2, let's consider a particle that undergoes a displacement x while being acted on by a net force with x -component F_x , which we now allow to vary. Just as in Fig. 6.16, we divide the total displacement x into a large number of small segments Δx . We can apply the work–energy theorem, Eq. (6.6), to each segment because the value of F_x in each small segment is approximately constant. The change in kinetic energy in segment Δx_a is equal to the work $F_{ax}\Delta x_a$, and so on. The total change of kinetic energy is the sum of the changes in the individual segments, and thus is equal to the total work done on the particle during the entire displacement. So $W_{\text{tot}} = \Delta K$ holds for varying forces as well as for constant ones.

Here's an alternative derivation of the work–energy theorem for a force that may vary with position. It involves making a change of variable from x to v_x in the work integral. As a preliminary, we note that the acceleration a of the particle can be expressed in various ways, using $a_x = dv_x/dt$, $v_x = dx/dt$, and the chain rule for derivatives:

$$a_x = \frac{dv_x}{dt} = \frac{dv_x}{dx} \frac{dx}{dt} = v_x \frac{dv_x}{dx} \quad (6.11)$$

From this result, Eq. (6.7) tells us that the total work done by the *net* force F_x is

$$W_{\text{tot}} = \int_{x_1}^{x_2} F_x dx = \int_{x_1}^{x_2} ma_x dx = \int_{x_1}^{x_2} mv_x \frac{dv_x}{dx} dx \quad (6.12)$$

Now $(dv_x/dx) dx$ is the change in velocity dv_x during the displacement dx , so in Eq. (6.12) we can substitute dv_x for $(dv_x/dx) dx$. This changes the integration variable from x to v_x , so we change the limits from x_1 and x_2 to the corresponding x -velocities v_1 and v_2 at these points. This gives us

$$W_{\text{tot}} = \int_{v_1}^{v_2} mv_x dv_x$$

The integral of $v_x dv_x$ is just $v_x^2/2$. Substituting the upper and lower limits, we finally find

$$W_{\text{tot}} = \frac{1}{2}mv_2^2 - \frac{1}{2}mv_1^2 \quad (6.13)$$

This is the same as Eq. (6.6), so the work–energy theorem is valid even without the assumption that the net force is constant.

Example 6.7 Motion with a varying force

An air-track glider of mass 0.100 kg is attached to the end of a horizontal air track by a spring with force constant 20.0 N/m (Fig. 6.22a). Initially the spring is unstretched and the glider is moving at 1.50 m/s to the right. Find the maximum distance d that the glider moves to the right (a) if the air track is turned on so that there is no friction, and (b) if the air is turned off so that there is kinetic friction with coefficient $\mu_k = 0.47$.

SOLUTION

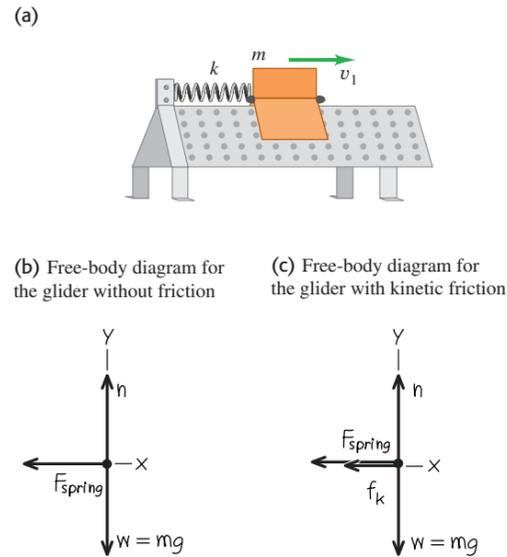
IDENTIFY: The force exerted by the spring is not constant, so we *cannot* use the constant-acceleration formulas of Chapter 2 to

solve this problem. Instead, we'll use the work–energy theorem, which involves the distance moved (our target variable) through the formula for work.

SET UP: In Figs. 6.22b and 6.22c we chose the positive x -direction to be to the right (in the direction of the glider's motion). We take $x = 0$ at the glider's initial position (where the spring is unstretched) and $x = d$ (the target variable) at the position where the glider stops. The motion is purely horizontal, so only the horizontal forces do work. Note that Eq. (6.10) gives the work done *on* the spring as it stretches, but to use the work–energy theorem we

Continued

6.22 (a) A glider attached to an air track by a spring. (b), (c) Our free-body diagrams.



The stretched spring subsequently pulls the glider back to the left, so the glider is at rest only instantaneously.

(b) If the air is turned off, we must also include the work done by the constant force of kinetic friction. The normal force n is equal in magnitude to the weight of the glider, since the track is horizontal and there are no other vertical forces. Hence the magnitude of the kinetic friction force is $f_k = \mu_k n = \mu_k mg$. The friction force is directed opposite to the displacement, so the work done by friction is

$$W_{\text{fric}} = f_k d \cos 180^\circ = -f_k d = -\mu_k mgd$$

The total work is the sum of W_{fric} and the work done by the spring, $-\frac{1}{2}kd^2$. The work–energy theorem then says that

$$\begin{aligned} -\mu_k mgd - \frac{1}{2}kd^2 &= 0 - \frac{1}{2}mv_1^2 \\ -(0.47)(0.100 \text{ kg})(9.8 \text{ m/s}^2)d - \frac{1}{2}(20.0 \text{ N/m})d^2 \\ &= -\frac{1}{2}(0.100 \text{ kg})(1.50 \text{ m/s})^2 \\ (10.0 \text{ N/m})d^2 + (0.461 \text{ N})d - (0.113 \text{ N} \cdot \text{m}) &= 0 \end{aligned}$$

This is a quadratic equation for d . The solutions are

$$\begin{aligned} d &= \frac{-(0.461 \text{ N}) \pm \sqrt{(0.461 \text{ N})^2 - 4(10.0 \text{ N/m})(-0.113 \text{ N} \cdot \text{m})}}{2(10.0 \text{ N/m})} \\ &= 0.086 \text{ m} \quad \text{or} \quad -0.132 \text{ m} \end{aligned}$$

We have used d as the symbol for a positive displacement, so only the positive value of d makes sense. Thus with friction the glider moves a distance

$$d = 0.086 \text{ m} = 8.6 \text{ cm}$$

EVALUATE: With friction present, the glider goes a shorter distance and the spring stretches less, as you might expect. Again the glider stops instantaneously, and again the spring force pulls the glider to the left; whether it moves or not depends on how great the static friction force is. How large would the coefficient of static friction μ_s have to be to keep the glider from springing back to the left?

Work–Energy Theorem for Motion Along a Curve

We can generalize our definition of work further to include a force that varies in direction as well as magnitude, and a displacement that lies along a curved path. Suppose a particle moves from point P_1 to P_2 along a curve, as shown in Fig. 6.23a. We divide the portion of the curve between these points into many infinitesimal vector displacements, and we call a typical one of these $d\vec{l}$. Each $d\vec{l}$ is tangent to the path at its position. Let \vec{F} be the force at a typical point along the path, and let ϕ be the angle between \vec{F} and $d\vec{l}$ at this point. Then the small element of work dW done on the particle during the displacement $d\vec{l}$ may be written as

$$dW = F \cos \phi \, dl = F_{\parallel} \, dl = \vec{F} \cdot d\vec{l}$$

where $F_{\parallel} = F \cos \phi$ is the component of \vec{F} in the direction parallel to $d\vec{l}$ (Fig. 6.23b). The total work done by \vec{F} on the particle as it moves from P_1 to P_2 is then

$$W = \int_{P_1}^{P_2} F \cos \phi \, dl = \int_{P_1}^{P_2} F_{\parallel} \, dl = \int_{P_1}^{P_2} \vec{F} \cdot d\vec{l} \quad (\text{work done on a curved path}) \quad (6.14)$$

We can now show that the work–energy theorem, Eq. (6.6), holds true even with varying forces and a displacement along a curved path. The force \vec{F} is essentially constant over any given infinitesimal segment $d\vec{l}$ of the path, so we can apply the work–energy theorem for straight-line motion to that segment. Thus the change in the particle’s kinetic energy K over that segment equals the work $dW = F_{\parallel} \, dl = \vec{F} \cdot d\vec{l}$ done on the particle. Adding up these infinitesimal quantities of work from all the segments along the whole path gives the total work done, Eq. (6.14), which equals the total change in kinetic energy over the whole path. So $W_{\text{tot}} = \Delta K = K_2 - K_1$ is true *in general*, no matter what the path and no matter what the character of the forces. This can be proved more rigorously by using steps like those in Eqs. (6.11) through (6.13) (see Challenge Problem 6.104).

Note that only the component of the net force parallel to the path, F_{\parallel} , does work on the particle, so only this component can change the speed and kinetic energy of the particle. The component perpendicular to the path, $F_{\perp} = F \sin \phi$, has no effect on the particle’s speed; it acts only to change the particle’s direction.

The integral in Eq. (6.14) is called a *line integral*. To evaluate this integral in a specific problem, we need some sort of detailed description of the path and of the way in which \vec{F} varies along the path. We usually express the line integral in terms of some scalar variable, as in the following example.

Example 6.8 Motion on a curved path I

At a family picnic you are appointed to push your obnoxious cousin Throckmorton in a swing (Fig. 6.24a). His weight is w , the length of the chains is R , and you push Throcky until the chains make an angle θ_0 with the vertical. To do this, you exert a varying horizontal force \vec{F} that starts at zero and gradually increases just enough so that Throcky and the swing move very slowly and remain very nearly in equilibrium. What is the total work done on Throcky by all forces? What is the work done by the tension T in the chains? What is the work you do by exerting the force \vec{F} ? (Neglect the weight of the chains and seat.)

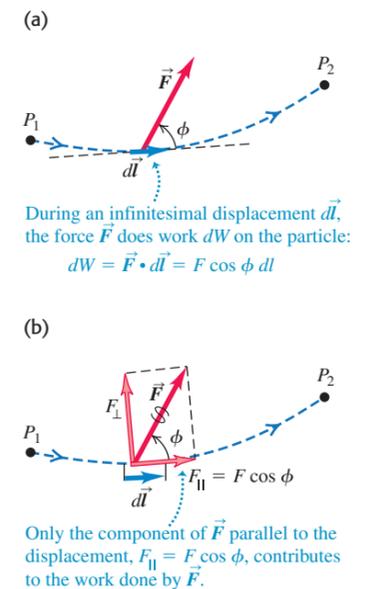
SOLUTION

IDENTIFY: The motion is along a curve, so we will use Eq. (6.14) to calculate the work done by the net force, by the tension force, and by the force \vec{F} .

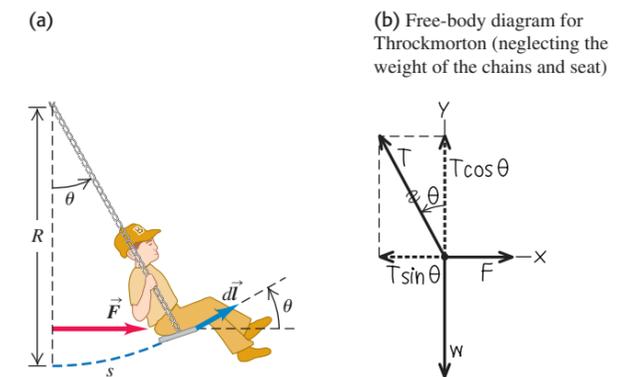
SET UP: Figure 6.24b shows our free-body diagram and coordinate system. We have replaced the tensions in the two chains with a single tension T .

EXECUTE: There are two ways to find the total work done during the motion: (1) by calculating the work done by each force and then adding the quantities of work together, and (2) by calculating the work done by the net force. The second approach is far easier in this situation because Throcky is in equilibrium at every point. Hence the net force on him is zero, the integral of the net force in

6.23 A particle moves along a curved path from point P_1 to P_2 , acted on by a force \vec{F} that varies in magnitude and direction.



6.24 (a) Pushing cousin Throckmorton in a swing. (b) Our free-body diagram.



Eq. (6.14) is zero, and the total work done on him by all forces is zero.

It’s also easy to find the work done by the chain tension on Throcky because this force is perpendicular to the direction of motion at all points along the path. Hence at all points the angle between the chain tension and the displacement vector $d\vec{l}$ is 90° and the scalar product in Eq. (6.14) is zero. Thus the chain tension does zero work.

Continued

To compute the work done by \vec{F} , we need to know how this force varies with the angle θ . The net force on Throcky is zero, so $\sum F_x = 0$ and $\sum F_y = 0$. From Fig. 6.24b, we get

$$\begin{aligned}\sum F_x &= F + (-T \sin \theta) = 0 \\ \sum F_y &= T \cos \theta + (-w) = 0\end{aligned}$$

By eliminating T from these two equations, we obtain

$$F = w \tan \theta$$

The point where \vec{F} is applied swings through the arc s . The arc length s equals the radius R of the circular path multiplied by the length θ (in radians), so $s = R\theta$. Therefore the displacement $d\vec{l}$ corresponding to a small change of angle $d\theta$ has a magnitude $dl = ds = R d\theta$. The work done by \vec{F} is

$$W = \int \vec{F} \cdot d\vec{l} = \int F \cos \theta ds$$

Now we express everything in terms of the angle θ , whose value increases from 0 to θ_0 :

$$\begin{aligned}W &= \int_0^{\theta_0} (w \tan \theta) \cos \theta (R d\theta) = wR \int_0^{\theta_0} \sin \theta d\theta \\ &= wR(1 - \cos \theta_0)\end{aligned}$$

EVALUATE: If $\theta_0 = 0$, there is no displacement; then $\cos \theta_0 = 1$ and $W = 0$, as we should expect. If $\theta_0 = 90^\circ$, then $\cos \theta_0 = 0$ and $W = wR$. In that case the work you do is the same as if you had lifted Throcky straight up a distance R with a force equal to his weight w . In fact, the quantity $R(1 - \cos \theta_0)$ is the increase in his height above the ground during the displacement, so for any value of θ_0 the work done by the force \vec{F} is the change in height multiplied by the weight. This is an example of a more general result that we'll prove in Section 7.1.

Example 6.9 Motion on a curved path II

In Example 6.8 the infinitesimal displacement $d\vec{l}$ (Fig. 6.24a) has a magnitude of ds , an x -component of $ds \cos \theta$, and a y -component of $ds \sin \theta$. Hence $d\vec{l} = \hat{i} ds \cos \theta + \hat{j} ds \sin \theta$. Use this expression and Eq. (6.14) to calculate the work done during the motion by the chain tension, by the force of gravity, and by the force \vec{F} .

SOLUTION

IDENTIFY: We again use Eq. (6.14), but now we'll use Eq. (1.21) to find the scalar product in terms of components.

SET UP: We use the same free-body diagram, Fig. 6.24b, as in Example 6.8.

EXECUTE: From Fig. 6.24b, we can write the three forces in terms of unit vectors:

$$\begin{aligned}\vec{T} &= \hat{i}(-T \sin \theta) + \hat{j}T \cos \theta \\ \vec{w} &= \hat{j}(-w) \\ \vec{F} &= \hat{i}F\end{aligned}$$

To use Eq. (6.14), we must calculate the scalar product of each of these forces with $d\vec{l}$. Using Eq. (1.21),

$$\begin{aligned}\vec{T} \cdot d\vec{l} &= (-T \sin \theta)(ds \cos \theta) + (T \cos \theta)(ds \sin \theta) = 0 \\ \vec{w} \cdot d\vec{l} &= (-w)(ds \sin \theta) = -w \sin \theta ds \\ \vec{F} \cdot d\vec{l} &= F(ds \cos \theta) = F \cos \theta ds\end{aligned}$$

Test Your Understanding of Section 6.3 In Example 5.21 (Section 5.4) we examined a conical pendulum. The speed of the pendulum bob remains constant as it travels around the circle shown in Fig. 5.32a. (a) Over one complete circle, how much work does the tension force F do on the bob? (i) a positive amount; (ii) a negative amount; (iii) zero. (b) Over one complete circle, how much work does the weight do on the bob? (i) a positive amount; (ii) a negative amount; (iii) zero.



6.4 Power

The definition of work makes no reference to the passage of time. If you lift a barbell weighing 100 N through a vertical distance of 1.0 m at constant velocity, you do $(100 \text{ N})(1.0 \text{ m}) = 100 \text{ J}$ of work whether it takes you 1 second, 1 hour, or 1 year to do it. But often we need to know how quickly work is done. We describe this in terms of *power*. In ordinary conversation the word “power” is often synonymous with “energy” or “force.” In physics we use a much more precise definition: **Power** is the time *rate* at which work is done. Like work and energy, power is a scalar quantity.

When a quantity of work ΔW is done during a time interval Δt , the average work done per unit time or **average power** P_{av} is defined to be

$$P_{\text{av}} = \frac{\Delta W}{\Delta t} \quad (\text{average power}) \quad (6.15)$$

The rate at which work is done might not be constant. We can define **instantaneous power** P as the quotient in Eq. (6.15) as Δt approaches zero:

$$P = \lim_{\Delta t \rightarrow 0} \frac{\Delta W}{\Delta t} = \frac{dW}{dt} \quad (\text{instantaneous power}) \quad (6.16)$$

The SI unit of power is the **watt** (W), named for the English inventor James Watt. One watt equals 1 joule per second: $1 \text{ W} = 1 \text{ J/s}$ (Fig. 6.25). The kilowatt ($1 \text{ kW} = 10^3 \text{ W}$) and the megawatt ($1 \text{ MW} = 10^6 \text{ W}$) are also commonly used. In the British system, work is expressed in foot-pounds, and the unit of power is the foot-pound per second. A larger unit called the *horsepower* (hp) is also used (Fig. 6.26):

$$1 \text{ hp} = 550 \text{ ft} \cdot \text{lb/s} = 33,000 \text{ ft} \cdot \text{lb/min}$$

That is, a 1-hp motor running at full load does 33,000 ft · lb of work every minute. A useful conversion factor is

$$1 \text{ hp} = 746 \text{ W} = 0.746 \text{ kW}$$

The watt is a familiar unit of *electrical* power; a 100-W light bulb converts 100 J of electrical energy into light and heat each second. But there's nothing inherently electrical about a watt. A light bulb could be rated in horsepower, and an engine can be rated in kilowatts.

The *kilowatt-hour* ($\text{kW} \cdot \text{h}$) is the usual commercial unit of electrical energy. One kilowatt-hour is the total work done in 1 hour (3600 s) when the power is 1 kilowatt (10^3 J/s), so

$$1 \text{ kW} \cdot \text{h} = (10^3 \text{ J/s})(3600 \text{ s}) = 3.6 \times 10^6 \text{ J} = 3.6 \text{ MJ}$$

The kilowatt-hour is a unit of *work* or *energy*, not power.

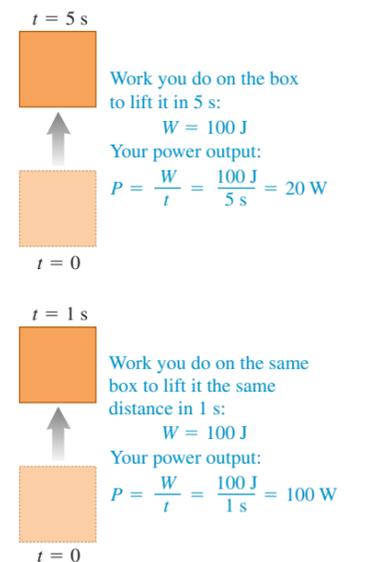
In mechanics we can also express power in terms of force and velocity. Suppose that a force \vec{F} acts on a body while it undergoes a vector displacement $\Delta \vec{s}$. If F_{\parallel} is the component of \vec{F} tangent to the path (parallel to $\Delta \vec{s}$), then the work done by the force is $\Delta W = F_{\parallel} \Delta s$. The average power is

$$P_{\text{av}} = \frac{F_{\parallel} \Delta s}{\Delta t} = F_{\parallel} \frac{\Delta s}{\Delta t} = F_{\parallel} v_{\text{av}} \quad (6.17)$$

Instantaneous power P is the limit of this expression as $\Delta t \rightarrow 0$:

$$P = F_{\parallel} v \quad (6.18)$$

6.25 The same amount of work is done in both of these situations, but the power (the rate at which work is done) is different.



6.26 The value of the horsepower derives from experiments by James Watt, who measured that a horse could do 33,000 foot-pounds of work per minute in lifting coal from a coal pit.



where v is the magnitude of the instantaneous velocity. We can also express Eq. (6.18) in terms of the scalar product:

$$P = \vec{F} \cdot \vec{v} \quad (\text{instantaneous rate at which force } \vec{F} \text{ does work on a particle)} \quad (6.19)$$

Example 6.10 Force and power

Each of the two jet engines in a Boeing 767 airliner develops a thrust (a forward force on the airplane) of 197,000 N (44,300 lb). When the airplane is flying at 250 m/s (900 km/h, or roughly 560 mi/h), what horsepower does each engine develop?

SOLUTION

IDENTIFY: Our target variable is the instantaneous power P , which is the rate at which the thrust does work.

SET UP: We use Eq. (6.18). The thrust is in the direction of motion, so F_{\parallel} is just equal to the thrust.

EXECUTE: At $v = 250$ m/s, the power developed by each engine is

$$\begin{aligned} P &= F_{\parallel}v = (1.97 \times 10^5 \text{ N})(250 \text{ m/s}) = 4.93 \times 10^7 \text{ W} \\ &= (4.93 \times 10^7 \text{ W}) \frac{1 \text{ hp}}{746 \text{ W}} = 66,000 \text{ hp} \end{aligned}$$

EVALUATE: The speed of modern airliners is directly related to the power of their engines (Fig. 6.27). The largest propeller-driven airliners of the 1950s had engines that developed about 3400 hp (2.5×10^6 W), giving them maximum speeds of about 600 km/h (370 mi/h). Each engine in a Boeing 767 develops nearly 20 times more power, enabling it to fly at about 900 km/h (560 mi/h) and to carry a much heavier load.

If the engines are at maximum thrust while the airliner is at rest on the ground so that $v = 0$, the engines develop *zero* power. Force and power are not the same thing!

6.27 (a) Propeller-driven and (b) jet airliners.



The time is 15.0 min = 900 s, so from Eq. (6.15) the average power is

$$P_{\text{av}} = \frac{2.17 \times 10^5 \text{ J}}{900 \text{ s}} = 241 \text{ W} = 0.241 \text{ kW} = 0.323 \text{ hp}$$

Let's try the calculation again using Eq. (6.17). The force exerted is vertical, and the average vertical component of velocity is $(443 \text{ m})/(900 \text{ s}) = 0.492$ m/s, so the average power is

$$\begin{aligned} P_{\text{av}} &= F_{\parallel}v_{\text{av}} = (mg)v_{\text{av}} \\ &= (50.0 \text{ kg})(9.80 \text{ m/s}^2)(0.492 \text{ m/s}) = 241 \text{ W} \end{aligned}$$

which is the same result as before.

EVALUATE: The runner's *total* power output will be several times greater than 241 W. The reason is that the runner isn't really a particle but a collection of parts that exert forces on each other and do work, such as the work done to inhale and exhale and to make her arms and legs swing. What we've calculated is only the part of her power output that lifts her to the top of the building.

Test Your Understanding of Section 6.4 The air surrounding an airplane in flight exerts a drag force that acts opposite to the airplane's motion. When the Boeing 767 in Example 6.10 is flying in a straight line at a constant altitude at a constant 250 m/s, what is the rate at which the drag force does work on it? (i) 132,000 hp; (ii) 66,000 hp; (iii) 0; (iv) -66,000 hp; (v) -132,000 hp.



Example 6.11 A "power climb"

A 50.0-kg marathon runner runs up the stairs to the top of Chicago's 443-m-tall Sears Tower, the tallest building in the United States (Fig. 6.28). To lift herself to the top in 15.0 minutes, what must be her average power output in watts? In kilowatts? In horsepower?

SOLUTION

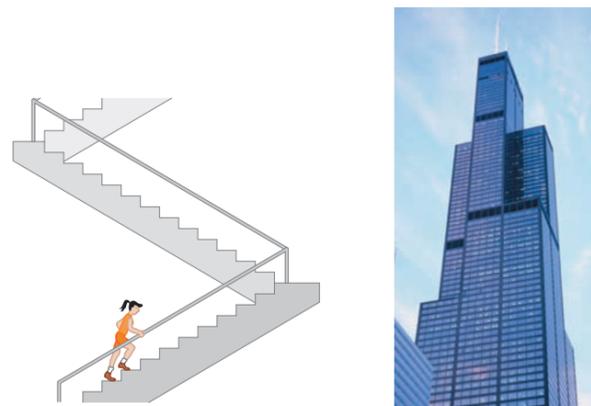
IDENTIFY: We'll treat the runner as a particle of mass m . Her average power output P_{av} must be enough to lift her at constant speed against gravity.

SET UP: We can find P_{av} in two ways: (1) by first determining how much work she must do and then dividing it by the elapsed time, as in Eq. (6.15), or (2) by calculating the average upward force she must exert (in the direction of the climb) and then multiplying it by her upward velocity, as in Eq. (6.17).

EXECUTE: As in Example 6.8, lifting a mass m against gravity requires an amount of work equal to the weight mg multiplied by the height h it is lifted. Hence the work she must do is

$$\begin{aligned} W &= mgh = (50.0 \text{ kg})(9.80 \text{ m/s}^2)(443 \text{ m}) \\ &= 2.17 \times 10^5 \text{ J} \end{aligned}$$

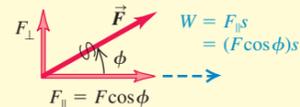
6.28 How much power is required to run up the stairs of Chicago's Sears Tower in 15 minutes?



Work done by a force: When a constant force \vec{F} acts on a particle that undergoes a straight-line displacement \vec{s} , the work done by the force on the particle is defined to be the scalar product of \vec{F} and \vec{s} . The unit of work in SI units is 1 joule = 1 newton-meter (1 J = 1 N · m). Work is a scalar quantity; it can be positive or negative, but it has no direction in space. (See Examples 6.1 and 6.2.)

$$W = \vec{F} \cdot \vec{s} = F_s \cos \phi \quad (6.2), (6.3)$$

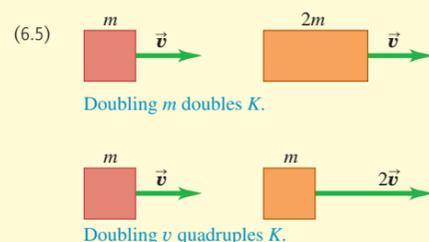
$$\phi = \text{angle between } \vec{F} \text{ and } \vec{s}$$



Kinetic energy: The kinetic energy K of a particle equals the amount of work required to accelerate the particle from rest to speed v . It is also equal to the amount of work the particle can do in the process of being brought to rest. Kinetic energy is a scalar that has no direction in space; it is always positive or zero. Its units are the same as the units of work:

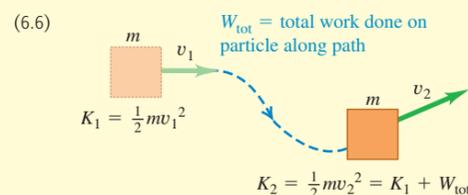
$$K = \frac{1}{2}mv^2$$

$$1 \text{ J} = 1 \text{ N} \cdot \text{m} = 1 \text{ kg} \cdot \text{m}^2/\text{s}^2$$



The work-energy theorem: When forces act on a particle while it undergoes a displacement, the particle's kinetic energy changes by an amount equal to the total work done on the particle by all the forces. This relationship, called the work-energy theorem, is valid whether the forces are constant or varying and whether the particle moves along a straight or curved path. It is applicable only to bodies that can be treated as a particle. (See Examples 6.3–6.5)

$$W_{\text{tot}} = K_2 - K_1 = \Delta K$$

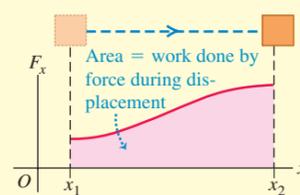


Work done by a varying force or on a curved path: When a force varies during a straight-line displacement, the work done by the force is given by an integral, Eq. (6.7). (See Examples 6.6 and 6.7.) When a particle follows a curved path, the work done on it by a force \vec{F} is given by an integral that involves the angle ϕ between the force and the displacement. This expression is valid even if the force magnitude and the angle ϕ vary during the displacement. (See Examples 6.8 and 6.9.)

$$W = \int_{x_1}^{x_2} F_x dx \quad (6.7)$$

$$W = \int_{P_1}^{P_2} F \cos \phi dl = \int_{P_1}^{P_2} F_{\parallel} dl \quad (6.14)$$

$$= \int_{P_1}^{P_2} \vec{F} \cdot d\vec{l}$$

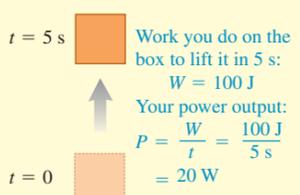


Power: Power is the time rate of doing work. The average power P_{av} is the amount of work ΔW done in time Δt divided by that time. The instantaneous power is the limit of the average power as Δt goes to zero. When a force \vec{F} acts on a particle moving with velocity \vec{v} , the instantaneous power (the rate at which the force does work) is the scalar product of \vec{F} and \vec{v} . Like work and kinetic energy, power is a scalar quantity. The SI unit of power is 1 watt = 1 joule/second (1 W = 1 J/s). (See Examples 6.10 and 6.11.)

$$P_{\text{av}} = \frac{\Delta W}{\Delta t} \quad (6.15)$$

$$P = \lim_{\Delta t \rightarrow 0} \frac{\Delta W}{\Delta t} = \frac{dW}{dt} \quad (6.16)$$

$$P = \vec{F} \cdot \vec{v} \quad (6.19)$$



Key Terms

- work, 182
- joule, 182
- kinetic energy, 187
- work-energy theorem, 187
- force constant, 193
- Hooke's law, 193
- power, 199
- average power, 199
- instantaneous power, 199
- watt, 199

Answer to Chapter Opening Question

It is indeed true that the shell does work on the gases. However, because the shell exerts a backward force on the gases as the gases and shell move forward through the barrel, the work done by the shell is *negative* (see Section 6.1).

Answers to Test Your Understanding Questions

- 6.1 Answer: (iii)** The electron has constant velocity, so its acceleration is zero and (by Newton's second law) the net force on the electron is also zero. Therefore the total work done by all the forces (equal to the work done by the net force) must be zero as well. The individual forces may do nonzero work, but that's not what the question asks.
- 6.2 Answer: (iv), (i), (iii), (ii)** Body (i) has kinetic energy $K = \frac{1}{2}mv^2 = \frac{1}{2}(2.0 \text{ kg})(5.0 \text{ m/s})^2 = 25 \text{ J}$. Body (ii) had zero kinetic energy initially and then had 30 J of work done on it, so its final kinetic energy is $K_2 = K_1 + W = 0 + 30 \text{ J} = 30 \text{ J}$. Body (iii) had initial kinetic energy $K_1 = \frac{1}{2}mv_1^2 = \frac{1}{2}(1.0 \text{ kg})(4.0 \text{ m/s})^2 = 8.0 \text{ J}$ and then had 20 J of work done on it, so its final kinetic energy is $K_2 = K_1 + W = 8.0 \text{ J} + 20 \text{ J} = 28 \text{ J}$. Body (iv) had initial kinetic

energy $K_1 = \frac{1}{2}mv_1^2 = \frac{1}{2}(2.0 \text{ kg})(10 \text{ m/s})^2 = 100 \text{ J}$; when it did 80 J of work on another body, the other body did -80 J of work on body (iv), so the final kinetic energy of body (iv) is $K_2 = K_1 + W = 100 \text{ J} + (-80 \text{ J}) = 20 \text{ J}$.

6.3 Answers: (a) (iii), (b) (iii) At any point during the pendulum bob's motion, the tension force and the weight both act perpendicular to the motion—that is, perpendicular to an infinitesimal displacement $d\vec{l}$ of the bob. (In Fig. 5.32b, the displacement $d\vec{l}$ would be directed outward from the plane of the free-body diagram.) Hence for either force the scalar product inside the integral in Eq. (6.14) is $\vec{F} \cdot d\vec{l} = 0$, and the work done along any part of the circular path (including a complete circle) is $W = \int \vec{F} \cdot d\vec{l} = 0$.

6.4 Answer: (v) The airliner has a constant horizontal velocity, so the net horizontal force on it must be zero. Hence the backward drag force must have the same magnitude as the forward force due to the combined thrust of the two engines. This means that the drag force must do *negative* work on the airplane at the same rate that the combined thrust force does *positive* work. The combined thrust does work at a rate of $2(66,000 \text{ hp}) = 132,000 \text{ hp}$, so the drag force must do work at a rate of $-132,000 \text{ hp}$.

PROBLEMS

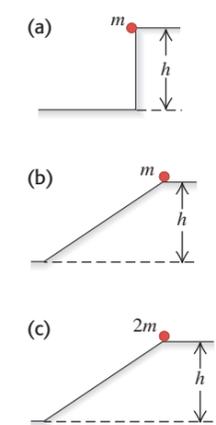
For instructor-assigned homework, go to www.masteringphysics.com

Discussion Questions

- Q6.1.** The sign of many physical quantities depends on the choice of coordinates. For example, g can be negative or positive, depending on whether we choose upward or downward as positive. Is the same thing true of work? In other words, can we make positive work negative by a different choice of coordinates? Explain.
- Q6.2.** An elevator is hoisted by its cables at constant speed. Is the total work done on the elevator positive, negative, or zero? Explain.
- Q6.3.** A rope tied to a body is pulled, causing the body to accelerate. But according to Newton's third law, the body pulls back on the rope with an equal and opposite force. Is the total work done then zero? If so, how can the body's kinetic energy change? Explain.
- Q6.4.** If it takes total work W to give an object a speed v and kinetic energy K , starting from rest, what will be the object's speed (in terms of v) and kinetic energy (in terms of K) if we do twice as much work on it, again starting from rest?
- Q6.5.** If there is a net nonzero force on a moving object, is it possible for the total work done on the object to be zero? Explain, with an example that illustrates your answer.
- Q6.6.** In Example 5.5 (Section 5.1), how does the work done on the bucket by the tension in the cable compare to the work done on the cart by the tension in the cable?
- Q6.7.** In the conical pendulum in Example 5.21 (Section 5.4), which of the forces do work on the bob while it is swinging?

- Q6.8.** For the cases shown in Fig. 6.29, the object is released from rest at the top and feels no friction or air resistance. In which (if any) cases will the mass have (i) the greatest speed at the bottom and (ii) the most work done on it by the time it reaches the bottom?
- Q6.9.** A force \vec{F} is in the x -direction and has a magnitude that depends on x . Sketch a possible graph of F versus x such that the force does zero work on an object that moves from x_1 to x_2 , even though the force magnitude is not zero at all x in this range.
- Q6.10.** Does the kinetic energy of a car change more when it speeds up from 10 to 15 m/s or from 15 to 20 m/s? Explain.
- Q6.11.** A falling brick has a mass of 1.5 kg and is moving straight downward with a speed of 5.0 m/s. A 1.5-kg physics book is sliding across the floor with a speed of 5.0 m/s. A 1.5-kg melon is traveling with a horizontal velocity component 3.0 m/s to the right and a vertical component 4.0 m/s upward. Do these objects all have the same velocity? Do these objects all have the same kinetic energy? For each question, give the reasoning behind your answer.

Figure 6.29 Question Q6.8.



- Q6.12.** Can the *total* work done on an object during a displacement be negative? Explain. If the total work is negative, can its magnitude be larger than the initial kinetic energy of the object? Explain.
- Q6.13.** A net force acts on an object and accelerates it from rest to a speed v_1 . In doing so, the force does an amount of work W_1 . By what factor must the work done on the object be increased to produce three times the final speed, with the object again starting from rest?
- Q6.14.** A truck speeding down the highway has a lot of kinetic energy relative to a stopped state trooper, but no kinetic energy relative to the truck driver. In these two frames of reference, is the same amount of work required to stop the truck? Explain.
- Q6.15.** You are holding a briefcase by the handle, with your arm straight down by your side. Does the force your hand exerts do work on the briefcase when (a) you walk at a constant speed down a horizontal hallway and (b) you ride an escalator from the first to second floor of a building? In each case justify your answer.
- Q6.16.** When a book slides along a tabletop, the force of friction does negative work on it. Can friction ever do *positive* work? Explain. (*Hint:* Think of a box in the back of an accelerating truck.)
- Q6.17.** Time yourself while running up a flight of steps, and compute the average rate at which you do work against the force of gravity. Express your answer in watts and in horsepower.
- Q6.18. Fractured Physics.** Many terms from physics are badly misused in everyday language. In each case, explain the errors involved. (a) A *strong* person is called *powerful*. What is wrong with this use of *power*? (b) When a worker carries a bag of concrete along a level construction site, people say he did a lot of *work*. Did he?
- Q6.19.** An advertisement for a portable electrical generating unit claims that the unit's diesel engine produces 28,000 hp to drive an electrical generator that produces 30 MW of electrical power. Is this possible? Explain.
- Q6.20.** A car speeds up while the engine delivers constant power. Is the acceleration greater at the beginning of this process or at the end? Explain.
- Q6.21.** Consider a graph of instantaneous power versus time, with the vertical P axis starting at $P = 0$. What is the physical significance of the area under the P versus t curve between vertical lines at t_1 and t_2 ? How could you find the average power from the graph? Draw a P versus t curve that consists of two straight-line sections and for which the peak power is equal to twice the average power.
- Q6.22.** A nonzero net force acts on an object. Is it possible for any of the following quantities to be constant: (a) the particle's speed; (b) the particle's velocity; (c) the particle's kinetic energy.
- Q6.23.** When a certain force is applied to an ideal spring, the spring stretches a distance x from its unstretched length and does work W . If instead twice the force is applied, what distance (in terms of x) does the spring stretch from its unstretched length, and how much work (in terms of W) is required to stretch it this distance?
- Q6.24.** If work W is required to stretch a spring a distance x from its unstretched length, what work (in terms of W) is required to stretch the spring an *additional* distance x ?

Exercises

Section 6.1 Work

- 6.1.** An old oaken bucket of mass 6.75 kg hangs in a well at the end of a rope. The rope passes over a frictionless pulley at the top of the well, and you pull horizontally on the end of the rope to raise the bucket slowly a distance of 4.00 m. (a) How much work

do you do on the bucket in pulling it up? (b) How much work does gravity do on the bucket? (c) What is the total work done on the bucket?

6.2. A tow truck pulls a car 5.00 km along a horizontal roadway using a cable having a tension of 850 N. (a) How much work does the cable do on the car if it pulls horizontally? If it pulls at 35.0° above the horizontal? (b) How much work does the cable do on the tow truck in both cases of part (a)? (c) How much work does gravity do on the car in part (a)?

6.3. A factory worker pushes a 30.0-kg crate a distance of 4.5 m along a level floor at constant velocity by pushing horizontally on it. The coefficient of kinetic friction between the crate and the floor is 0.25. (a) What magnitude of force must the worker apply? (b) How much work is done on the crate by this force? (c) How much work is done on the crate by friction? (d) How much work is done on the crate by the normal force? By gravity? (e) What is the total work done on the crate?

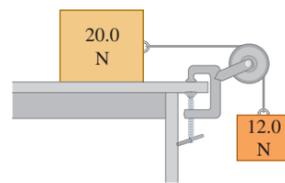
6.4. Suppose the worker in Exercise 6.3 pushes downward at an angle of 30° below the horizontal. (a) What magnitude of force must the worker apply to move the crate at constant velocity? (b) How much work is done on the crate by this force when the crate is pushed a distance of 4.5 m? (c) How much work is done on the crate by friction during this displacement? (d) How much work is done on the crate by the normal force? By gravity? (e) What is the total work done on the crate?

6.5. A 75.0-kg painter climbs a ladder that is 2.75 m long leaning against a vertical wall. The ladder makes an 30.0° angle with the wall. (a) How much work does gravity do on the painter? (b) Does the answer to part (a) depend on whether the painter climbs at constant speed or accelerates up the ladder?

6.6. Two tugboats pull a disabled supertanker. Each tug exerts a constant force of 1.80×10^6 N, one 14° west of north and the other 14° east of north, as they pull the tanker 0.75 km toward the north. What is the total work they do on the supertanker?

6.7. Two blocks are connected by a very light string passing over a massless and frictionless pulley (Figure 6.30). Traveling at constant speed, the 20.0-N block moves 75.0 cm to the right and the 12.0-N block moves 75.0 cm downward. During this process, how much work is done (a) on the 12.0-N block by (i) gravity and (ii) the tension in the string? (b) On the 20.0-N block by (i) gravity, (ii) the tension in the string, (iii) friction, and (iv) the normal force? (c) Find the total work done on each block.

Figure 6.30 Exercise 6.7.



6.8. A loaded grocery cart is rolling across a parking lot in a strong wind. You apply a constant force $\vec{F} = (30 \text{ N})\hat{i} - (40 \text{ N})\hat{j}$ to the cart as it undergoes a displacement $\vec{s} = (-9.0 \text{ m})\hat{i} - (3.0 \text{ m})\hat{j}$. How much work does the force you apply do on the grocery cart?

6.9. A 0.800-kg ball is tied to the end of a string 1.60 m long and swung in a vertical circle. (a) During one complete circle, starting anywhere, calculate the total work done on the ball by (i) the tension in the string and (ii) gravity. (b) Repeat part (a) for motion along the semicircle from the lowest to the highest point on the path.

Section 6.2 Kinetic Energy and the Work–Energy Theorem

6.10. (a) How many joules of kinetic energy does a 750-kg automobile traveling at a typical highway speed of 65 mi/h have? (b) By what factor would its kinetic energy decrease if the car traveled half as fast? (c) How fast (in mi/h) would the car have to travel to have half as much kinetic energy as in part (a)?

6.11. Meteor Crater. About 50,000 years ago, a meteor crashed into the earth near present-day Flagstaff, Arizona. Recent (2005) measurements estimate that this meteor had a mass of about 1.4×10^8 kg (around 150,000 tons) and hit the ground at 12 km/s. (a) How much kinetic energy did this meteor deliver to the ground? (b) How does this energy compare to the energy released by a 1.0-megaton nuclear bomb? (A megaton bomb releases the same energy as a million tons of TNT, and 1.0 ton of TNT releases 4.184×10^9 J of energy.)

6.12. Some Typical Kinetic Energies. (a) How many joules of kinetic energy does a 75-kg person have when walking and when running? (b) In the Bohr model of the atom, the ground-state electron in hydrogen has an orbital speed of 2190 km/s. What is its kinetic energy? (Consult Appendix F.) (c) If you drop a 1.0-kg weight (about 2 lb) from shoulder height, how many joules of kinetic energy will it have when it reaches the ground? (d) Is it reasonable that a 30-kg child could run fast enough to have 100 J of kinetic energy?

6.13. The mass of a proton is 1836 times the mass of an electron. (a) A proton is traveling at speed V . At what speed (in terms of V) would an electron have the same kinetic energy as the proton? (b) An electron has kinetic energy K . If a proton has the same speed as the electron, what is its kinetic energy (in terms of K)?

6.14. A 4.80-kg watermelon is dropped from rest from the roof of a 25.0-m-tall building and feels no appreciable air resistance. (a) Calculate the work done by gravity on the watermelon during its displacement from the roof to the ground. (b) Just before it strikes the ground, what is the watermelon's (i) kinetic energy and (ii) speed? (c) Which of the answers in parts (a) and (b) would be *different* if there were appreciable air resistance?

6.15. Use the work–energy theorem to solve each of these problems. You can use Newton's laws to check your answers. Neglect air resistance in all cases. (a) A branch falls from the top of a 95.0-m-tall redwood tree, starting from rest. How fast is it moving when it reaches the ground? (b) A volcano ejects a boulder directly upward 525 m into the air. How fast was the boulder moving just as it left the volcano? (c) A skier moving at 5.00 m/s encounters a long, rough horizontal patch of snow having coefficient of kinetic friction 0.220 with her skis. How far does she travel on this patch before stopping? (d) Suppose the rough patch in part (c) was only 2.90 m long? How fast would the skier be moving when she reached the end of the patch? (e) At the base of a frictionless icy hill that rises at 25.0° above the horizontal, a toboggan has a speed of 12.0 m/s toward the hill. How high vertically above the base will it go before stopping?

6.16. You throw a 20-N rock vertically into the air from ground level. You observe that when it is 15.0 m above the ground, it is traveling at 25.0 m/s upward. Use the work–energy theorem to find (a) the rock's speed just as it left the ground and (b) its maximum height.

6.17. You are a member of an Alpine Rescue Team. You must project a box of supplies up an incline of constant slope angle α so that it reaches a stranded skier who is a vertical distance h above the bottom of the incline. The incline is slippery, but there is some

friction present, with kinetic friction coefficient μ_k . Use the work–energy theorem to calculate the minimum speed you must give the box at the bottom of the incline so that it will reach the skier. Express your answer in terms of g , h , μ_k , and α .

6.18. A mass m slides down a smooth inclined plane from an initial vertical height h , making an angle α with the horizontal. (a) The work done by a force is the sum of the work done by the components of the force. Consider the components of gravity parallel and perpendicular to the surface of the plane. Calculate the work done on the mass by each of the components, and use these results to show that the work done by gravity is exactly the same as if the mass had fallen straight down through the air from a height h . (b) Use the work–energy theorem to prove that the speed of the mass at the bottom of the incline is the same as if it had been dropped from height h , independent of the angle α of the incline. Explain how this speed can be independent of the slope angle. (c) Use the results of part (b) to find the speed of a rock that slides down an icy frictionless hill, starting from rest 15.0 m above the bottom.

6.19. A car is stopped in a distance D by a constant friction force that is independent of the car's speed. What is the stopping distance (in terms of D) (a) if the car's initial speed is tripled, and (b) if the speed is the same as it originally was but the friction force is tripled? (Solve using the work–energy theorem.)

6.20. A moving electron has kinetic energy K_1 . After a net amount of work W has been done on it, the electron is moving one-quarter as fast in the opposite direction. (a) Find W in terms of K_1 . (b) Does your answer depend on the final direction of the electron's motion?

6.21. A sled with mass 8.00 kg moves in a straight line on a frictionless horizontal surface. At one point in its path, its speed is 4.00 m/s; after it has traveled 2.50 m beyond this point, its speed is 6.00 m/s. Use the work–energy theorem to find the force acting on the sled, assuming that this force is constant and that it acts in the direction of the sled's motion.

6.22. A soccer ball with mass 0.420 kg is initially moving with speed 2.00 m/s. A soccer player kicks the ball, exerting a constant force of magnitude 40.0 N in the same direction as the ball's motion. Over what distance must the player's foot be in contact with the ball to increase the ball's speed to 6.00 m/s?

6.23. A 12-pack of Omni-Cola (mass 4.30 kg) is initially at rest on a horizontal floor. It is then pushed in a straight line for 1.20 m by a trained dog that exerts a horizontal force with magnitude 36.0 N. Use the work–energy theorem to find the final speed of the 12-pack if (a) there is no friction between the 12-pack and the floor, and (b) the coefficient of kinetic friction between the 12-pack and the floor is 0.30.

6.24. A batter hits a baseball with mass 0.145 kg straight upward with an initial speed of 25.0 m/s. (a) How much work has gravity done on the baseball when it reaches a height of 20.0 m above the bat? (b) Use the work–energy theorem to calculate the speed of the baseball at a height of 20.0 m above the bat. You can ignore air resistance. (c) Does the answer to part (b) depend on whether the baseball is moving upward or downward at a height of 20.0 m? Explain.

6.25. A little red wagon with mass 7.00 kg moves in a straight line on a frictionless horizontal surface. It has an initial speed of 4.00 m/s and then is pushed 3.0 m in the direction of the initial velocity by a force with a magnitude of 10.0 N. (a) Use the work–energy theorem to calculate the wagon's final speed. (b) Calculate the acceleration produced by the force. Use this acceleration in the

kinematic relationships of Chapter 2 to calculate the wagon's final speed. Compare this result to that calculated in part (a).

6.26. A block of ice with mass 2.00 kg slides 0.750 m down an inclined plane that slopes downward at an angle of 36.9° below the horizontal. If the block of ice starts from rest, what is its final speed? You can ignore friction.

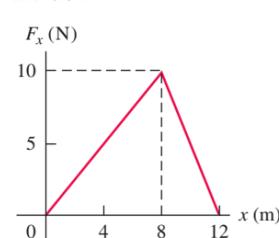
6.27. Stopping Distance. A car is traveling on a level road with speed v_0 at the instant when the brakes lock, so that the tires slide rather than roll. (a) Use the work–energy theorem to calculate the minimum stopping distance of the car in terms of v_0 , g , and the coefficient of kinetic friction μ_k between the tires and the road. (b) By what factor would the minimum stopping distance change if (i) the coefficient of kinetic friction were doubled, or (ii) the initial speed were doubled, or (iii) both the coefficient of kinetic friction and the initial speed were doubled?

Section 6.3 Work and Energy with Varying Forces

6.28. To stretch a spring 3.00 cm from its unstretched length, 12.0 J of work must be done. (a) What is the force constant of this spring? (b) What magnitude force is needed to stretch the spring 3.00 cm from its unstretched length? (c) How much work must be done to compress this spring 4.00 cm from its unstretched length, and what force is needed to stretch it this distance?

6.29. A force of 160 N stretches a spring 0.050 m beyond its unstretched length. (a) What magnitude of force is required to stretch the spring 0.015 m beyond its unstretched length? To compress the spring 0.020 m? (b) How much work must be done to stretch the spring 0.015 m beyond its unstretched length? To compress the spring 0.020 m from its unstretched length?

6.30. A child applies a force \vec{F} parallel to the x -axis to a 10.0-kg sled moving on the frozen surface of a small pond. As the child controls the speed of the sled, the x -component of the force she applies varies with the x -coordinate of the sled as shown in Fig. 6.31. Calculate the work done by the force \vec{F} when the sled moves (a) from $x = 0$ to $x = 8.0$ m; (b) from $x = 8.0$ m to $x = 12.0$ m; (c) from $x = 0$ to $x = 12.0$ m.



6.31. Suppose the sled in Exercise 6.30 is initially at rest at $x = 0$. Use the work–energy theorem to find the speed of the sled at (a) $x = 8.0$ m and (b) $x = 12.0$ m. You can ignore friction between the sled and the surface of the pond.

6.32. A balky cow is leaving the barn as you try harder and harder to push her back in. In coordinates with the origin at the barn door, the cow walks from $x = 0$ to $x = 6.9$ m as you apply a force with x -component $F_x = -[20.0 \text{ N} + (3.0 \text{ N/m})x]$. How much work does the force you apply do on the cow during this displacement?

6.33. A 6.0-kg box moving at 3.0 m/s on a horizontal, frictionless surface runs into a light spring of force constant 75 N/cm. Use the work–energy theorem to find the maximum compression of the spring.

6.34. Leg Presses. As part of your daily workout, you lie on your back and push with your feet against a platform attached to two stiff springs arranged side by side so that they are parallel to each other. When you push the platform, you compress the springs. You do 80.0 J of work when you compress the springs 0.200 m from their uncompressed length. (a) What magnitude of force must you apply to hold the platform in this position? (b) How much

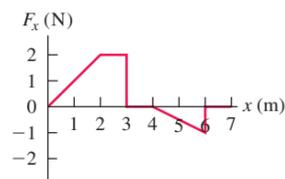
additional work must you do to move the platform 0.200 m farther, and what maximum force must you apply?

6.35. (a) In Example 6.7 (Section 6.3) it was calculated that with the air track turned off, the glider travels 8.6 cm before it stops instantaneously. How large would the coefficient of static friction μ_s have to be to keep the glider from springing back to the left? (b) If the coefficient of static friction between the glider and the track is $\mu_s = 0.60$, what is the maximum initial speed v_1 that the glider can be given and still remain at rest after it stops instantaneously? With the air track turned off, the coefficient of kinetic friction is $\mu_k = 0.47$.

6.36. A 4.00-kg block of ice is placed against a horizontal spring that has force constant $k = 200 \text{ N/m}$ and is compressed 0.025 m. The spring is released and accelerates the block along a horizontal surface. You can ignore friction and the mass of the spring. (a) Calculate the work done on the block by the spring during the motion of the block from its initial position to where the spring has returned to its uncompressed length. (b) What is the speed of the block after it leaves the spring?

6.37. A force \vec{F} is applied to a 2.0-kg radio-controlled model car parallel to the x -axis as it moves along a straight track. The x -component of the force varies with the x -coordinate of the car as shown in Fig. 6.32. Calculate the work done by the force \vec{F} when the car moves from (a) $x = 0$ to $x = 3.0$ m; (b) $x = 3.0$ m to $x = 4.0$ m; (c) $x = 4.0$ m to $x = 7.0$ m; (d) $x = 0$ to $x = 7.0$ m; (e) $x = 7.0$ m to $x = 2.0$ m.

Figure 6.32 Exercises 6.37 and 6.38.



6.38. Suppose the 2.0-kg model car in Exercise 6.37 is initially at rest at $x = 0$ and \vec{F} is the net force acting on it. Use the work–energy theorem to find the speed of the car at (a) $x = 3.0$ m; (b) $x = 4.0$ m; (c) $x = 7.0$ m.

6.39. At a waterpark, sleds with riders are sent along a slippery, horizontal surface by the release of a large compressed spring. The spring with force constant $k = 40.0 \text{ N/cm}$ and negligible mass rests on the frictionless horizontal surface. One end is in contact with a stationary wall. A sled and rider with total mass 70.0 kg are pushed against the other end, compressing the spring 0.375 m. The sled is then released with zero initial velocity. What is the sled's speed when the spring (a) returns to its uncompressed length and (b) is still compressed 0.200 m?

6.40. Half of a Spring. (a) Suppose you cut a massless ideal spring in half. If the full spring had a force constant k , what is the force constant of each half, in terms of k ? (Hint: Think of the original spring as two equal halves, each producing the same force as the entire spring. Do you see why the forces must be equal?) (b) If you cut the spring into three equal segments instead, what is the force constant of each one, in terms of k ?

6.41. A small glider is placed against a compressed spring at the bottom of an air track that slopes upward at an angle of 40.0° above the horizontal. The glider has mass 0.0900 kg. The spring has $k = 640 \text{ N/m}$ and negligible mass. When the spring is released, the glider travels a maximum distance of 1.80 m along the air track before sliding back down. Before reaching this maxi-

mum distance, the glider loses contact with the spring. (a) What distance was the spring originally compressed? (b) When the glider has traveled along the air track 0.80 m from its initial position against the compressed spring, is it still in contact with the spring? What is the kinetic energy of the glider at this point?

6.42. An ingenious bricklayer builds a device for shooting bricks up to the top of the wall where he is working. He places a brick on a vertical compressed spring with force constant $k = 450 \text{ N/m}$ and negligible mass. When the spring is released, the brick is propelled upward. If the brick has mass 1.80 kg and is to reach a maximum height of 3.6 m above its initial position on the compressed spring, what distance must the bricklayer compress the spring initially? (The brick loses contact with the spring when the spring returns to its uncompressed length. Why?)

Section 6.4 Power

6.43. How many joules of energy does a 100-watt light bulb use per hour? How fast would a 70-kg person have to run to have that amount of kinetic energy?

6.44. The total consumption of electrical energy in the United States is about $1.0 \times 10^{19} \text{ J}$ per year. (a) What is the average rate of electrical energy consumption in watts? (b) The population of the United States is about 300 million people. What is the average rate of electrical energy consumption per person? (c) The sun transfers energy to the earth by radiation at a rate of approximately 1.0 kW per square meter of surface. If this energy could be collected and converted to electrical energy with 40% efficiency, how great an area (in square kilometers) would be required to collect the electrical energy used in the United States?

6.45. Magnetar. On December 27, 2004, astronomers observed the greatest flash of light ever recorded from outside the solar system. It came from the highly magnetic neutron star SGR 1806-20 (a magnetar). During 0.20 s, this star released as much energy as our sun does in 250,000 years. If P is the average power output of our sun, what was the average power output (in terms of P) of this magnetar?

6.46. A 20.0-kg rock is sliding on a rough, horizontal surface at 8.00 m/s and eventually stops due to friction. The coefficient of kinetic friction between the rock and the surface is 0.200. What average power is produced by friction as the rock stops?

6.47. A tandem (two-person) bicycle team must overcome a force of 165 N to maintain a speed of 9.00 m/s. Find the power required per rider, assuming that each contributes equally. Express your answer in watts and in horsepower.

6.48. When its 75-kW (100-hp) engine is generating full power, a small single-engine airplane with mass 700 kg gains altitude at a rate of 2.5 m/s (150 m/min, or 500 ft/min). What fraction of the engine power is being used to make the airplane climb? (The remainder is used to overcome the effects of air resistance and of inefficiencies in the propeller and engine.)

6.49. Working Like a Horse. Your job is to lift 30-kg crates a vertical distance of 0.90 m from the ground onto the bed of a truck. (a) How many crates would you have to load onto the truck in 1 minute for the average power output you use to lift the crates to equal 0.50 hp? (b) How many crates for an average power output of 100 W?

6.50. An elevator has mass 600 kg, not including passengers. The elevator is designed to ascend, at constant speed, a vertical distance of 20.0 m (five floors) in 16.0 s, and it is driven by a motor that can provide up to 40 hp to the elevator. What is the maximum number of passengers that can ride in the elevator? Assume that an average passenger has mass 65.0 kg.

6.51. Automotive Power. It is not unusual for a 1000-kg car to get 30 mi/gal when traveling at 60 mi/h on a level road. If this car makes a 200-km trip, (a) how many joules of energy does it consume, and (b) what is the average rate of energy consumption during the trip? Note that 1.0 gal of gasoline yields $1.3 \times 10^9 \text{ J}$ (although this can vary). Consult Appendix E.

6.52. The aircraft carrier *John F. Kennedy* has mass $7.4 \times 10^7 \text{ kg}$. When its engines are developing their full power of 280,000 hp, the *John F. Kennedy* travels at its top speed of 35 knots (65 km/h). If 70% of the power output of the engines is applied to pushing the ship through the water, what is the magnitude of the force of water resistance that opposes the carrier's motion at this speed?

6.53. A ski tow operates on a 15.0° slope of length 300 m. The rope moves at 12.0 km/h and provides power for 50 riders at one time, with an average mass per rider of 70.0 kg. Estimate the power required to operate the tow.

6.54. A typical flying insect applies an average force equal to twice its weight during each downward stroke while hovering. Take the mass of the insect to be 10 g, and assume the wings move an average downward distance of 1.0 cm during each stroke. Assuming 100 downward strokes per second, estimate the average power output of the insect.

Problems

6.55. Rotating Bar. A thin, uniform 12.0-kg bar that is 2.00 m long rotates uniformly about a pivot at one end, making 5.00 complete revolutions every 3.00 seconds. What is the kinetic energy of this bar? (Hint: Different points in the bar have different speeds. Break the bar up into infinitesimal segments of mass dm and integrate to add up the kinetic energy of all these segments.)

6.56. A Near-Earth Asteroid. On April 13, 2029 (Friday the 13th!), the asteroid 99942 Apophis will pass within 18,600 mi of the earth—about 1/13 the distance to the moon! It has a density of 2600 kg/m^3 , can be modeled as a sphere 320 m in diameter, and will be traveling at 12.6 km/s. (a) If, due to a small disturbance in its orbit, the asteroid were to hit the earth, how much kinetic energy would it deliver? (b) The largest nuclear bomb ever tested by the United States was the “Castle/Bravo” bomb, having a yield of 15 megatons of TNT. (A megaton of TNT releases $4.184 \times 10^{15} \text{ J}$ of energy.) How many Castle/Bravo bombs would be equivalent to the energy of Apophis?

6.57. A luggage handler pulls a 20.0-kg suitcase up a ramp inclined at 25.0° above the horizontal by a force \vec{F} of magnitude 140 N that acts parallel to the ramp. The coefficient of kinetic friction between the ramp and the incline is $\mu_k = 0.300$. If the suitcase travels 3.80 m along the ramp, calculate (a) the work done on the suitcase by the force \vec{F} ; (b) the work done on the suitcase by the gravitational force; (c) the work done on the suitcase by the normal force; (d) the work done on the suitcase by the friction force; (e) the total work done on the suitcase. (f) If the speed of the suitcase is zero at the bottom of the ramp, what is its speed after it has traveled 3.80 m along the ramp?

6.58. Chin-Ups. While doing a chin-up, a man lifts his body 0.40 m. (a) How much work must the man do per kilogram of body mass? (b) The muscles involved in doing a chin-up can generate about 70 J of work per kilogram of muscle mass. If the man can just barely do a 0.40-m chin-up, what percentage of his body's mass do these muscles constitute? (For comparison, the total percentage of muscle in a typical 70-kg man with 14% body fat is about 43%.) (c) Repeat part (b) for the man's young son, who has arms half as long as his father's but whose muscles can

also generate 70 J of work per kilogram of muscle mass. (d) Adults and children have about the same percentage of muscle in their bodies. Explain why children can commonly do chin-ups more easily than their fathers.

6.59. Simple Machines. Ramps for the disabled are used because a large weight w can be raised by a relatively small force equal to $w \sin \alpha$ plus the small friction force. Such inclined planes are an example of a class of devices called *simple machines*. An input force F_{in} is applied to the system and results in an output force F_{out} applied to the object that is moved. For a simple machine the ratio of these forces, F_{out}/F_{in} , is called the actual mechanical advantage (AMA). The inverse ratio of the distances that the points of application of these forces move through during the motion of the object, s_{in}/s_{out} , is called the ideal mechanical advantage (IMA). (a) Find the IMA for an inclined plane. (b) What can we say about the relationship between the work supplied to the machine, W_{in} , and the work output of the machine, W_{out} , if $AMA = IMA$? (c) Sketch a single pulley arranged to give $IMA = 2$. (d) We define the efficiency e of a simple machine to equal the ratio of the output work to the input work, $e = W_{out}/W_{in}$. Show that $e = AMA/IMA$.

6.60. Consider the blocks in Exercise 6.7 as they move 75.0 cm. Find the total work done on each one (a) if there is no friction between the table and the 20.0-N block, and (b) if $\mu_s = 0.500$ and $\mu_k = 0.325$ between the table and the 20.0-N block.

6.61. The space shuttle *Endeavour*, with mass 86,400 kg, is in a circular orbit of radius 6.66×10^6 m around the earth. It takes 90.1 min for the shuttle to complete each orbit. On a repair mission, the shuttle is cautiously moving 1.00 m closer to a disabled satellite every 3.00 s. Calculate the shuttle's kinetic energy (a) relative to the earth and (b) relative to the satellite.

6.62. A 5.00-kg package slides 1.50 m down a long ramp that is inclined at 12.0° below the horizontal. The coefficient of kinetic friction between the package and the ramp is $\mu_k = 0.310$. Calculate (a) the work done on the package by friction; (b) the work done on the package by gravity; (c) the work done on the package by the normal force; (d) the total work done on the package. (e) If the package has a speed of 2.20 m/s at the top of the ramp, what is its speed after sliding 1.50 m down the ramp?

6.63. Springs in Parallel. Two springs are in parallel if they are parallel to each other and are connected at their ends (Figure 6.33). We can think of this combination as being equivalent to a single spring. The force constant of the equivalent single spring is called the *effective* force constant, k_{eff} , of the combination. (a) Show that the effective force constant of this combination is $k_{eff} = k_1 + k_2$. (b) Generalize this result for N springs in parallel.

6.64. Springs in Series. Two massless springs are connected in series when they are attached one after the other, head to tail. (a) Show that the effective force constant (see Problem 6.63) of a series combination is given by $\frac{1}{k_{eff}} = \frac{1}{k_1} + \frac{1}{k_2}$. (Hint: For a given force, the total distance stretched by the equivalent single spring is the sum of the distances stretched by the springs in combination. Also, each spring must exert the same force. Do you see why?) (b) Generalize this result for N springs in series.

6.65. An object is attracted toward the origin with a force given by $F_x = -k|x|^2$. (Gravitational and electrical forces have this distance

dependence.) (a) Calculate the work done by the force F_x when the object moves in the x -direction from x_1 to x_2 . If $x_2 > x_1$, is the work done by F_x positive or negative? (b) The only other force acting on the object is a force that you exert with your hand to move the object slowly from x_1 to x_2 . How much work do you do? If $x_2 > x_1$, is the work you do positive or negative? (c) Explain the similarities and differences between your answers to parts (a) and (b).

6.66. The gravitational pull of the earth on an object is inversely proportional to the square of the distance of the object from the center of the earth. At the earth's surface this force is equal to the object's normal weight mg , where $g = 9.8 \text{ m/s}^2$, and at large distances, the force is zero. If a 20,000-kg asteroid falls to earth from a very great distance away, what will be its minimum speed as it strikes the earth's surface, and how much kinetic energy will it impart to our planet? You can ignore the effects of the earth's atmosphere.

6.67. Varying Coefficient of Friction. A box is sliding with a speed of 4.50 m/s on a horizontal surface when, at point P , it encounters a rough section. On the rough section, the coefficient of friction is not constant, but starts at 0.100 at P and increases linearly with distance past P , reaching a value of 0.600 at 12.5 m past point P . (a) Use the work–energy theorem to find how far this box slides before stopping. (b) What is the coefficient of friction at the stopping point? (c) How far would the box have slid if the friction coefficient didn't increase but instead had the constant value of 0.100?

6.68. Consider a spring that does not obey Hooke's law very faithfully. One end of the spring is fixed. To keep the spring stretched or compressed an amount x , a force along the x -axis with x -component $F_x = kx - bx^2 + cx^3$ must be applied to the free end. Here $k = 100 \text{ N/m}$, $b = 700 \text{ N/m}^2$, and $c = 12,000 \text{ N/m}^3$. Note that $x > 0$ when the spring is stretched and $x < 0$ when it is compressed. (a) How much work must be done to stretch this spring by 0.050 m from its unstretched length? (b) How much work must be done to compress this spring by 0.050 m from its unstretched length? (c) Is it easier to stretch or compress this spring? Explain why in terms of the dependence of F_x on x . (Many real springs behave qualitatively in the same way.)

6.69. A small block with a mass of 0.120 kg is attached to a cord passing through a hole in a frictionless, horizontal surface (Fig. 6.34). The block is originally revolving at a distance of 0.40 m from the hole with a speed of 0.70 m/s. The cord is then pulled from below, shortening the radius of the circle in which the block revolves to 0.10 m. At this new distance, the speed of the block is observed to be 2.80 m/s. (a) What is the tension in the cord in the original situation when the block has speed $v = 0.70 \text{ m/s}$? (b) What is the tension in the cord in the final situation when the block has speed $v = 2.80 \text{ m/s}$? (c) How much work was done by the person who pulled on the cord?

6.70. Proton Bombardment. A proton with mass $1.67 \times 10^{-27} \text{ kg}$ is propelled at an initial speed of $3.00 \times 10^5 \text{ m/s}$ directly toward a uranium nucleus 5.00 m away. The proton is repelled by the uranium nucleus with a force of magnitude $F = \alpha/x^2$, where x is the separation between the two objects and $\alpha = 2.12 \times 10^{-26} \text{ N} \cdot \text{m}^2$. Assume that the uranium nucleus remains at rest.

(a) What is the speed of the proton when it is $8.00 \times 10^{-10} \text{ m}$ from the uranium nucleus? (b) As the proton approaches the uranium nucleus, the repulsive force slows down the proton until it comes momentarily to rest, after which the proton moves away from the uranium nucleus. How close to the uranium nucleus does the proton get? (c) What is the speed of the proton when it is again 5.00 m away from the uranium nucleus?

6.71. A block of ice with mass 6.00 kg is initially at rest on a frictionless, horizontal surface. A worker then applies a horizontal force \vec{F} to it. As a result, the block moves along the x -axis such that its position as a function of time is given by $x(t) = \alpha t^2 + \beta t^3$, where $\alpha = 0.200 \text{ m/s}^2$ and $\beta = 0.0200 \text{ m/s}^3$. (a) Calculate the velocity of the object when $t = 4.00 \text{ s}$. (b) Calculate the magnitude of \vec{F} when $t = 4.00 \text{ s}$. (c) Calculate the work done by the force \vec{F} during the first 4.00 s of the motion.

6.72. The Genesis Crash. When the 210-kg Genesis Mission capsule crashed (see Exercise 5.17 in Chapter 5) with a speed of 311 km/h, it buried itself 81.0 cm deep in the desert floor. Assuming constant acceleration during the crash, at what average rate did the capsule do work on the desert?

6.73. You and your bicycle have combined mass 80.0 kg. When you reach the base of a bridge, you are traveling along the road at 5.00 m/s (Fig. 6.35). At the top of the bridge, you have climbed a vertical distance of 5.20 m and have slowed to 1.50 m/s. You can ignore work done by friction and any inefficiency in the bike or your legs. (a) What is the total work done on you and your bicycle when you go from the base to the top of the bridge? (b) How much work have you done with the force you apply to the pedals?

Figure 6.35 Problem 6.73.



6.74. A force in the $+x$ -direction has magnitude $F = b/x^n$, where b and n are constants. (a) For $n > 1$, calculate the work done on a particle by this force when the particle moves along the x -axis from $x = x_0$ to infinity. (b) Show that for $0 < n < 1$, even though F becomes zero as x becomes very large, an infinite amount of work is done by F when the particle moves from $x = x_0$ to infinity.

6.75. You are asked to design spring bumpers for the walls of a parking garage. A freely rolling 1200-kg car moving at 0.65 m/s is to compress the spring no more than 0.070 m before stopping. What should be the force constant of the spring? Assume that the spring has negligible mass.

6.76. The spring of a spring gun has force constant $k = 400 \text{ N/m}$ and negligible mass. The spring is compressed 6.00 cm, and a ball with mass 0.0300 kg is placed in the horizontal barrel against the compressed spring. The spring is then released, and the ball is pro-

pelled out the barrel of the gun. The barrel is 6.00 cm long, so the ball leaves the barrel at the same point that it loses contact with the spring. The gun is held so the barrel is horizontal. (a) Calculate the speed with which the ball leaves the barrel if you can ignore friction. (b) Calculate the speed of the ball as it leaves the barrel if a constant resisting force of 6.00 N acts on the ball as it moves along the barrel. (c) For the situation in part (b), at what position along the barrel does the ball have the greatest speed, and what is that speed? (In this case, the maximum speed does not occur at the end of the barrel.)

6.77. A 2.50-kg textbook is forced against a horizontal spring of negligible mass and force constant 250 N/m, compressing the spring a distance of 0.250 m. When released, the textbook slides on a horizontal tabletop with coefficient of kinetic friction $\mu_k = 0.30$. Use the work–energy theorem to find how far the textbook moves from its initial position before coming to rest.

6.78. Pushing a Cat. Your cat “Ms.” (mass 7.00 kg) is trying to make it to the top of a frictionless ramp 2.00 m long and inclined upward at 30.0° above the horizontal. Since the poor cat can't get any traction on the ramp, you push her up the entire length of the ramp by exerting a constant 100-N force parallel to the ramp. If Ms. takes a running start so that she is moving at 2.40 m/s at the bottom of the ramp, what is her speed when she reaches the top of the incline? Use the work–energy theorem.

6.79. Crash Barrier. A student proposes a design for an automobile crash barrier in which a 1700-kg sport utility vehicle moving at 20.0 m/s crashes into a spring of negligible mass that slows it to a stop. So that the passengers are not injured, the acceleration of the vehicle as it slows can be no greater than $5.00g$. (a) Find the required spring constant k , and find the distance the spring will compress in slowing the vehicle to a stop. In your calculation, disregard any deformation or crumpling of the vehicle and the friction between the vehicle and the ground. (b) What disadvantages are there to this design?

6.80. A physics professor is pushed up a ramp inclined upward at 30.0° above the horizontal as he sits in his desk chair that slides on frictionless rollers. The combined mass of the professor and chair is 85.0 kg. He is pushed 2.50 m along the incline by a group of students who together exert a constant horizontal force of 600 N. The professor's speed at the bottom of the ramp is 2.00 m/s. Use the work–energy theorem to find his speed at the top of the ramp.

6.81. A 5.00-kg block is moving at $v_0 = 6.00 \text{ m/s}$ along a frictionless, horizontal surface toward a spring with force constant $k = 500 \text{ N/m}$ that is attached to a wall (Fig. 6.36). The spring has negligible mass.

(a) Find the maximum distance the spring will be compressed. (b) If the spring is to compress by no more than 0.150 m, what should be the maximum value of v_0 ?

6.82. Consider the system shown in Fig. 6.37. The rope and pulley have negligible mass, and the pulley is frictionless. The coefficient of kinetic friction between the 8.00-kg block and the tabletop is $\mu_k = 0.250$. The blocks are released from rest. Use energy methods to calculate the speed of the 6.00-kg block after it has descended 1.50 m.

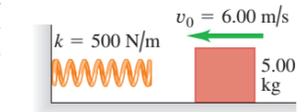
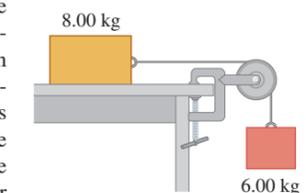


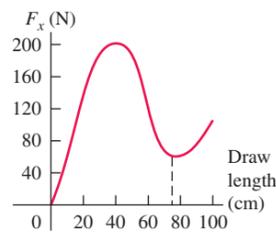
Figure 6.37 Problems 6.82 and 6.83.



6.83. Consider the system shown in Fig. 6.37. The rope and pulley have negligible mass, and the pulley is frictionless. Initially the 6.00-kg block is moving downward and the 8.00-kg block is moving to the right, both with a speed of 0.900 m/s. The blocks come to rest after moving 2.00 m. Use the work–energy theorem to calculate the coefficient of kinetic friction between the 8.00-kg block and the tabletop.

6.84. Bow and Arrow. Figure 6.38 shows how the force exerted by the string of a compound bow on an arrow varies as a function of how far back the arrow is pulled (the draw length). Assume that the same force is exerted on the arrow as it moves forward after being released. Full draw for this bow is at a draw length of 75.0 cm. If the bow shoots a 0.0250-kg arrow from full draw, what is the speed of the arrow as it leaves the bow?

Figure 6.38 Problem 6.84.



6.85. On an essentially frictionless, horizontal ice rink, a skater moving at 3.0 m/s encounters a rough patch that reduces her speed by 45% due to a friction force that is 25% of her weight. Use the work–energy theorem to find the length of this rough patch.

6.86. Rescue. Your friend (mass 65.0 kg) is standing on the ice in the middle of a frozen pond. There is very little friction between her feet and the ice, so she is unable to walk. Fortunately, a light rope is tied around her waist and you stand on the bank holding the other end. You pull on the rope for 3.00 s and accelerate your friend from rest to a speed of 6.00 m/s while you remain at rest. What is the average power supplied by the force you applied?

6.87. A pump is required to lift 800 kg of water (about 210 gallons) per minute from a well 14.0 m deep and eject it with a speed of 18.0 m/s. (a) How much work is done per minute in lifting the water? (b) How much work is done in giving the water the kinetic energy it has when ejected? (c) What must be the power output of the pump?

6.88. Find the power output of the worker in Problem 6.71 as a function of time. What is the numerical value of the power (in watts) at $t = 4.00$ s?

6.89. A physics student spends part of her day walking between classes or for recreation, during which time she expends energy at an average rate of 280 W. The remainder of the day she is sitting in class, studying, or resting; during these activities, she expends energy at an average rate of 100 W. If she expends a total of 1.1×10^7 J of energy in a 24-hour day, how much of the day did she spend walking?

6.90. All birds, independent of their size, must maintain a power output of 10–25 watts per kilogram of body mass in order to fly by flapping their wings. (a) The Andean giant hummingbird (*Patagona gigas*) has mass 70 g and flaps its wings 10 times per second while hovering. Estimate the amount of work done by such a hummingbird in each wingbeat. (b) A 70-kg athlete can maintain a power output of 1.4 kW for no more than a few seconds; the steady power output of a typical athlete is only 500 W or so. Is it possible for a human-powered aircraft to fly for extended periods by flapping its wings? Explain.

6.91. The Grand Coulee Dam is 1270 m long and 170 m high. The electrical power output from generators at its base is approximately 2000 MW. How many cubic meters of water must flow

from the top of the dam per second to produce this amount of power if 92% of the work done on the water by gravity is converted to electrical energy? (Each cubic meter of water has a mass of 1000 kg.)

6.92. The engine of a car with mass m supplies a constant power P to the wheels to accelerate the car. You can ignore rolling friction and air resistance. The car is initially at rest. (a) Show that the speed of the car is given as a function of time by $v = (2Pt/m)^{1/2}$. (b) Show that the acceleration of the car is not constant but is given as a function of time by $a = (P/2mt)^{1/2}$. (c) Show that the displacement as a function of time is given by $x - x_0 = (8P/9m)^{1/2} t^{3/2}$.

6.93. Power of the Human Heart. The human heart is a powerful and extremely reliable pump. Each day it takes in and discharges about 7500 L of blood. Assume that the work done by the heart is equal to the work required to lift this amount of blood a height equal to that of the average American woman (1.63 m). The density (mass per unit volume) of blood is 1.05×10^3 kg/m³. (a) How much work does the heart do in a day? (b) What is the heart's power output in watts?

6.94. Six diesel units in series can provide 13.4 MW of power to the lead car of a freight train. The diesel units have total mass 1.10×10^6 kg. The average car in the train has mass 8.2×10^4 kg and requires a horizontal pull of 2.8 kN to move at a constant 27 m/s on level tracks. (a) How many cars can be in the train under these conditions? (b) This would leave no power for accelerating or climbing hills. Show that the extra force needed to accelerate the train is about the same for a 0.10-m/s^2 acceleration or a 1.0% slope (slope angle $\alpha = \arctan 0.010$). (c) With the 1.0% slope, show that an extra 2.9 MW of power is needed to maintain the 27-m/s speed of the diesel units. (d) With 2.9 MW less power available, how many cars can the six diesel units pull up a 1.0% slope at a constant 27-m/s?

6.95. It takes a force of 53 kN on the lead car of a 16-car passenger train with mass 9.1×10^5 kg to pull it at a constant 45 m/s (101 mi/h) on level tracks. (a) What power must the locomotive provide to the lead car? (b) How much more power to the lead car than calculated in part (a) would be needed to give the train an acceleration of 1.5 m/s², at the instant that the train has a speed of 45 m/s on level tracks? (c) How much more power to the lead car than that calculated in part (a) would be needed to move the train up a 1.5% grade (slope angle $\alpha = \arctan 0.015$) at a constant 45 m/s?

6.96. An object has several forces acting on it. One of these forces is $\vec{F} = \alpha xy\hat{i}$, a force in the x -direction whose magnitude depends on the position of the object, with $\alpha = 2.50$ N/m². Calculate the work done on the object by this force for the following displacements of the object: (a) The object starts at the point $x = 0$, $y = 3.00$ m and moves parallel to the x -axis to the point $x = 2.00$ m, $y = 3.00$ m. (b) The object starts at the point $x = 2.00$ m, $y = 0$ and moves in the y -direction to the point $x = 2.00$ m, $y = 3.00$ m. (c) The object starts at the origin and moves on the line $y = 1.5x$ to the point $x = 2.00$ m, $y = 3.00$ m.

6.97. Cycling. For a touring bicyclist the drag coefficient $C(f_{\text{air}} = \frac{1}{2}CA\rho v^2)$ is 1.00, the frontal area A is 0.463 m², and the coefficient of rolling friction is 0.0045. The rider has mass 50.0 kg, and her bike has mass 12.0 kg. (a) To maintain a speed of 12.0 m/s (about 27 mi/h) on a level road, what must the rider's power output to the rear wheel be? (b) For racing, the same rider uses a different bike with coefficient of rolling friction 0.0030 and mass 9.00 kg. She also crouches down, reducing her drag coeffi-

cient to 0.88 and reducing her frontal area to 0.366 m². What must her power output to the rear wheel be then to maintain a speed of 12.0 m/s? (c) For the situation in part (b), what power output is required to maintain a speed of 6.0 m/s? Note the great drop in power requirement when the speed is only halved. (For more on aerodynamic speed limitations for a wide variety of human-powered vehicles, see "The Aerodynamics of Human-Powered Land Vehicles," *Scientific American*, December 1983.)

6.98. Automotive Power I. A truck engine transmits 28.0 kW (37.5 hp) to the driving wheels when the truck is traveling at a constant velocity of magnitude 60.0 km/h (37.3 mi/h) on a level road. (a) What is the resisting force acting on the truck? (b) Assume that 65% of the resisting force is due to rolling friction and the remainder is due to air resistance. If the force of rolling friction is independent of speed, and the force of air resistance is proportional to the square of the speed, what power will drive the truck at 30.0 km/h? At 120.0 km/h? Give your answers in kilowatts and in horsepower.

6.99. Automotive Power II. (a) If 8.00 hp are required to drive a 1800-kg automobile at 60.0 km/h on a level road, what is the total retarding force due to friction, air resistance, and so on? (b) What power is necessary to drive the car at 60.0 km/h up a 10.0% grade (a hill rising 10.0 m vertically in 100.0 m horizontally)? (c) What power is necessary to drive the car at 60.0 km/h down a 1.00% grade? (d) Down what percent grade would the car coast at 60.0 km/h?

Challenge Problems

6.100. On a winter's day in Maine, a warehouse worker is shoving boxes up a rough plank inclined at an angle α above the horizontal. The plank is partially covered with ice, with more ice near the bottom of the plank than near the top, so that the coefficient of friction increases with the distance x along the plank: $\mu = Ax$, where A is a positive constant and the bottom of the plank is at $x = 0$. (For this plank the coefficients of kinetic and static friction are equal: $\mu_k = \mu_s = \mu$.) The worker shoves a box up the plank so that it leaves the bottom of the plank moving at speed v_0 . Show that when the box first comes to rest, it will remain at rest if

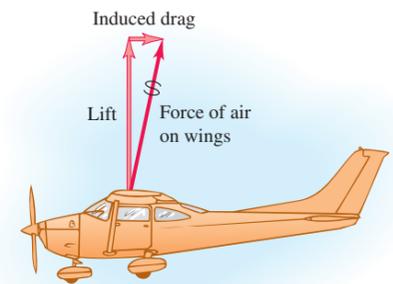
$$v_0^2 \geq \frac{3g \sin^2 \alpha}{A \cos \alpha}$$

6.101. A Spring with Mass. We usually ignore the kinetic energy of the moving coils of a spring, but let's try to get a reasonable approximation to this. Consider a spring of mass M , equilibrium length L_0 , and spring constant k . The work done to stretch or compress the spring by a distance L is $\frac{1}{2}kL^2$, where $X = L - L_0$. (a) Consider a spring, as described above, that has one end fixed and the other end moving with speed v . Assume that the speed of points along the length of the spring varies linearly with distance l from the fixed end. Assume also that the mass M of the spring is distributed uniformly along the length of the spring. Calculate the kinetic energy of the spring in terms of M and v . (Hint: Divide the spring into pieces of length dl ; find the speed of each piece in terms of l , v , and L ; find the mass of each piece in terms of dl , M , and L ; and integrate from 0 to L . The result is *not* $\frac{1}{2}Mv^2$, since not all of the spring moves with the same speed.) In a spring gun, a spring of mass 0.243 kg and force constant 3200 N/m is compressed 2.50 cm from its unstretched length.

When the trigger is pulled, the spring pushes horizontally on a 0.053-kg ball. The work done by friction is negligible. Calculate the ball's speed when the spring reaches its uncompressed length (b) ignoring the mass of the spring and (c) including, using the results of part (a), the mass of the spring. (d) In part (c), what is the final kinetic energy of the ball and of the spring?

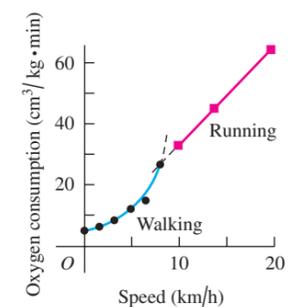
6.102. An airplane in flight is subject to an air resistance force proportional to the square of its speed v . But there is an additional resistive force because the airplane has wings. Air flowing over the wings is pushed down and slightly forward, so from Newton's third law the air exerts a force on the wings and airplane that is up and slightly backward (Fig. 6.39). The upward force is the lift force that keeps the airplane aloft, and the backward force is called *induced drag*. At flying speeds, induced drag is inversely proportional to v^2 , so that the total air resistance force can be expressed by $F_{\text{air}} = \alpha v^2 + \beta/v^2$, where α and β are positive constants that depend on the shape and size of the airplane and the density of the air. For a Cessna 150, a small single-engine airplane, $\alpha = 0.30$ N \cdot s²/m² and $\beta = 3.5 \times 10^5$ N \cdot m²/s². In steady flight, the engine must provide a forward force that exactly balances the air resistance force. (a) Calculate the speed (in km/h) at which this airplane will have the maximum *range* (that is, travel the greatest distance) for a given quantity of fuel. (b) Calculate the speed (in km/h) for which the airplane will have the maximum *endurance* (that is, remain in the air the longest time).

Figure 6.39 Challenge Problem 6.102.



6.103. Figure 6.40 shows the oxygen consumption rate of men walking and running at different speeds. The vertical axis shows the volume of oxygen (in cm³) that a man consumes per kilogram

Figure 6.40 Challenge Problem 6.103.



of body mass per minute. Note the transition from walking to running that occurs naturally at about 9 km/h. The metabolism of 1 cm^3 of oxygen releases about 20 J of energy. Using the data in the graph, calculate the energy required for a 70-kg man to travel 1 km on foot at (a) 5 km/h (walking); (b) 10 km/h (running); (c) 15 km/h (running). (d) Which speed is the most efficient—that is, requires the least energy to travel 1 km?

6.104. General Proof of the Work–Energy Theorem. Consider a particle that moves along a curved path in space from (x_1, y_1, z_1) to (x_2, y_2, z_2) . At the initial point, the particle has velocity $\vec{v} = v_{1x}\hat{i} + v_{1y}\hat{j} + v_{1z}\hat{k}$. The path that the particle follows may be divided into infinitesimal segments $d\vec{l} = dx\hat{i} + dy\hat{j} + dz\hat{k}$. As the

particle moves, it is acted on by a net force $\vec{F} = F_x\hat{i} + F_y\hat{j} + F_z\hat{k}$. The force components F_x , F_y , and F_z are in general functions of position. By the same sequence of steps used in Eqs. (6.11) through (6.13), prove the work–energy theorem for this general case. That is, prove that

$$W_{\text{tot}} = K_2 - K_1$$

where

$$W_{\text{tot}} = \int_{(x_1, y_1, z_1)}^{(x_2, y_2, z_2)} \vec{F} \cdot d\vec{l} = \int_{(x_1, y_1, z_1)}^{(x_2, y_2, z_2)} (F_x dx + F_y dy + F_z dz)$$