

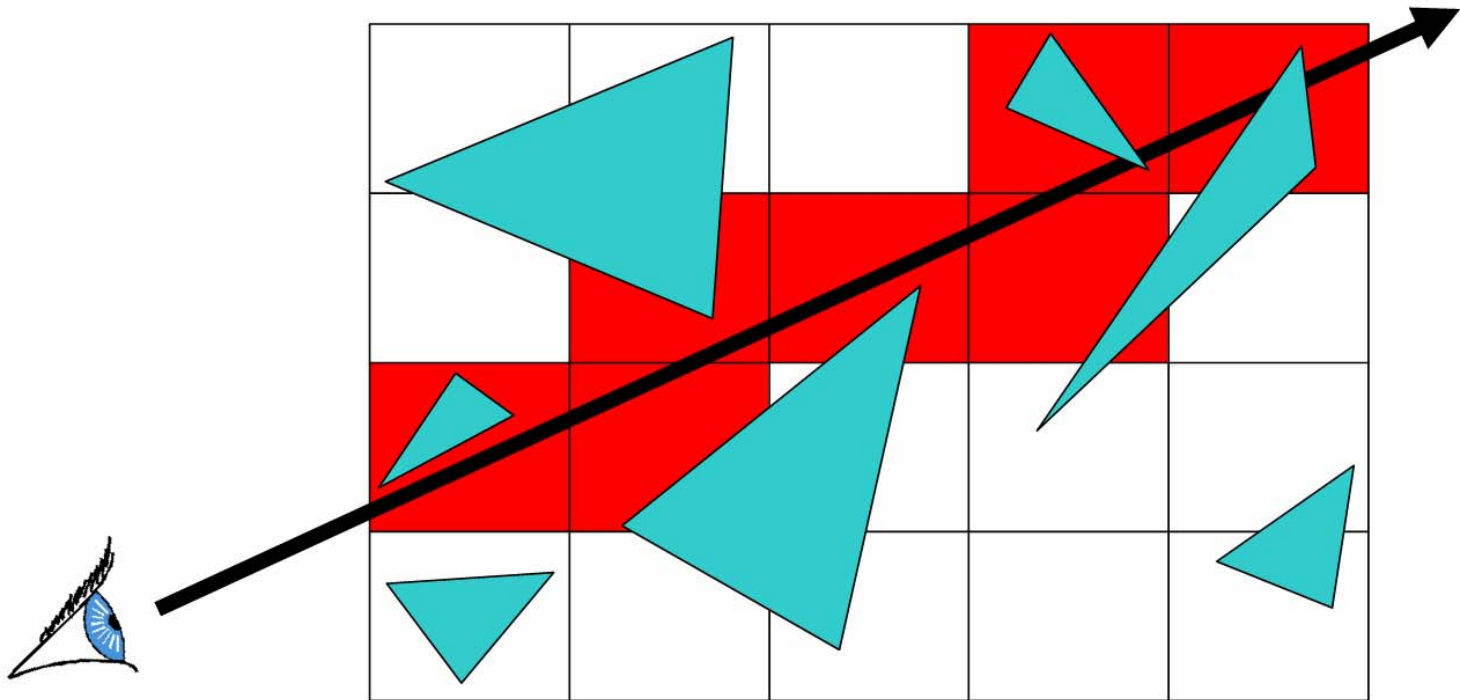
Curves & Surfaces

Schedule

- Sunday October 5th, * 3-5 PM *
Review Session for Quiz 1
- Extra Office Hours on Monday
- Tuesday October 7th:
Quiz 1: In class
1 hand-written 8.5x11 sheet of notes allowed
- Wednesday October 15th:
Assignment 4 (Grid Acceleration) due

Last Time:

- Acceleration Data Structures



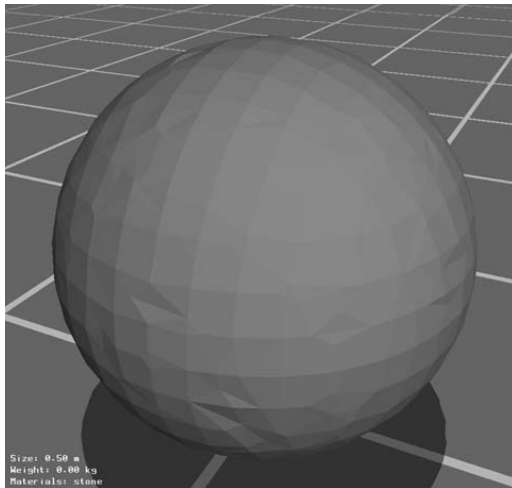
Questions?

Today

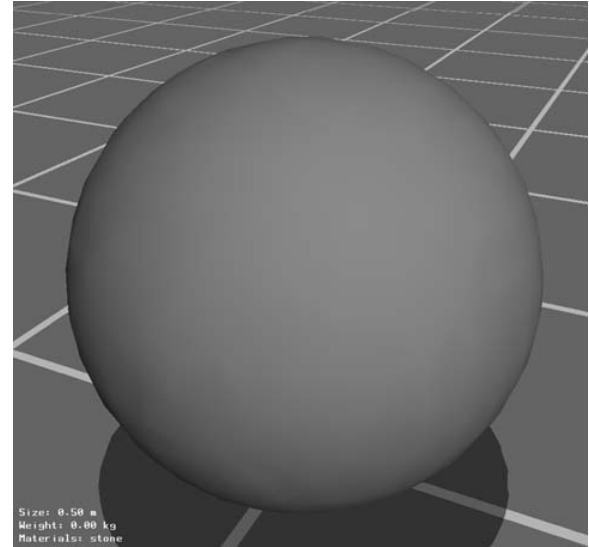
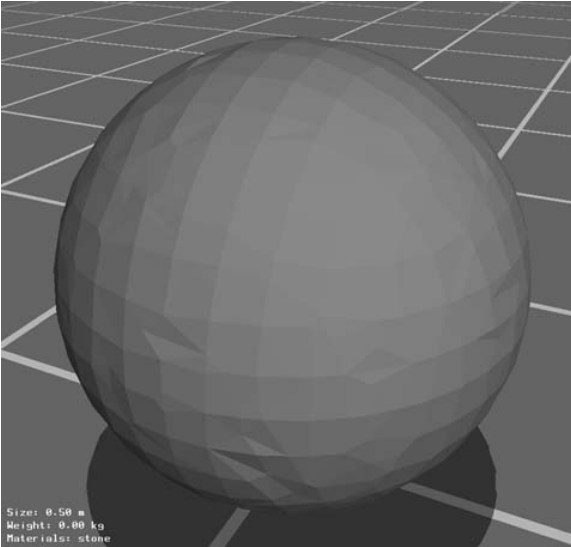
- Review
- Motivation
 - Limitations of Polygonal Models
 - Phong Normal Interpolation
 - Some Modeling Tools & Definitions
- Curves
- Surfaces / Patches
- Subdivision Surfaces
- Procedural Texturing

Limitations of Polygonal Meshes

- planar facets
- fixed resolution
- deformation is difficult
- no natural parameterization

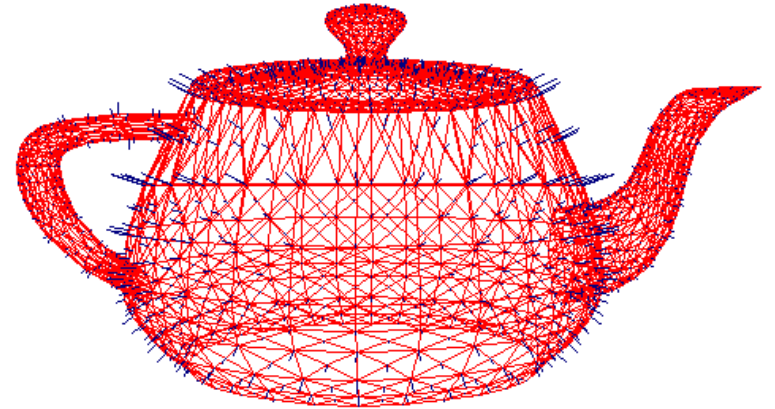


Can We Disguise the Facets?

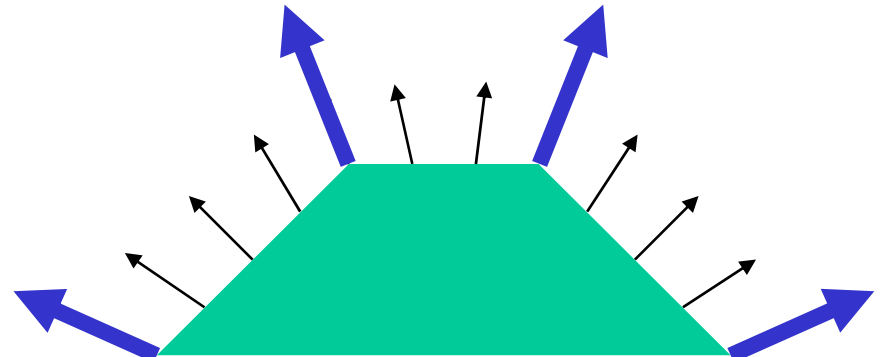
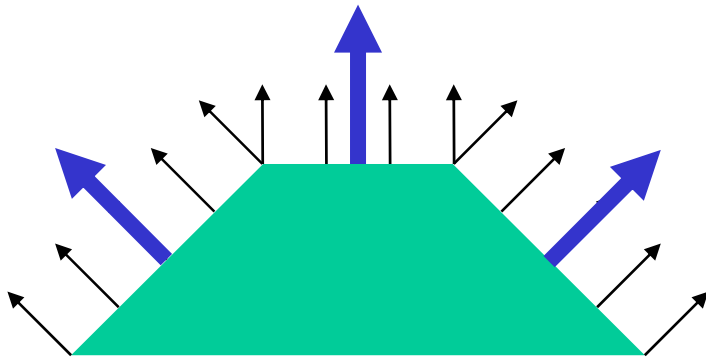


Phong Normal Interpolation

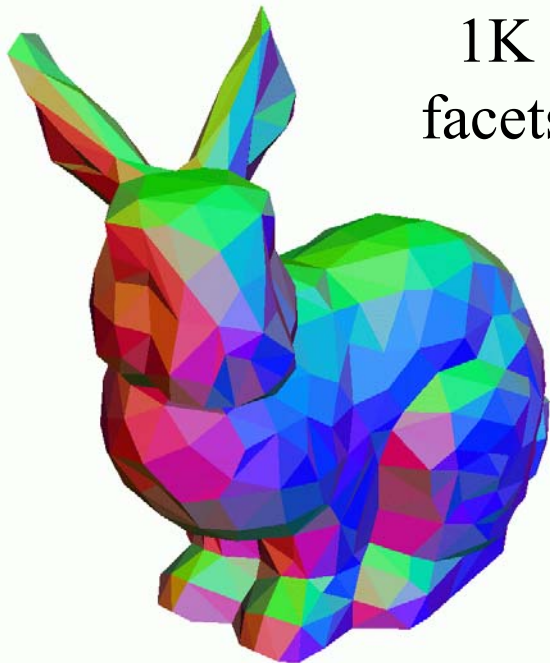
- Not Phong *Shading* from Assignment 3
- Instead of using the normal of the triangle, interpolate an averaged normal at each vertex across the face
- Must be renormalized



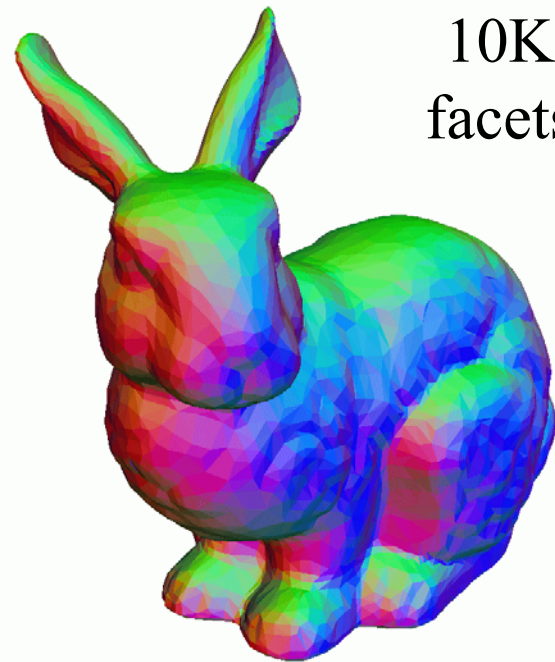
Courtesy of Leonard McMillan. Used with permission.



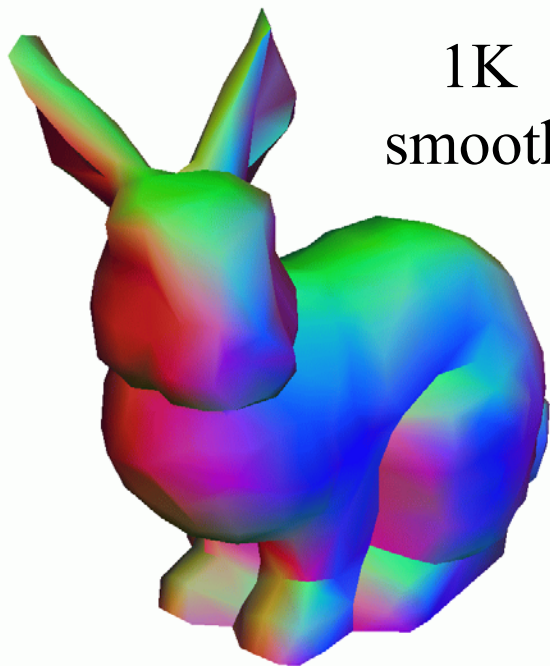
1K
facets



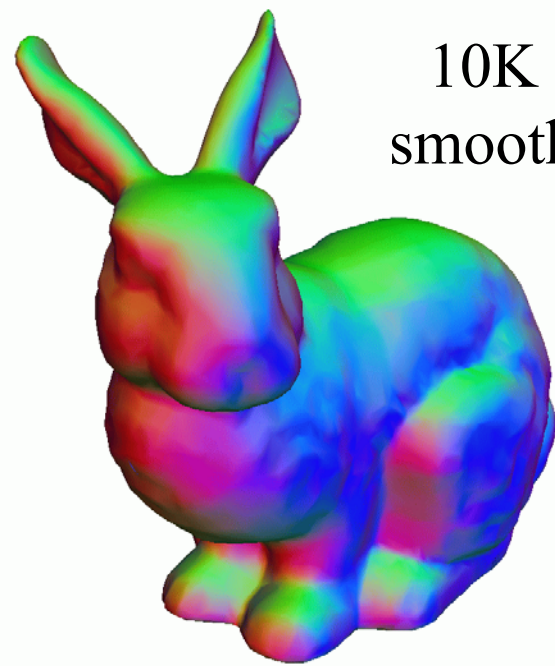
10K
facets



1K
smooth

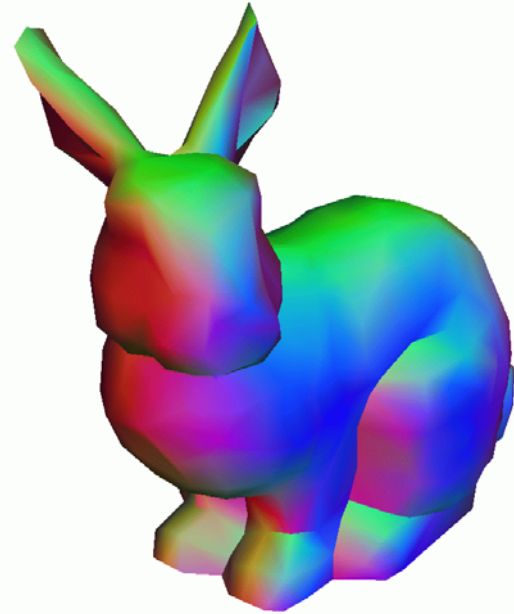


10K
smooth

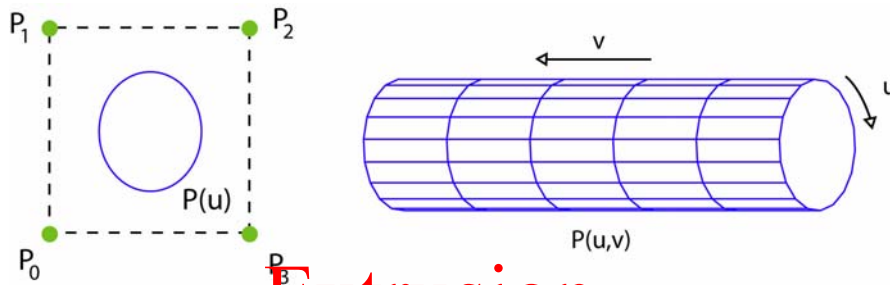


Better, but not always good enough

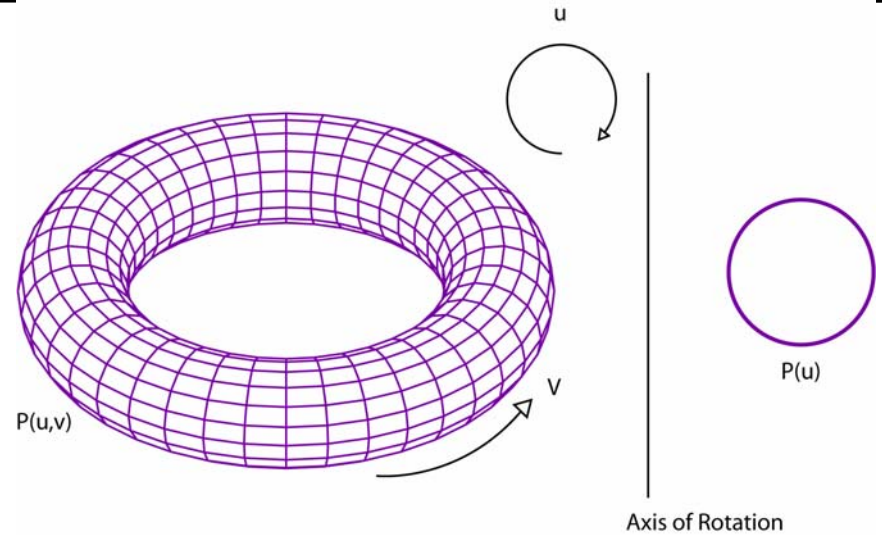
- Still low resolution
(missing fine details)
- Still have polygonal
silhouettes
- Intersection depth is
planar
- Collisions in a simulation
- Solid Texturing
- ...



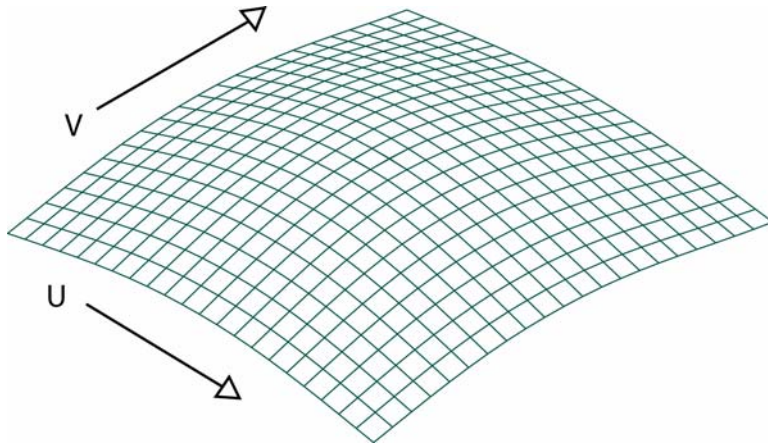
Some Non-Polygonal Modeling Tools



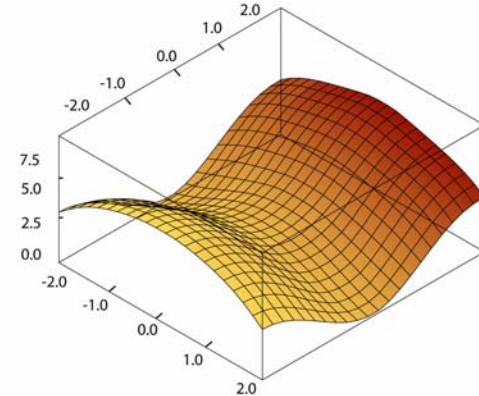
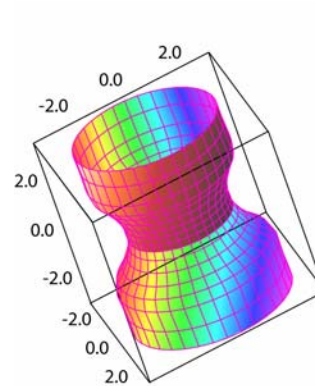
Extrusion



Surface of Revolution



Spline Surfaces/Patches



Quadrics and other
implicit polynomials

Continuity definitions:

- C^0 continuous
 - curve/surface has no breaks/gaps/holes
 - "watertight"
- C^1 continuous
 - curve/surface derivative is continuous
 - "looks smooth, no facets"
- C^2 continuous
 - curve/surface 2nd derivative is continuous
 - Actually important for shading



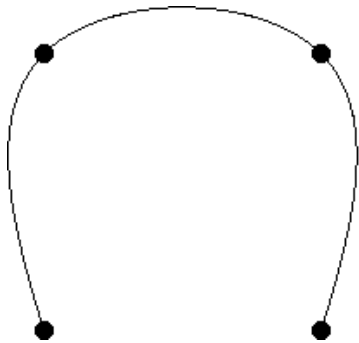
Questions?

Today

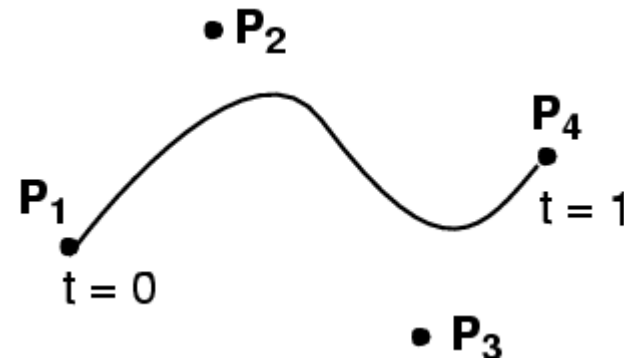
- Review
- Motivation
- Curves
 - What's a Spline?
 - Linear Interpolation
 - Interpolation Curves vs. Approximation Curves
 - Bézier
 - BSpline (NURBS)
- Surfaces / Patches
- Subdivision Surfaces
- Procedural Texturing

Definition: What's a Spline?

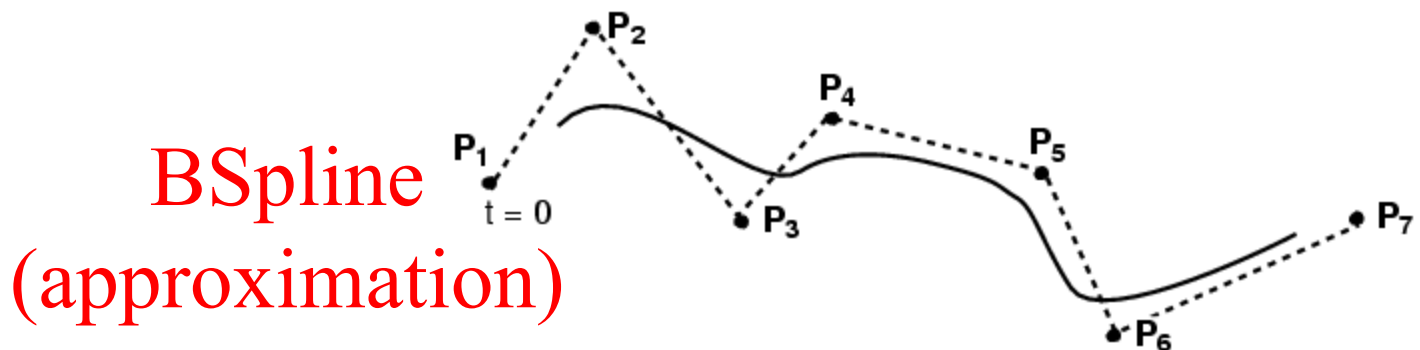
- Smooth curve defined by some control points
- Moving the control points changes the curve



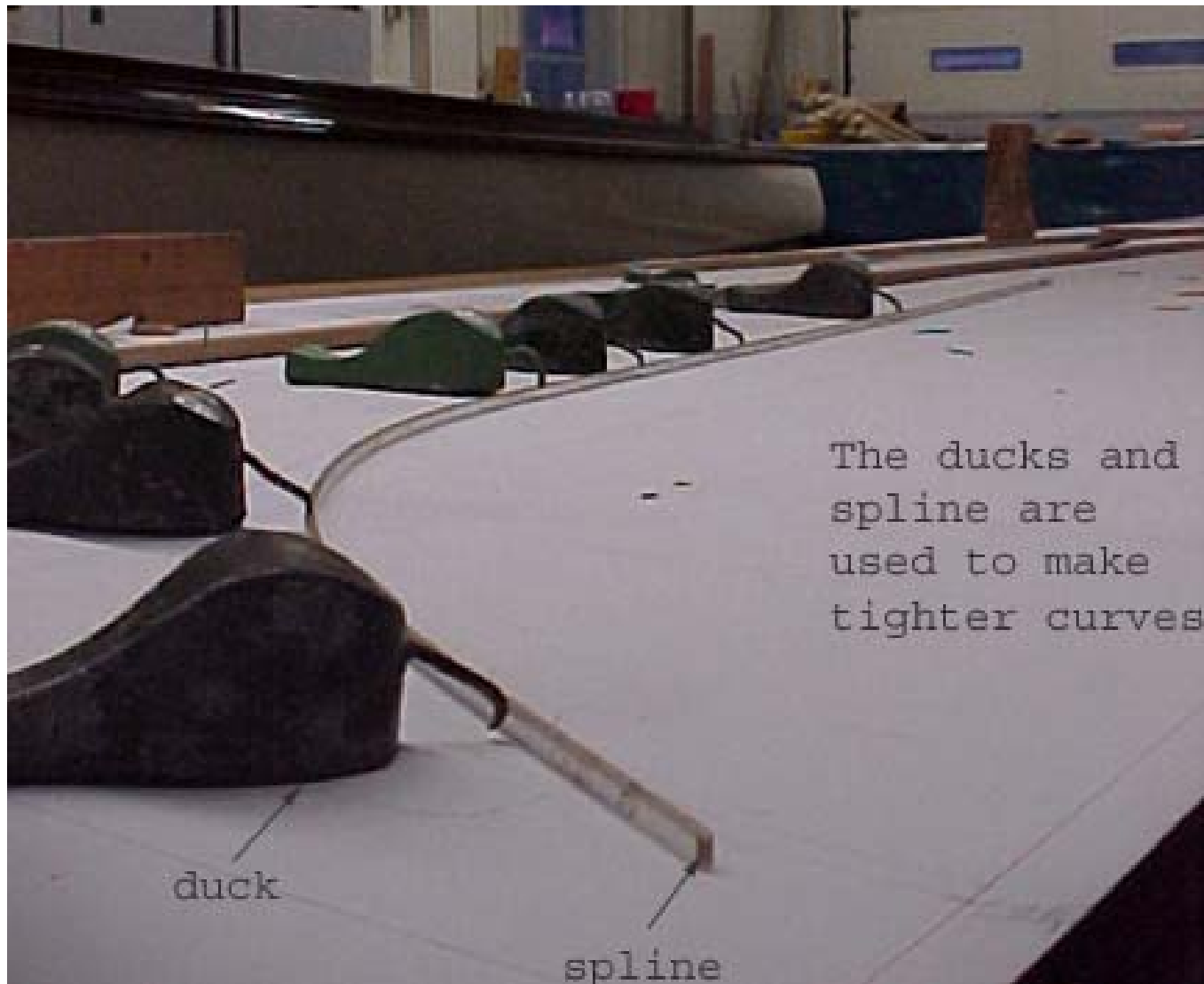
Interpolation



Bézier (approximation)

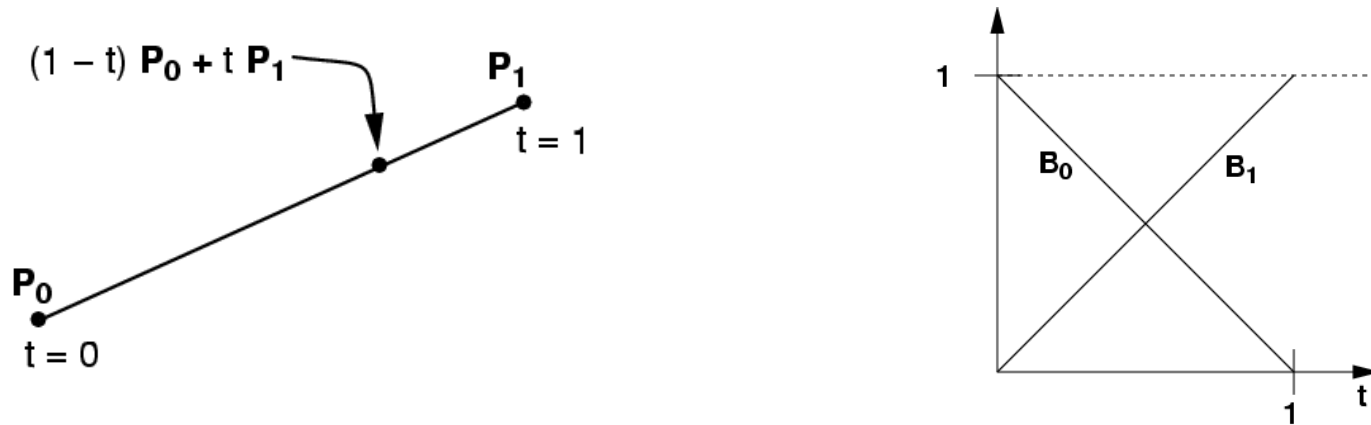


Interpolation Curves / Splines



Linear Interpolation

- Simplest "curve" between two points

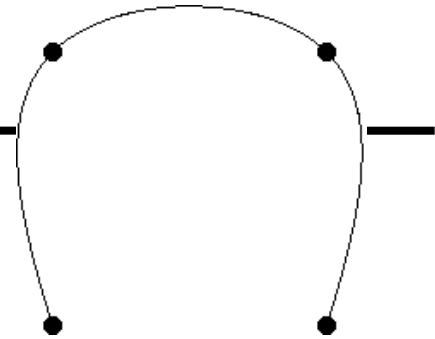


$$Q(t) = \begin{pmatrix} Q_x(t) \\ Q_y(t) \\ Q_z(t) \end{pmatrix} = \begin{pmatrix} (P_0) & (P_1) \end{pmatrix} \begin{pmatrix} -1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} t \\ 1 \end{pmatrix}$$

$$Q(t) = \mathbf{G}\mathbf{B}\mathbf{T}(t) = \text{Geometry } \mathbf{G} \cdot \text{Spline Basis } \mathbf{B} \cdot \text{Power Basis } \mathbf{T}(t)$$

Interpolation Curves

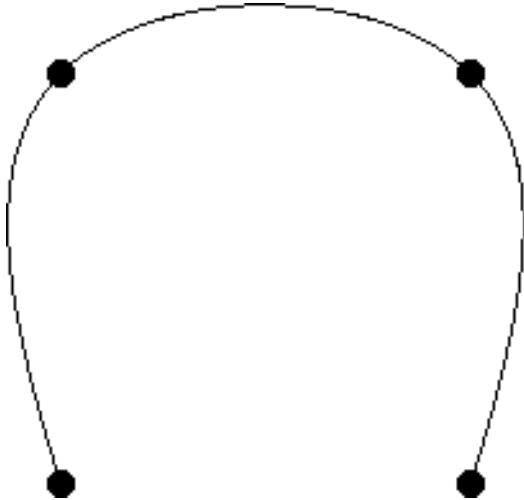
- Curve is constrained to pass through all control points
- Given points $P_0, P_1, \dots, P_n$, find lowest degree polynomial which passes through the points



$$x(t) = a_{n-1}t^{n-1} + \dots + a_2t^2 + a_1t + a_0$$
$$y(t) = b_{n-1}t^{n-1} + \dots + b_2t^2 + b_1t + b_0$$

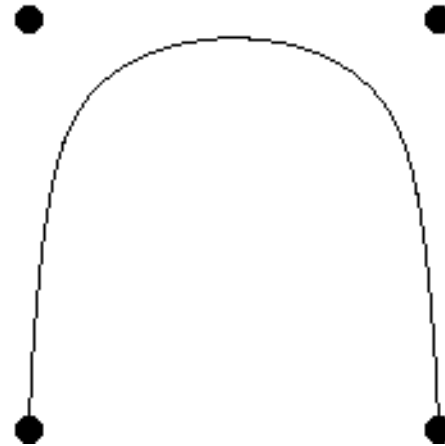
$$Q(t) = \mathbf{G}\mathbf{B}\mathbf{T}(\mathbf{t}) = \text{Geometry } \mathbf{G} \cdot \text{Spline Basis } \mathbf{B} \cdot \text{Power Basis } \mathbf{T}(\mathbf{t})$$

Interpolation vs. Approximation Curves



Interpolation

curve must pass
through control points

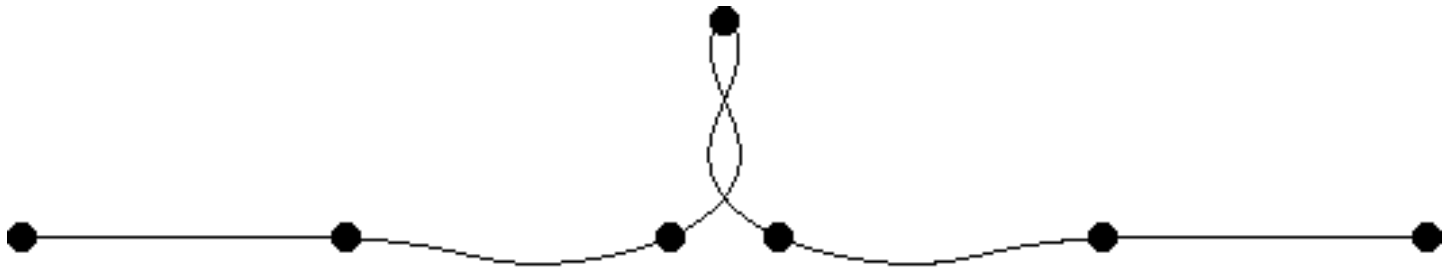


Approximation

curve is influenced
by control points

Interpolation vs. Approximation Curves

- Interpolation Curve – over constrained → lots of (undesirable?) oscillations

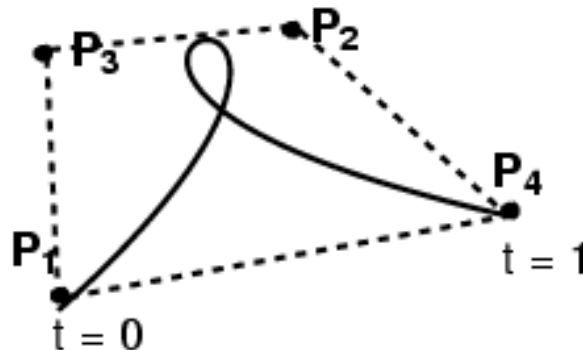
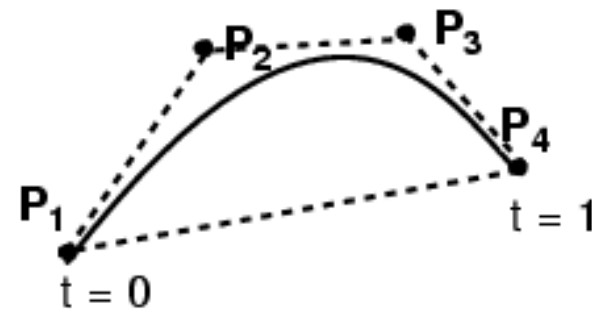
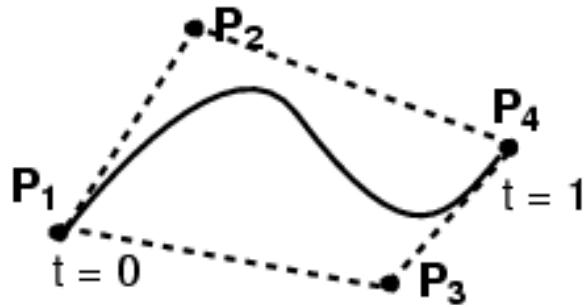


- Approximation Curve – more reasonable?



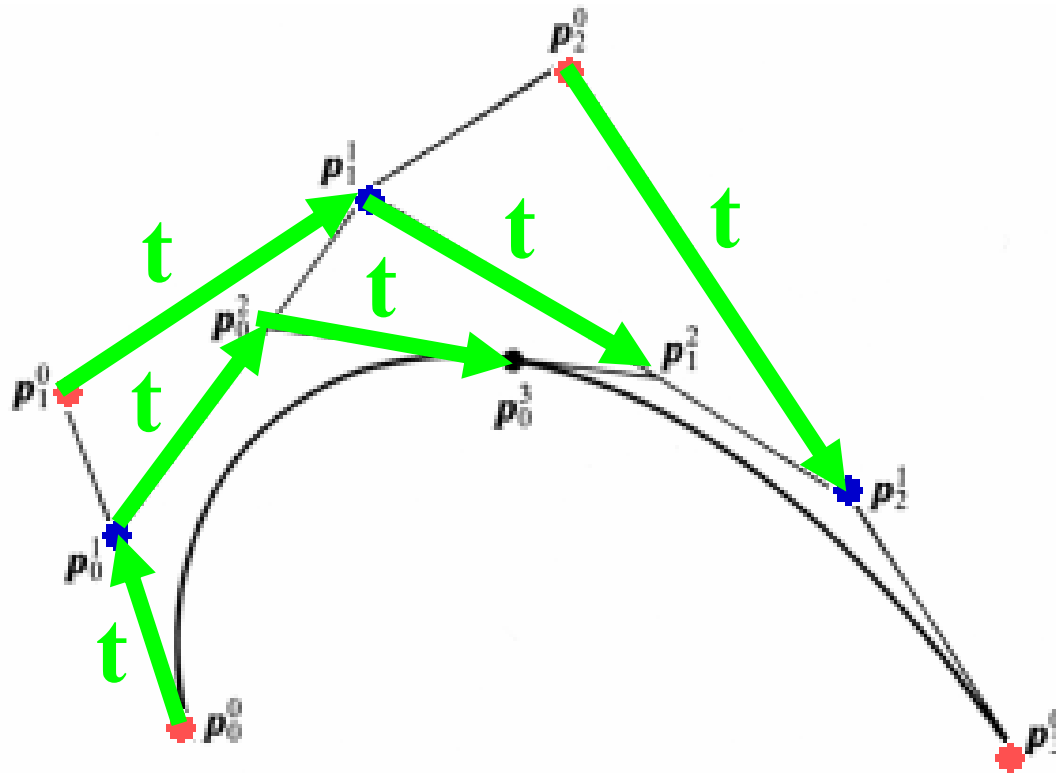
Cubic Bézier Curve

- 4 control points
- Curve passes through first & last control point
- Curve is tangent at P_0 to $(P_0 - P_1)$ and at P_4 to $(P_4 - P_3)$

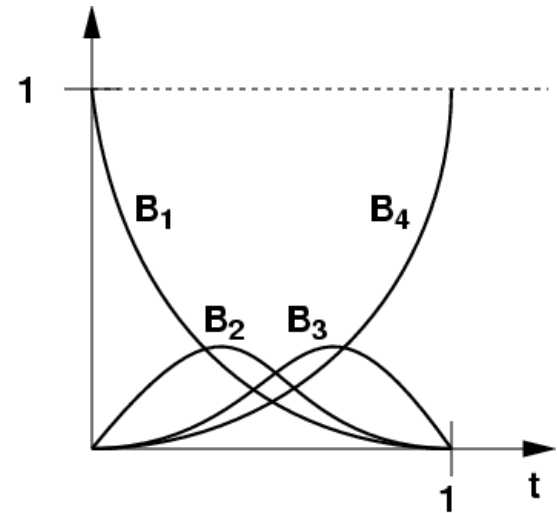
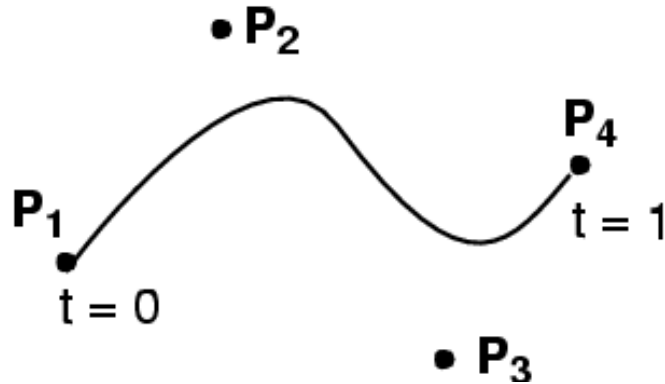


Cubic Bézier Curve

- de Casteljau's algorithm for constructing Bézier curves



Cubic Bézier Curve

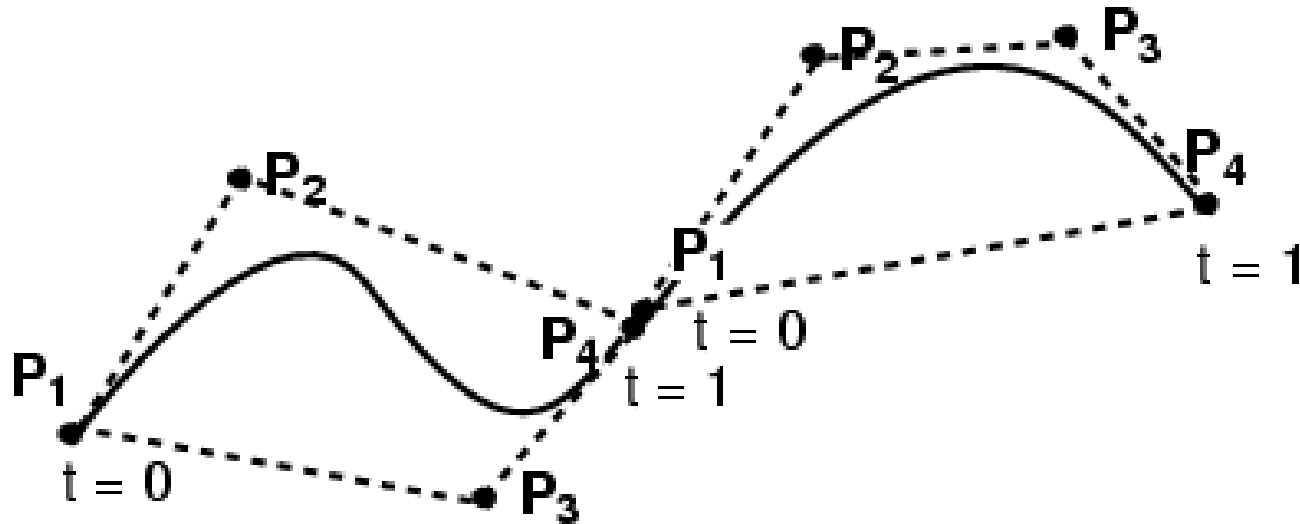


$$Q(t) = (1-t)^3 P_1 + 3t(1-t)^2 P_2 + 3t^2(1-t) P_3 + t^3 P_4$$

$$Q(t) = \mathbf{GBT}(t) \quad B_{Bezier} = \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 3 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

$$B_1(t) = (1-t)^3; B_2(t) = 3t(1-t)^2; B_3(t) = 3t^2(1-t); B_4(t) = t^3$$

Connecting Cubic Bézier Curves



- How can we guarantee C0 continuity (no gaps)?
- How can we guarantee C1 continuity (tangent vectors match)?
- Asymmetric: Curve goes through some control points but misses others

Higher-Order Bézier Curves

- > 4 control points
- Bernstein Polynomials as the basis functions

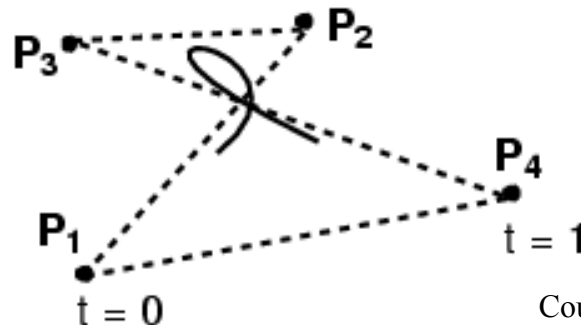
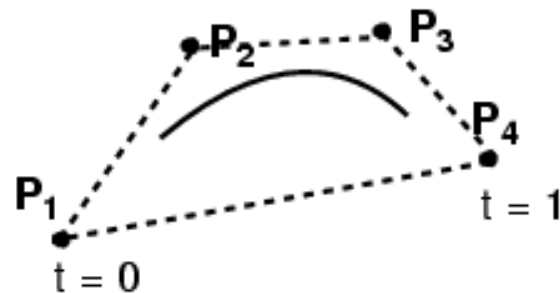
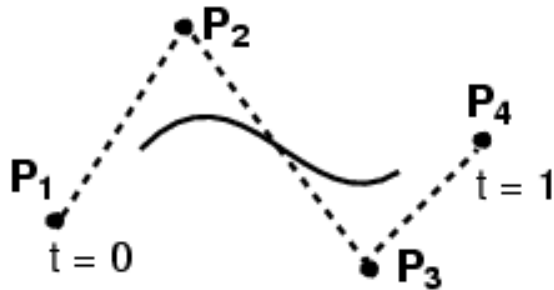
$$B_i^n(t) = \frac{n!}{i!(n-i)!} t^i (1-t)^{n-i}, \quad 0 \leq i \leq n$$

- Every control point affects the entire curve
 - Not simply a local effect
 - More difficult to control for modeling

Courtesy of Seth Teller. Used with permission.

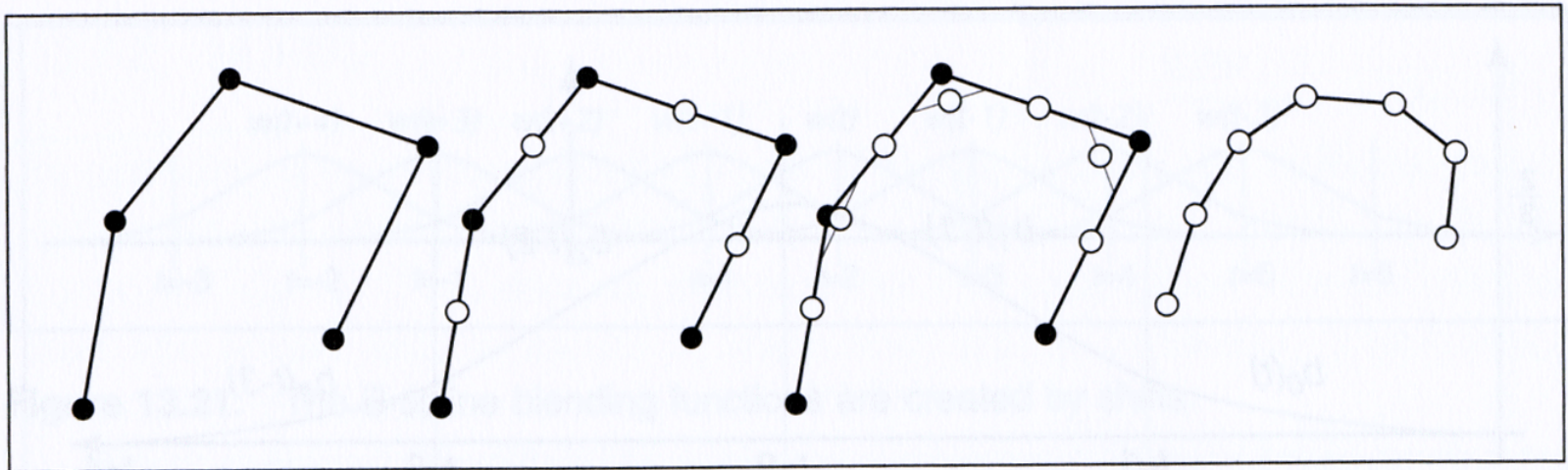
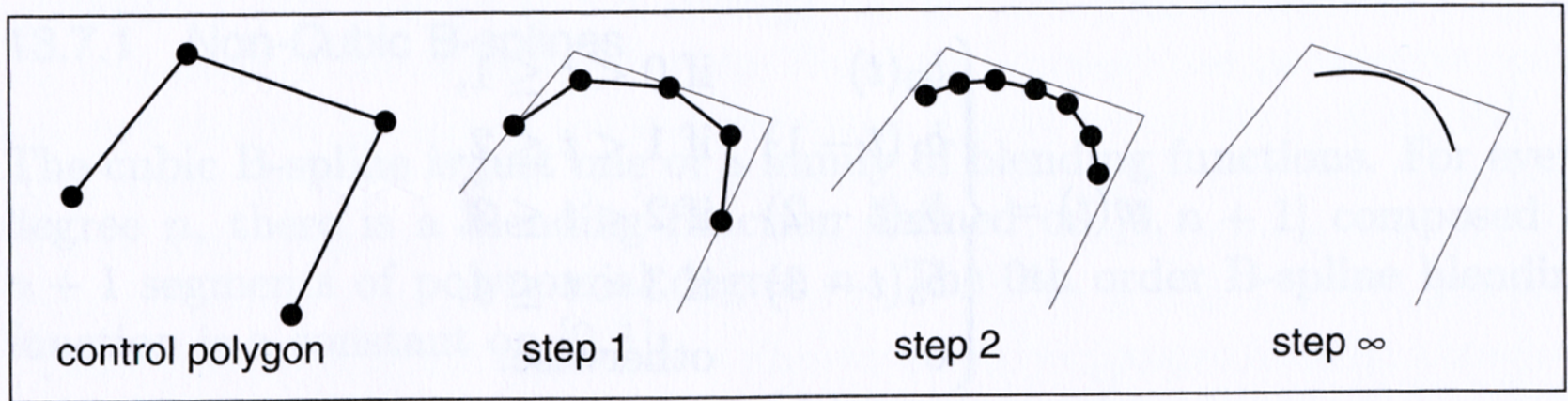
Cubic BSplines

- ≥ 4 control points
- Locally cubic
- Curve is not constrained to pass through any control points

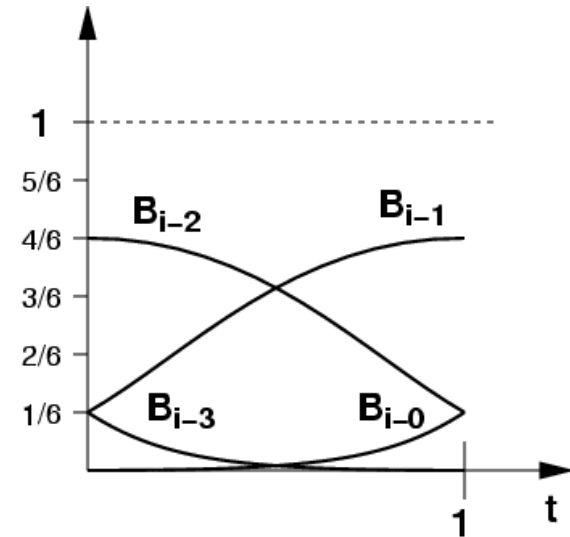
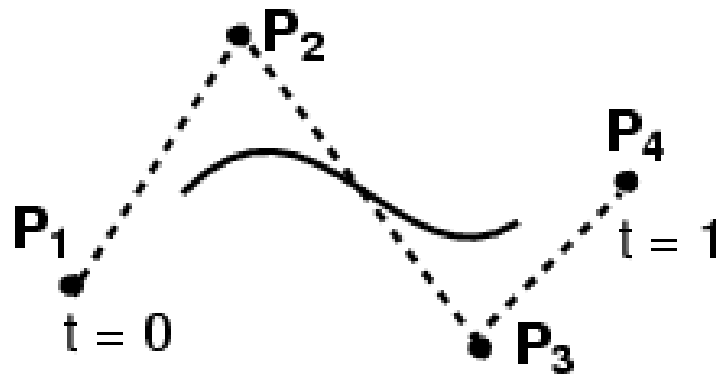


Cubic BSplines

- Iterative method for constructing BSplines



Cubic BSplines

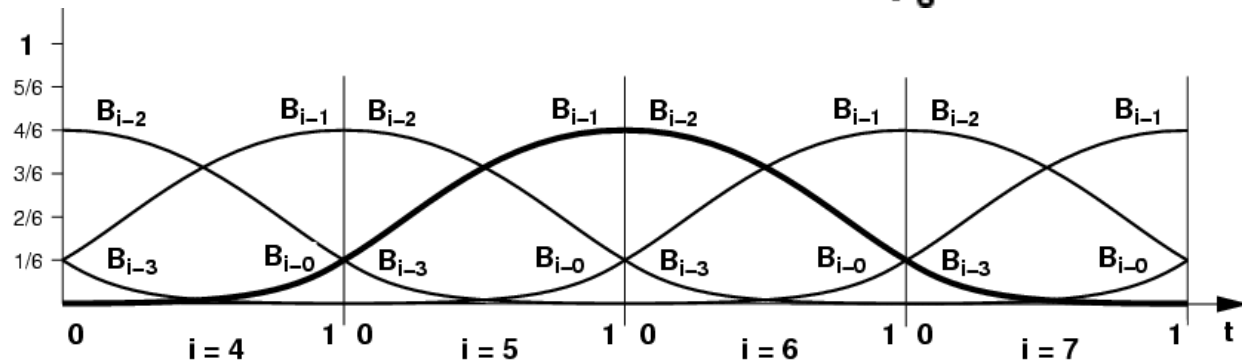
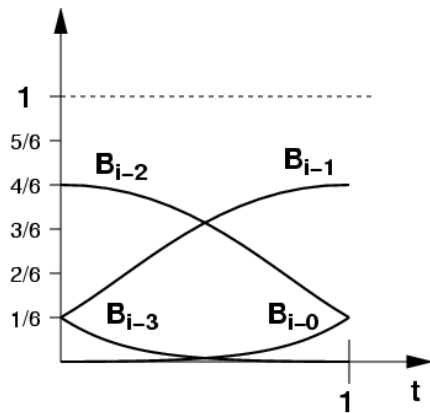
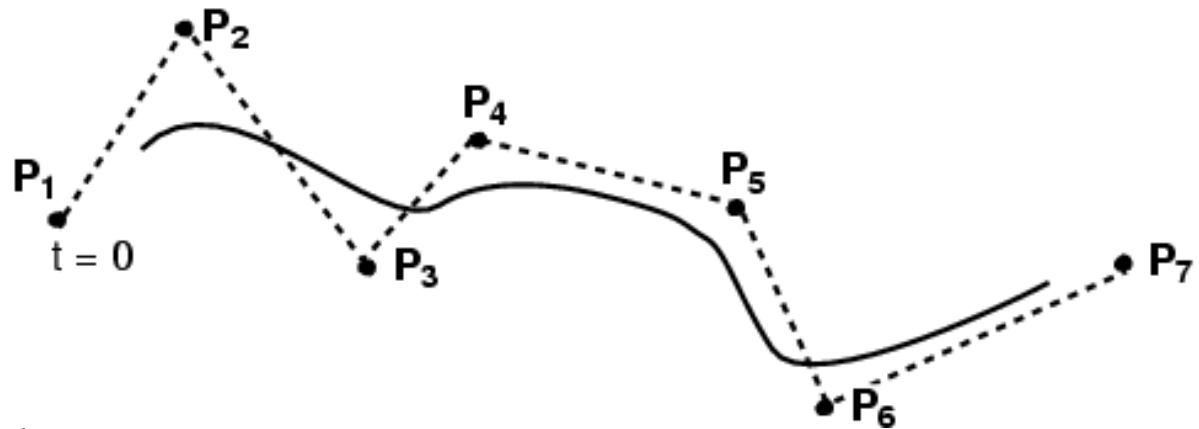
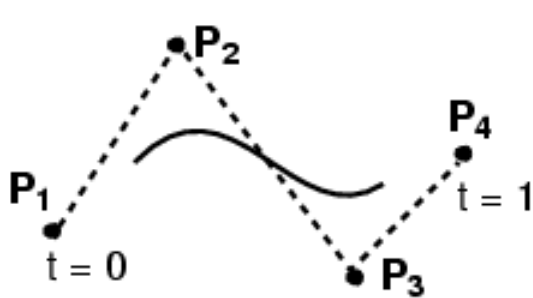


$$Q(t) = \frac{(1-t)^3}{6}P_{i-3} + \frac{3t^3 - 6t^2 + 4}{6}P_{i-2} + \frac{-3t^3 + 3t^2 + 3t + 1}{6}P_{i-1} + \frac{t^3}{6}P_i$$

$$Q(t) = \mathbf{GBT}(t) \quad B_{B-Spline} = \frac{1}{6} \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 0 & 3 & 0 \\ 1 & 4 & 1 & 0 \end{pmatrix}$$

Cubic BSplines

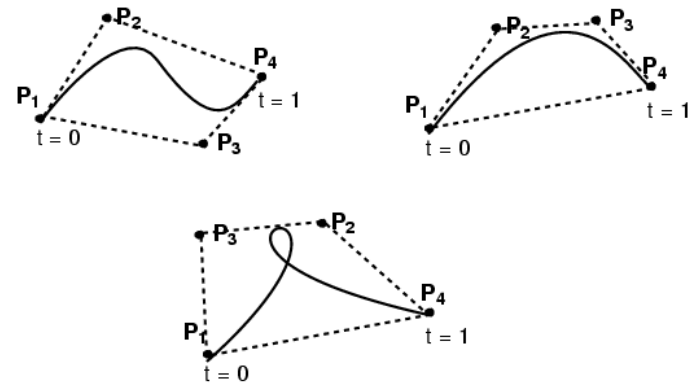
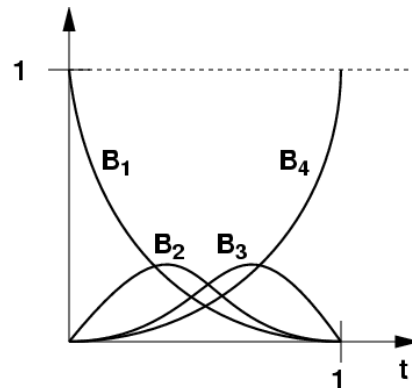
- can be chained together
- better control locally (windowing)



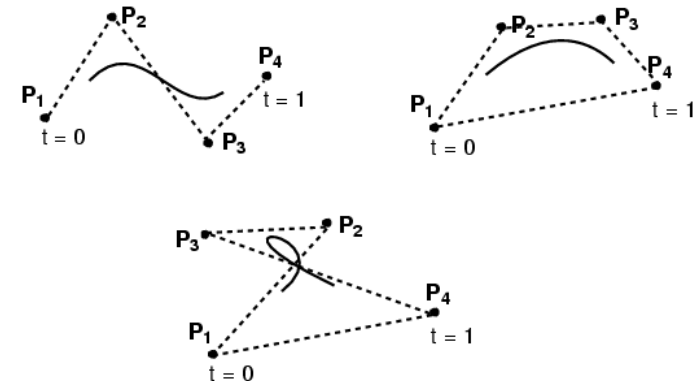
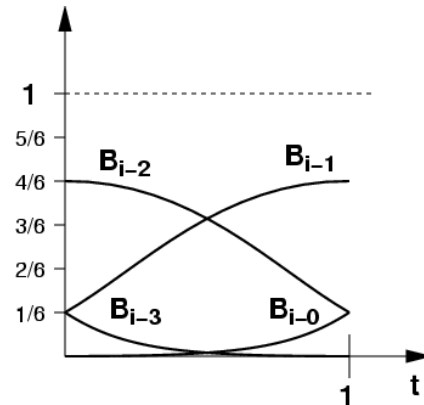
Bézier is not the same as BSpline

- Relationship to the control points is different

Bézier



BSpline



Bezier is not the same as Bspline

- But we can convert between the curves using the basis functions:

$$B_{Bezier} = \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 3 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$
$$B_{B-Spline} = \frac{1}{6} \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 0 & 3 & 0 \\ 1 & 4 & 1 & 0 \end{pmatrix}$$

$$Q(t) = \mathbf{G}\mathbf{B}\mathbf{T}(\mathbf{t}) = \text{Geometry } \mathbf{G} \cdot \text{Spline Basis } \mathbf{B} \cdot \text{Power Basis } \mathbf{T}(\mathbf{t})$$

NURBS (generalized BSplines)

- BSpline: uniform cubic BSpline
- NURBS: Non-Uniform Rational BSpline
 - non-uniform = different spacing between the blending functions, a.k.a. knots
 - rational = ratio of polynomials (instead of cubic)

Questions?

Today

- Review
- Motivation
- Spline Curves
- Spline Surfaces / Patches
 - Tensor Product
 - Bilinear Patches
 - Bezier Patches
- Subdivision Surfaces
- Procedural Texturing

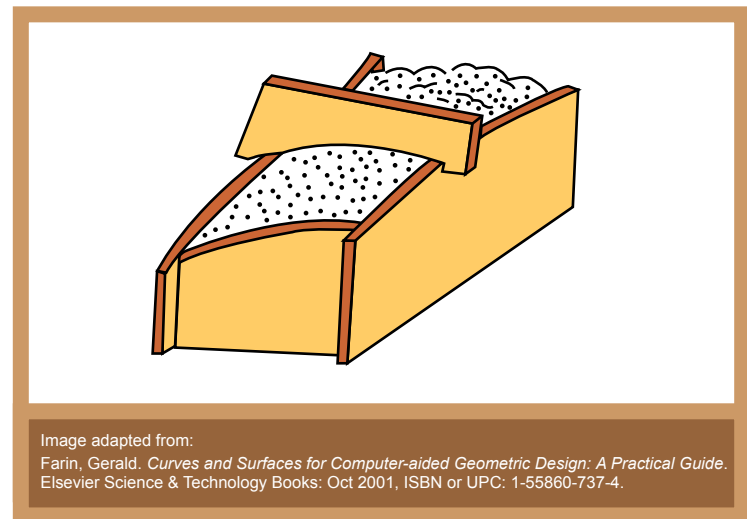
Tensor Product

- Of two vectors:

$$\begin{bmatrix} a_1 & a_2 & a_3 \end{bmatrix} \otimes \begin{bmatrix} b_1 & b_2 & b_3 & b_4 \end{bmatrix} = \begin{bmatrix} a_1 b_1 & a_2 b_1 & a_3 b_1 \\ a_1 b_2 & a_2 b_2 & a_3 b_2 \\ a_1 b_3 & a_2 b_3 & a_3 b_3 \\ a_1 b_4 & a_2 b_4 & a_3 b_4 \end{bmatrix}$$

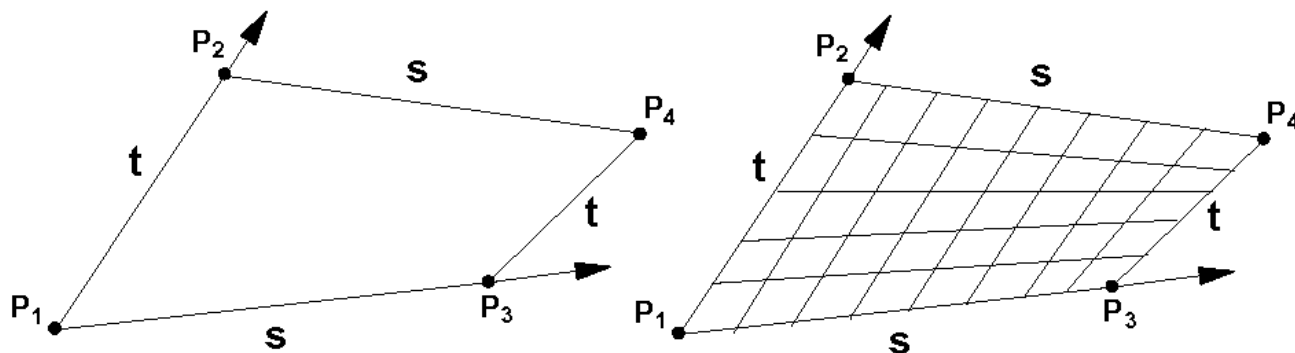
- Similarly, we can define a surface as the tensor product of two curves....

Farin, Curves and Surfaces for
Computer Aided Geometric Design



Bilinear Patch

Bi-lerp a (typically non-planar) quadrilateral

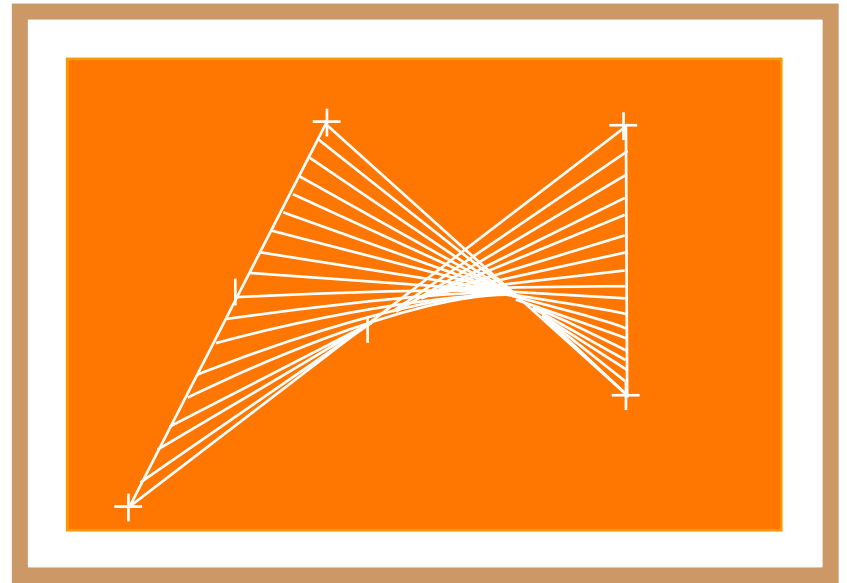
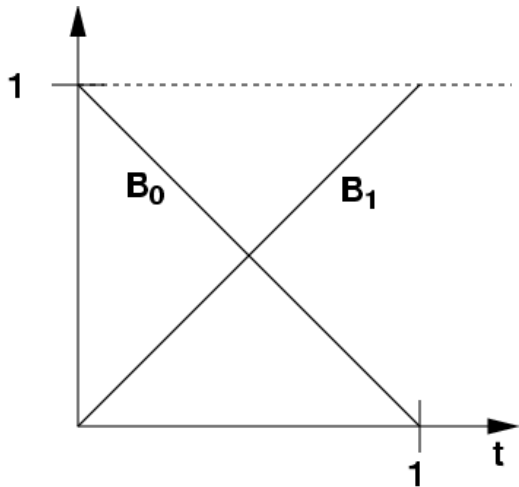


Notation: $\mathbf{L}(P_1, P_2, \alpha) \equiv (1 - \alpha)P_1 + \alpha P_2$

$$Q(s, t) = \mathbf{L}(\mathbf{L}(P_1, P_2, t), \mathbf{L}(P_3, P_4, t), s)$$

Bilinear Patch

- Smooth version of quadrilateral with non-planar vertices...



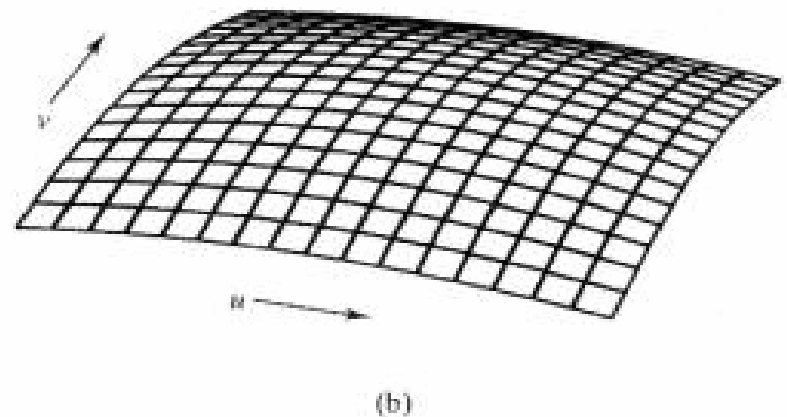
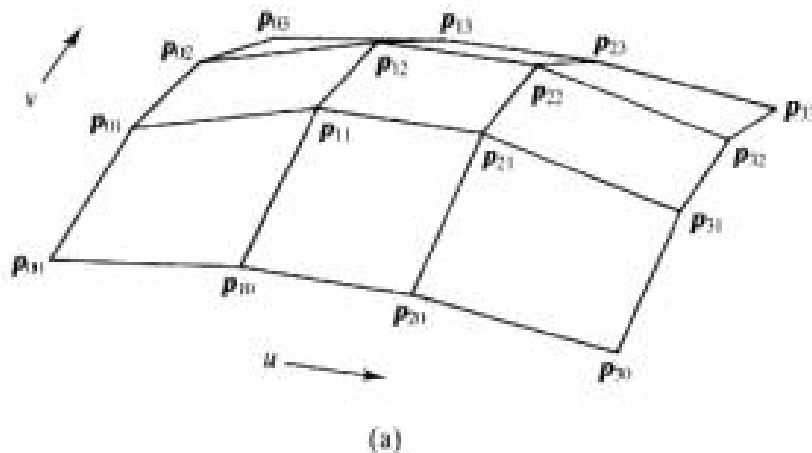
- But will this help us model smooth surfaces?
- Do we have control of the derivative at the edges?

Bicubic Bezier Patch

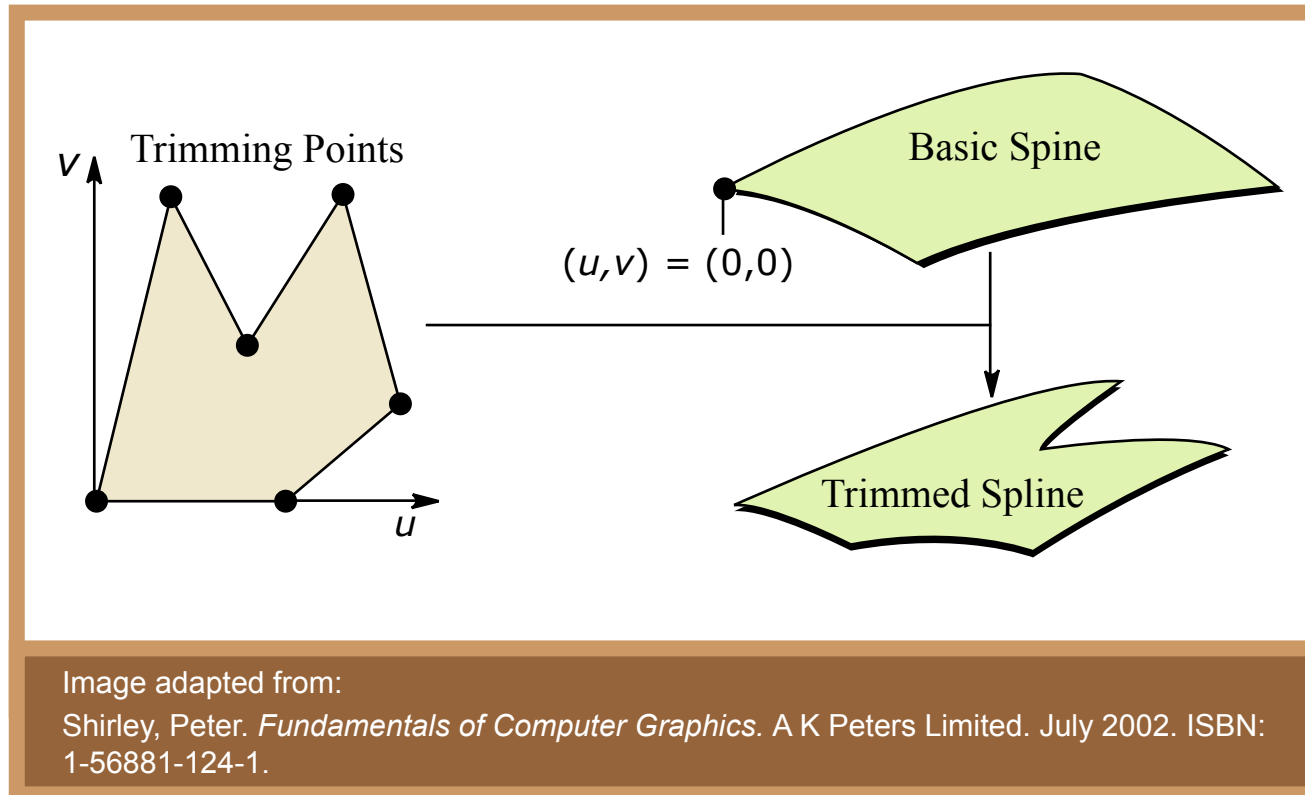
Notation: $\mathbf{CB}(P_1, P_2, P_3, P_4, \alpha)$ is Bézier curve with control points P_i evaluated at α

Define “Tensor-product” Bézier surface

$$Q(s, t) = \mathbf{CB}(\begin{array}{l} \mathbf{CB}(P_{00}, P_{01}, P_{02}, P_{03}, t), \\ \mathbf{CB}(P_{10}, P_{11}, P_{12}, P_{13}, t), \\ \mathbf{CB}(P_{20}, P_{21}, P_{22}, P_{23}, t), \\ \mathbf{CB}(P_{30}, P_{31}, P_{32}, P_{33}, t), \\ s) \end{array}$$



Trimming Curves for Patches



Questions?

Today

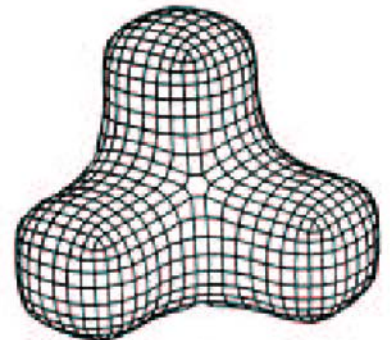
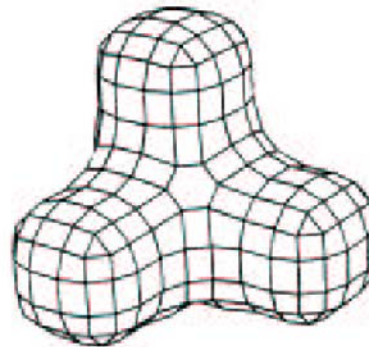
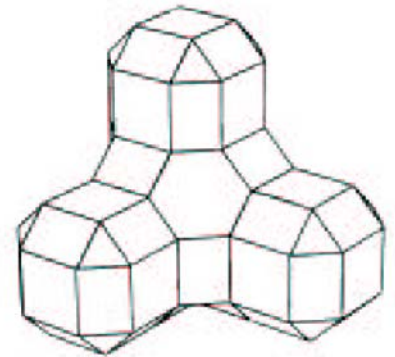
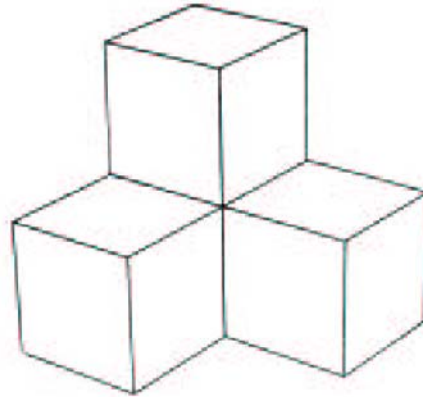
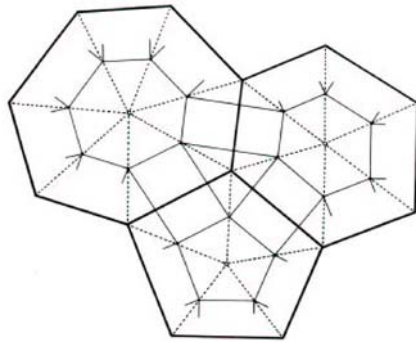
- Review
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- Spline Surfaces / Patches
- **Subdivision Surfaces**
- Procedural Texturing

Chaikin's Algorithm



Doo-Sabin Subdivision

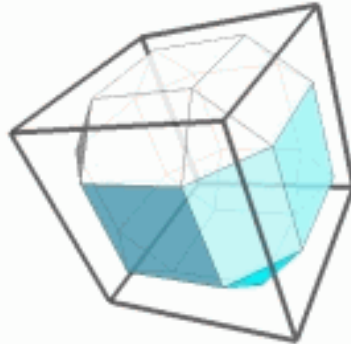
Idea: introduce a new vertex for each face
At the midpoint of old vertex, face centroid



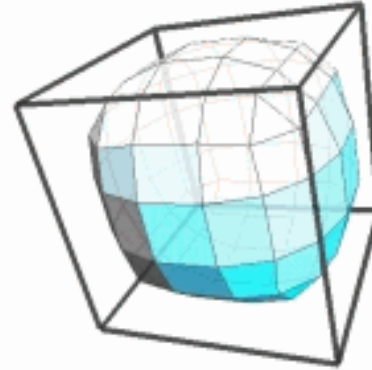
Doo-Sabin Subdivision



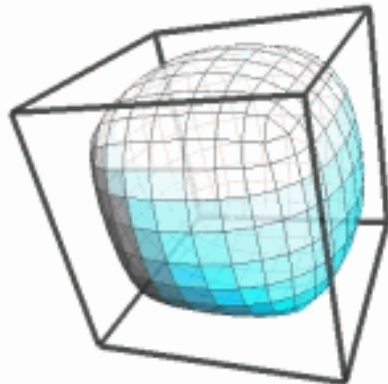
Original Cube



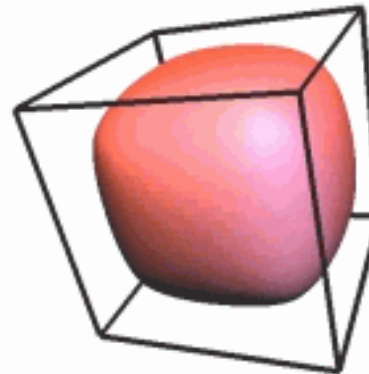
The 1st subdivision



The 2nd subdivision



The 3rd subdivision

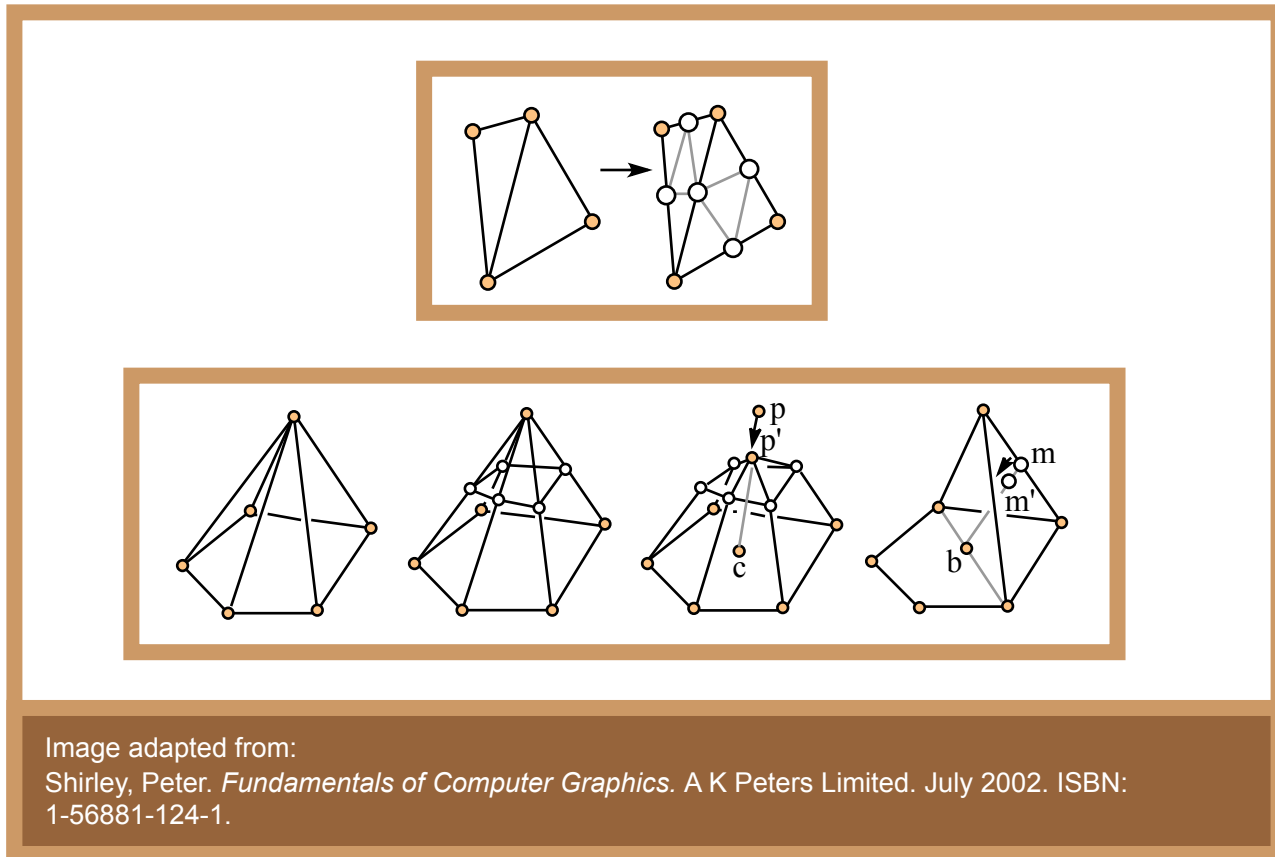


The 5th subdivision

Courtesy of Zheng Xu. Used with permission.

<http://www.ke.ics.saitama-u.ac.jp/xuz/pic/doo-sabin.gif>

Loop Subdivision



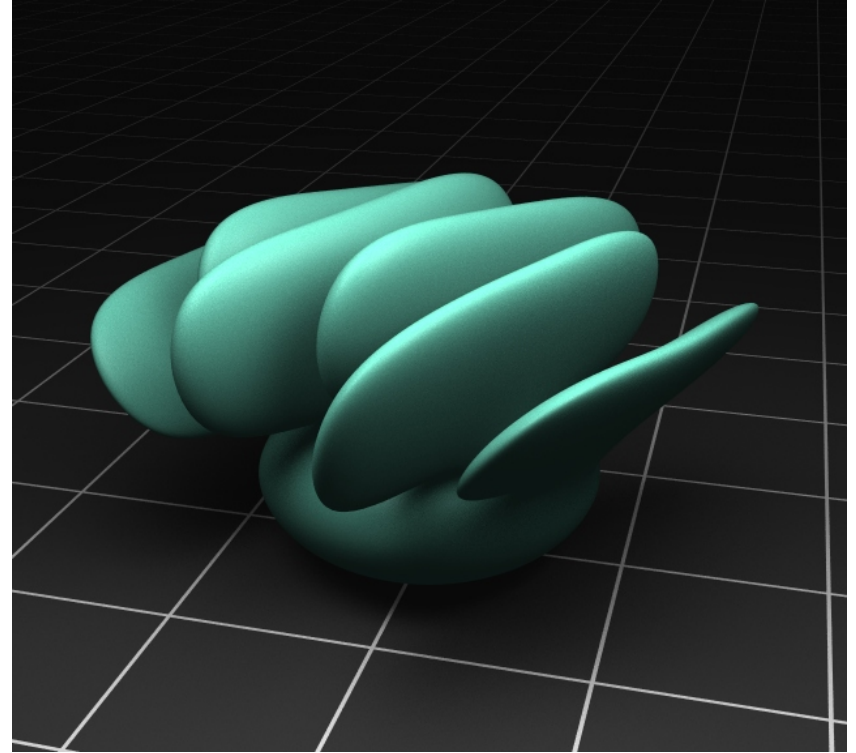
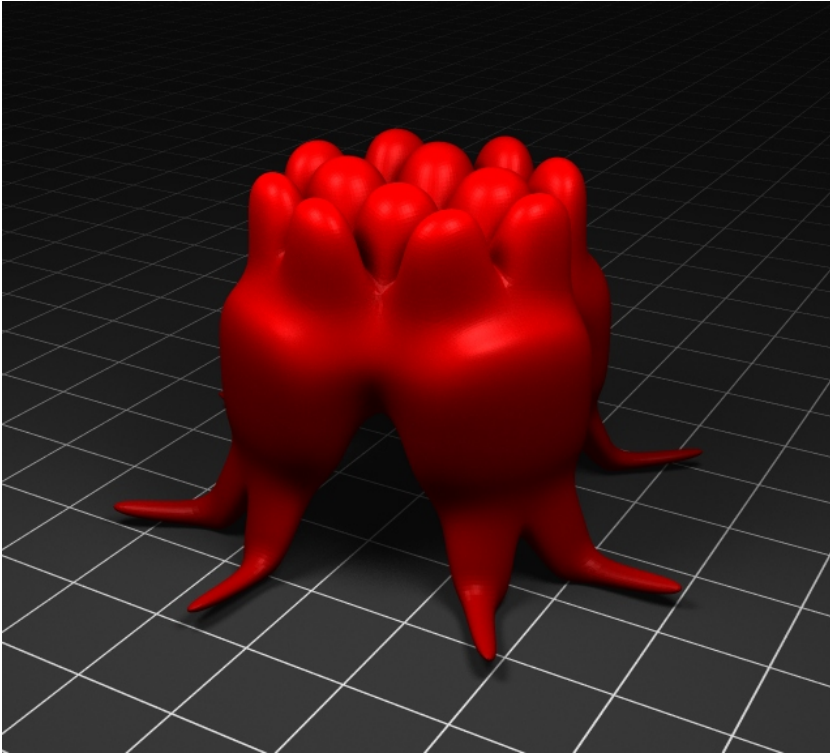
Loop Subdivision

- Some edges can be specified as crease edges

Image removed due to copyright considerations.

<http://grail.cs.washington.edu/projects/subdivision/>

Weird Subdivision Surface Models



Justin Legakis

Courtesy of Justin Legakis. Used with permission.

Questions?

Today

- Review
- Motivation
- Spline Curves
- Spline Surfaces / Patches
- Procedural Texturing

Procedural Textures

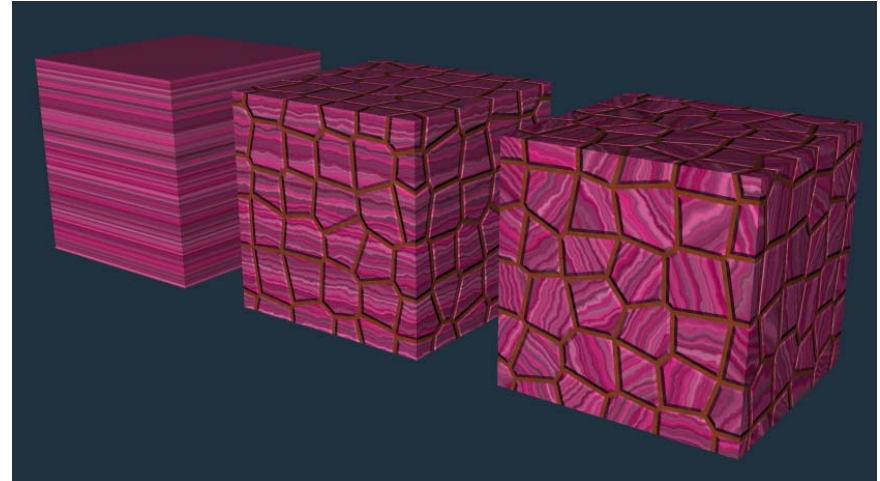
$f(x,y,z) \rightarrow \text{color}$

Image removed due to copyright considerations.

Procedural Solid Textures

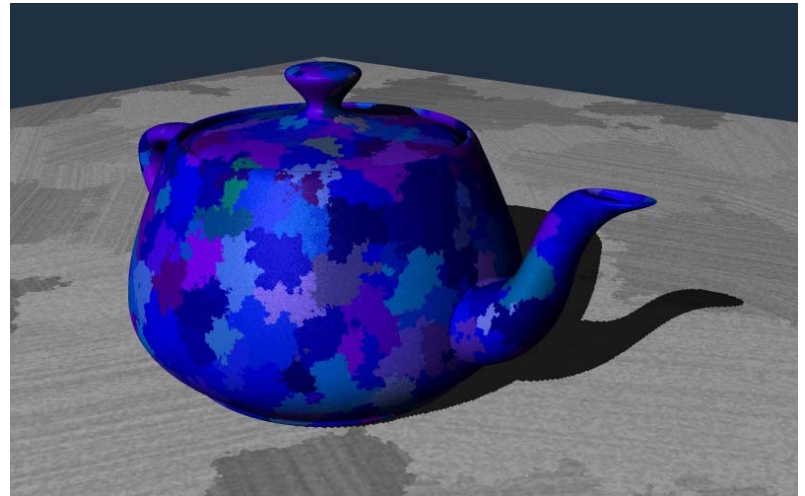
- Noise
- Turbulence

Image removed due to copyright considerations.



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Image removed due to copyright considerations.



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Questions?

Next Thursday:

Animation I: Keyframing