Ray Casting

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MIT EECS 6.837

Frédo Durand and Barb Cutler

Some slides courtesy of Leonard McMillan

Administrative

- Assignment 1
  - Due Wednesday September 17

Calendar

- ***1st quiz – Tuesday October 07th***
- ***2nd quiz --Thursday Nov 20th***
- ***Week Dec 1-5 project presentation***
- ***Last day of class: December 9: best projects & final report due***

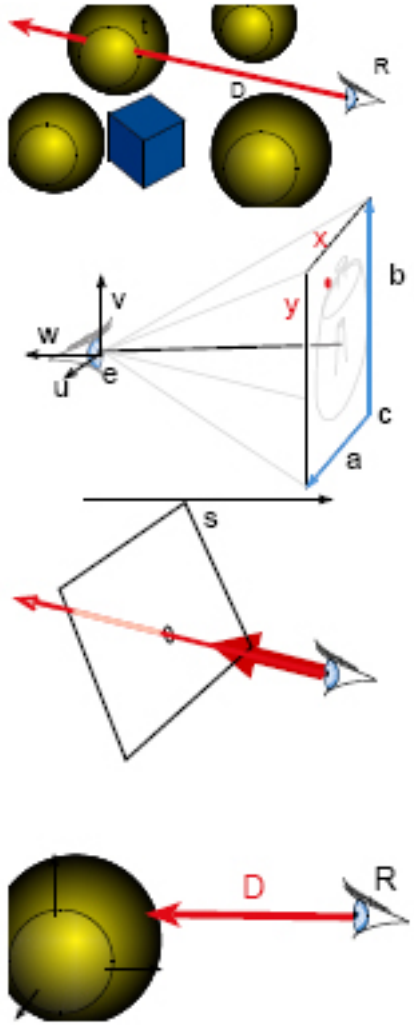
Questions?

Overview of the semester

- Ray Tracing
  - Quiz 1
- Animation, modeling, IBMR
  - Choice of final project
- Rendering pipeline
  - Quiz 2
- Advanced topics

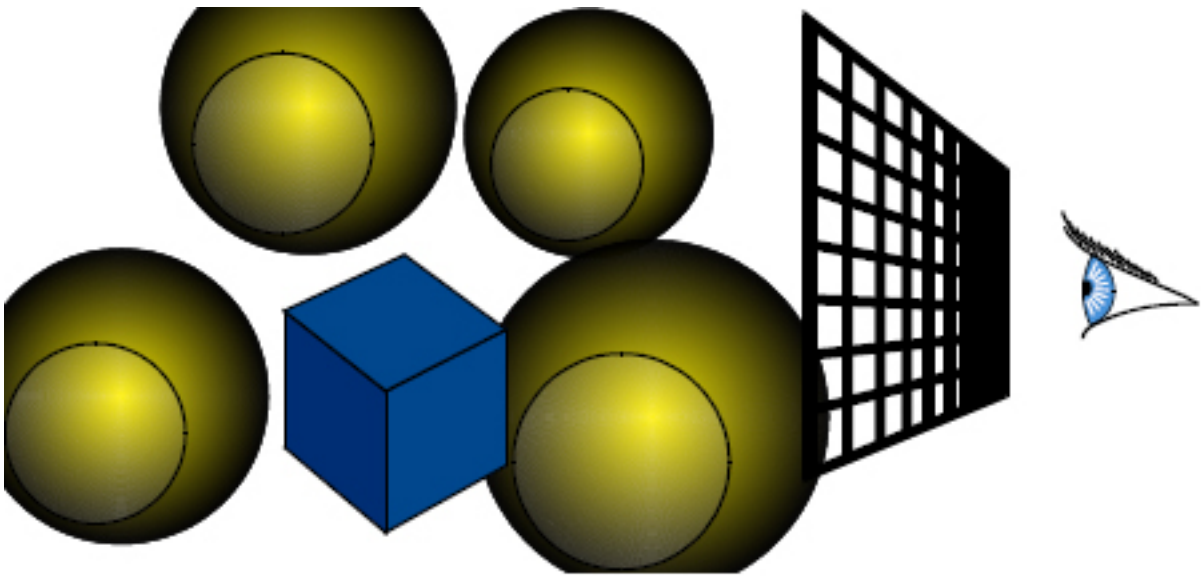
Overview of today

- Introduction
- Camera and ray generation
- Ray-plane intersection
- Ray-sphere intersection



Ray Casting

```
For every pixel
   Construct a ray from the eye
   For every object in the scene
       Find intersection with the ray
       Keep if closest
```



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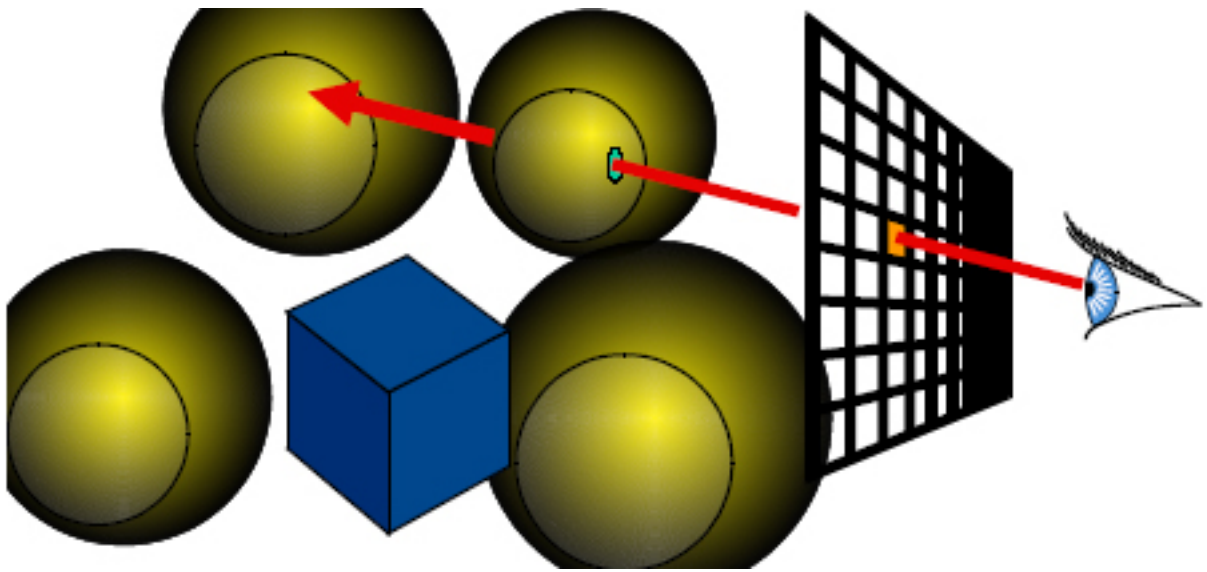
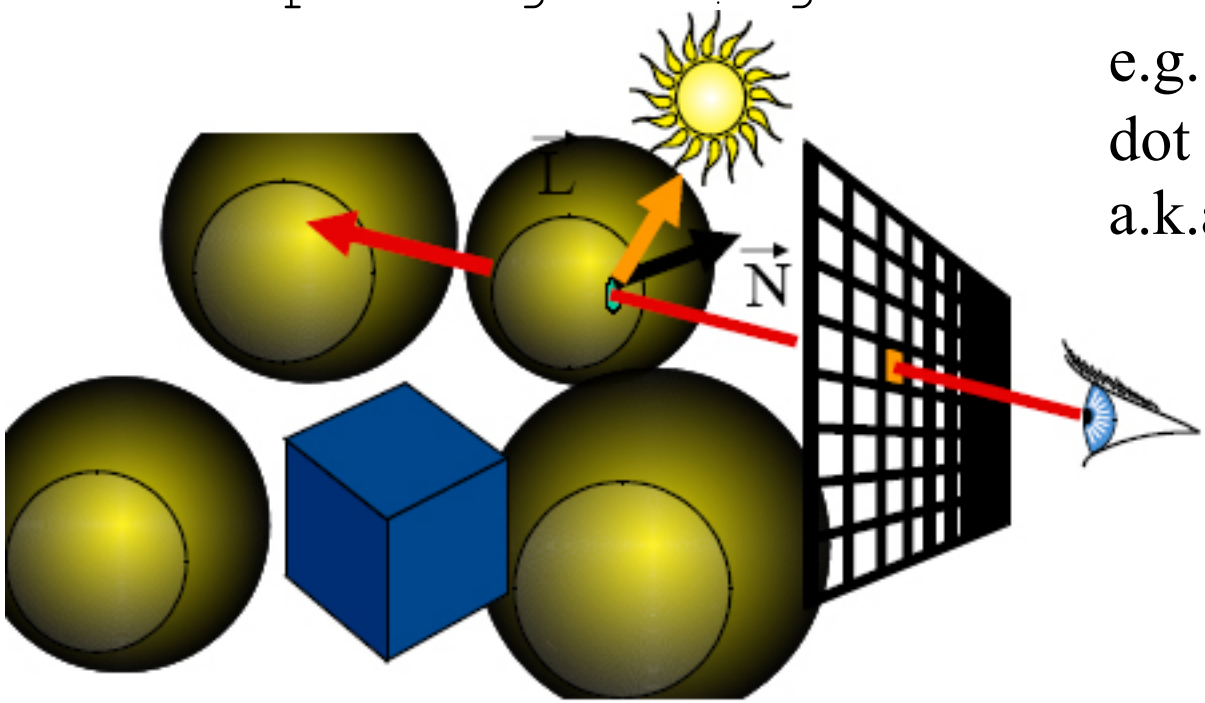


Shading

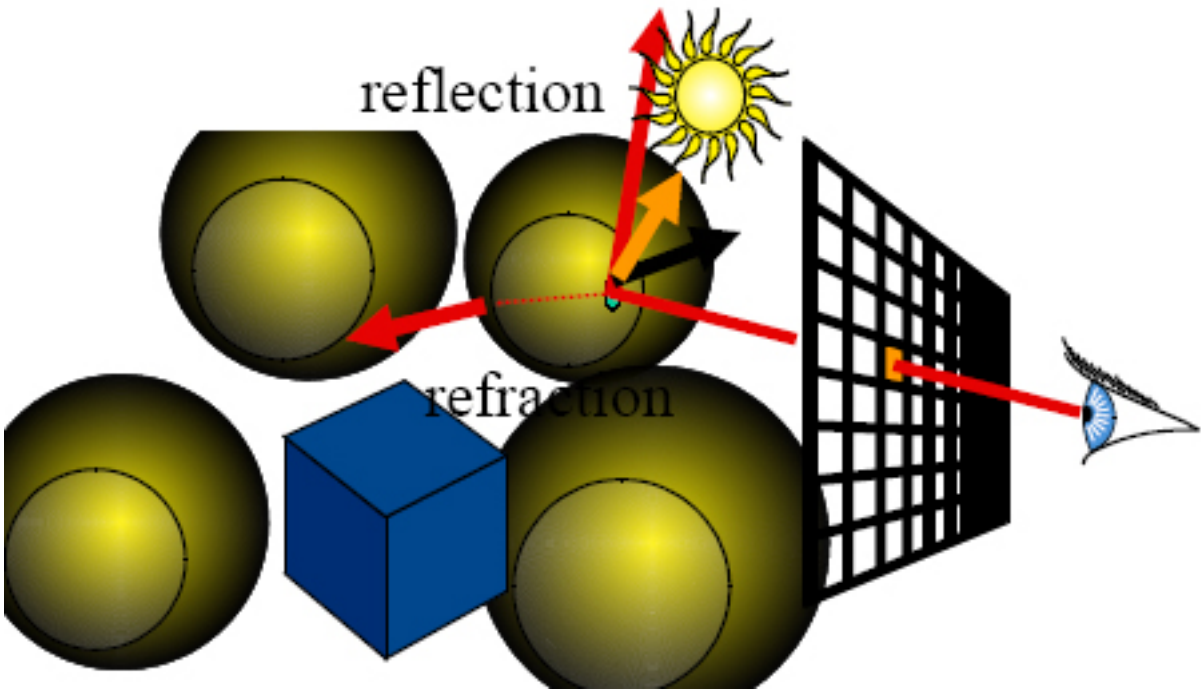
```
For every pixel
   Construct a ray from the eye
   For every object in the scene
       Find intersection with the ray
       Keep if closest
   Shade depending on light and normal vector
```



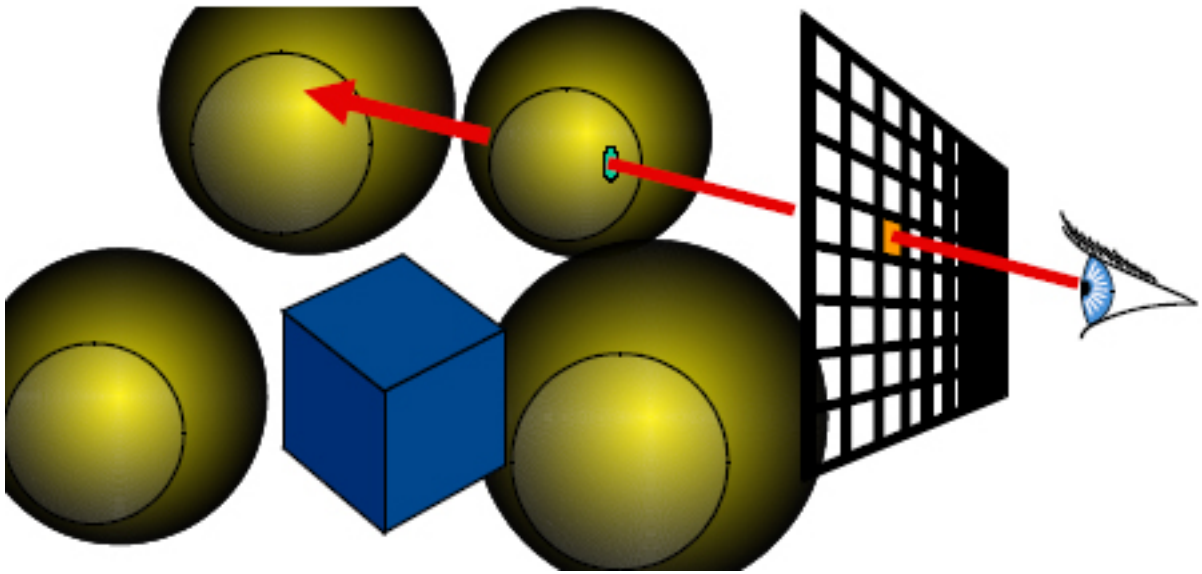
e.g. diffuse shading:
dot product $\vec{N}.\vec{L}$
a.k.a. Lambertian

Ray Tracing

- Secondary rays (shadows, reflection, refraction)
- In a couple of weeks

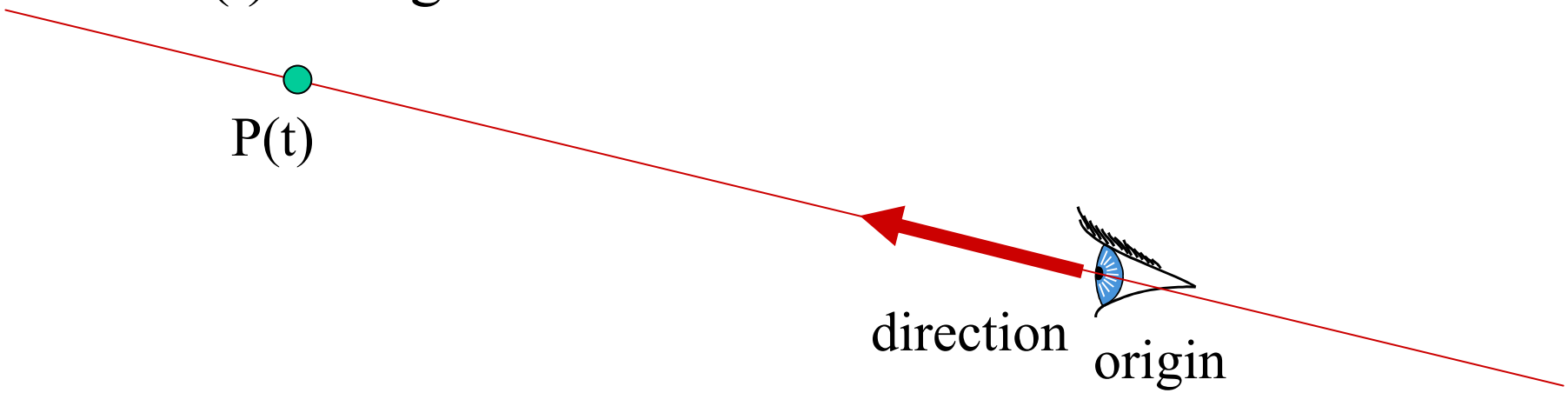


Ray representation?



Ray representation

- Two vectors:
  - Origin
  - Direction (normalized is better)
- Parametric line
  - P(t) = origin + t * direction



Ray Tracing

- Original Ray-traced image by Whitted

Image removed due to copyright considerations.

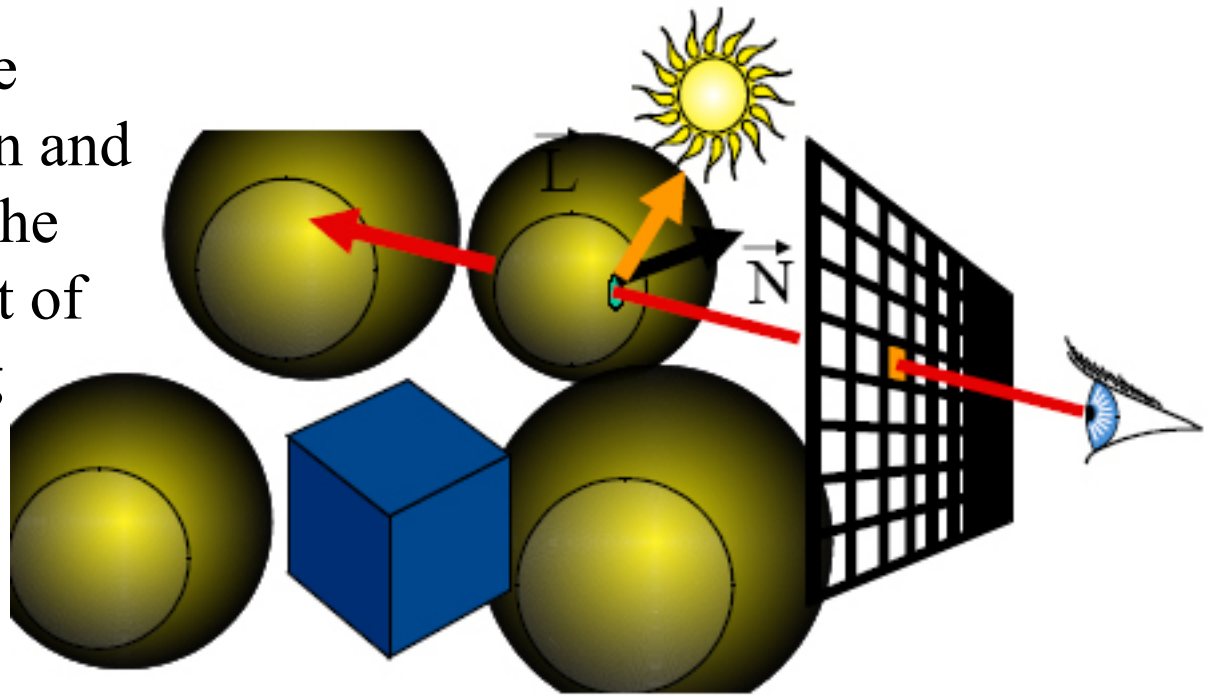
- Image computed using the Dali ray tracer by Henrik Wann Jensen
- Environment map by Paul Debevec

Image removed due to copyright considerations.

Ray casting

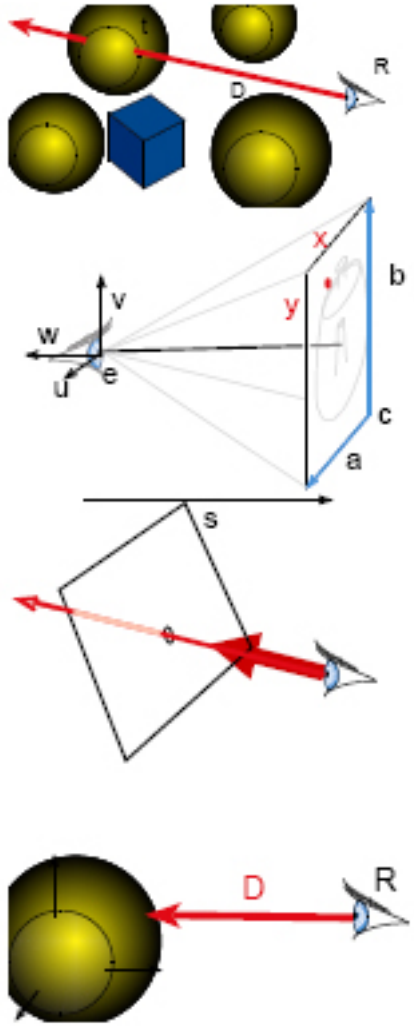
```
For every pixel
   Construct a ray from the eye
   For every object in the scene
       Find intersection with the ray
       Keep if closest
    Shade depending on light and normal vector
```

Finding the intersection and normal is the central part of ray casting



Overview of today

- Introduction
- Camera and ray generation
- Ray-plane intersection
- Ray-sphere intersection



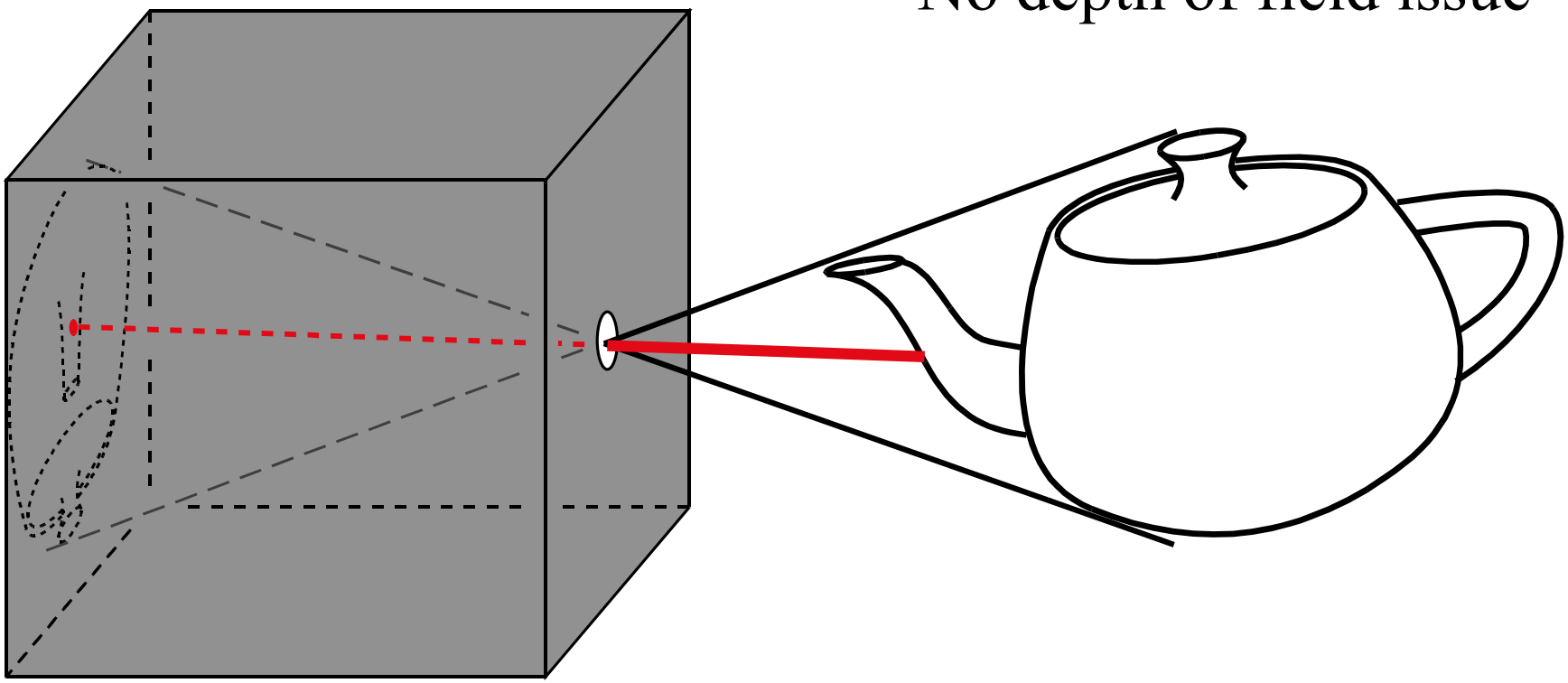
Cameras

```
For every pixel
  Construct a ray from the eye
  For every object in the scene
      Find intersection with the
        ray
      Keep if closest
```

Pinhole camera

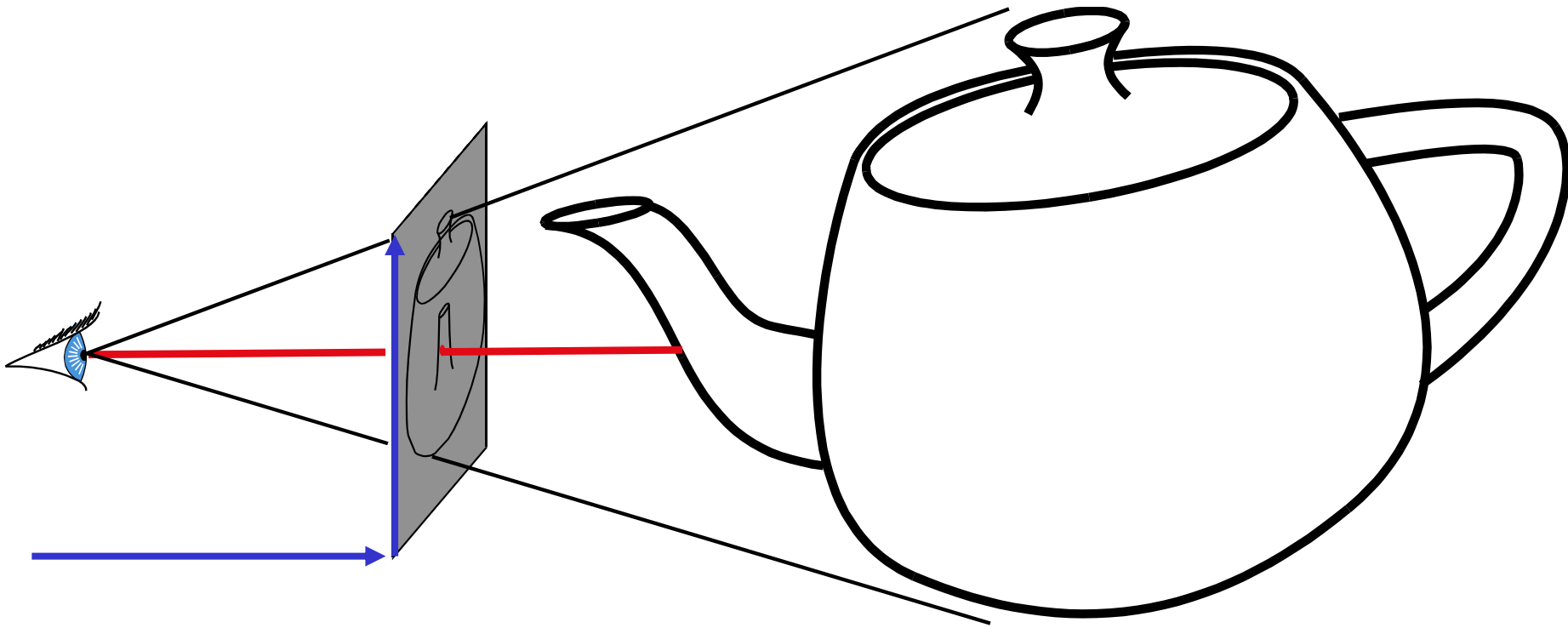
- Box with a tiny hole
- Inverted image
- Similar triangles

- Perfect image if hole infinitely small
- Pure geometric optics
- No depth of field issue



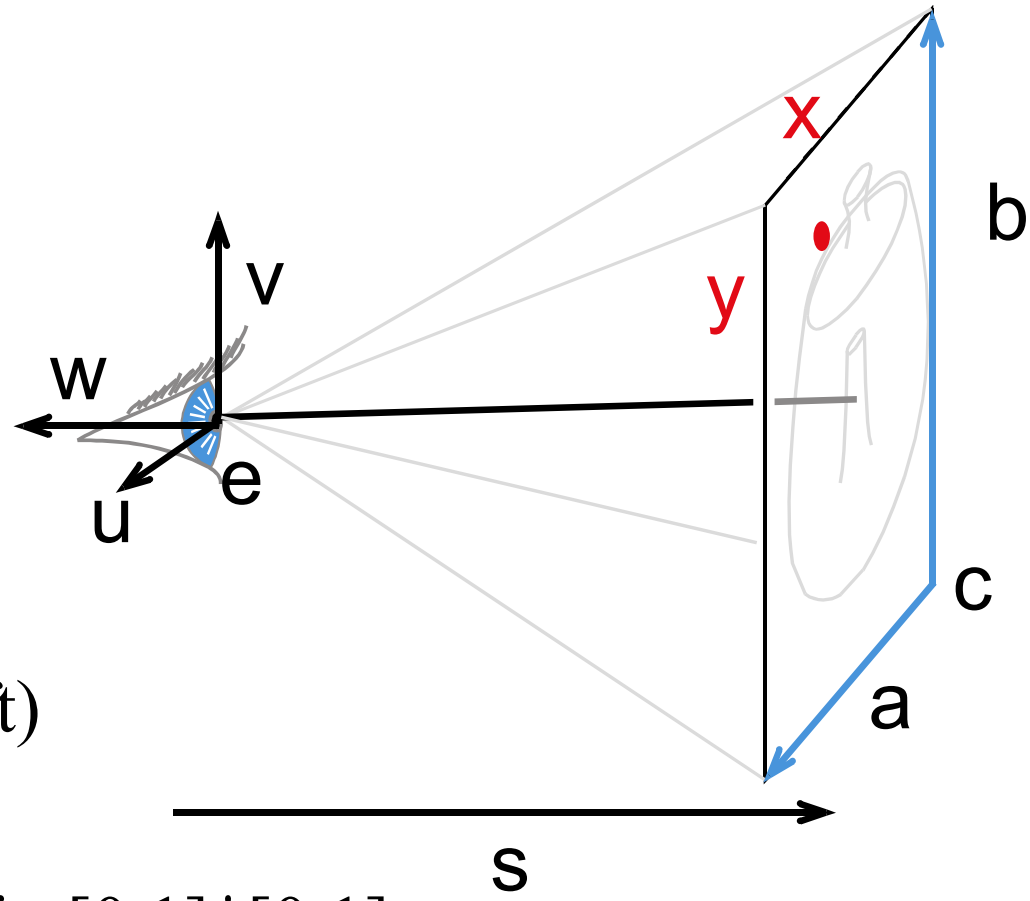
Simplified pinhole camera

- Eye-image pyramid (frustum)
- Note that the distance/size of image are arbitrary



Camera description

- Eye point e
- Orthobasis u, v, w
- Image distance s
- Image rectangle (u0, v0, u1, v1)



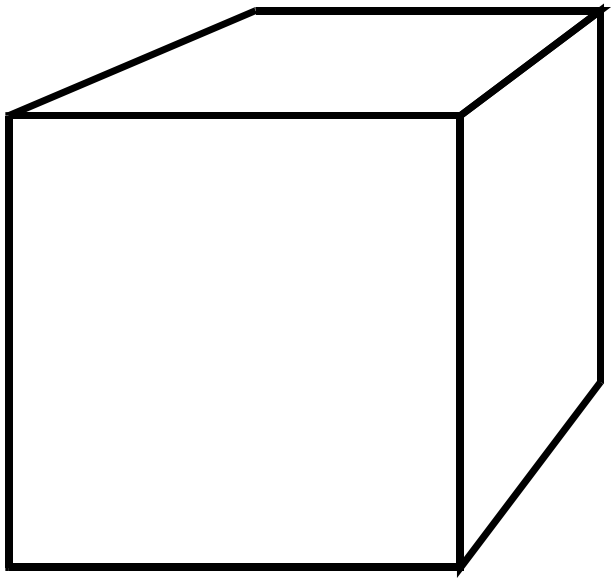
- Deduce c (lower left)
- Deduce a and b
- Screen coordinates in [0,1]*[0,1]
- A point is then c + x a +y b

Alternative perspective encoding

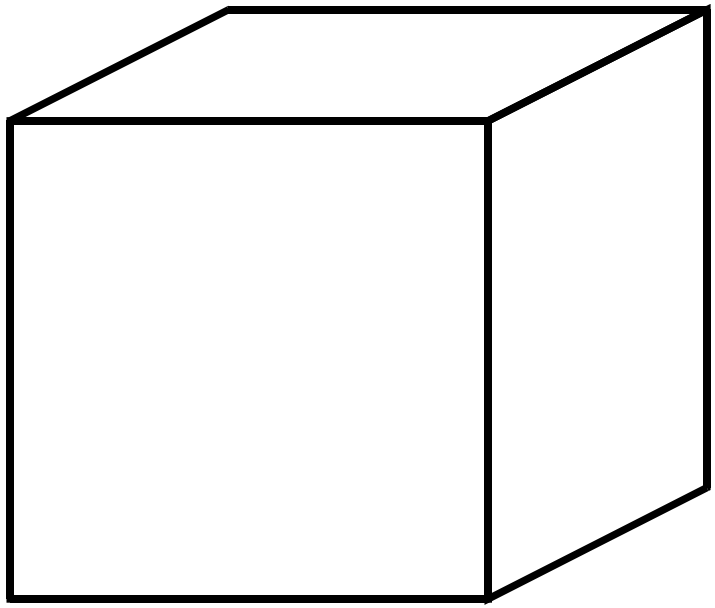
- 4x4 matrix & viewing frustum
- More about that next week

Orthographic camera

- Parallel projection
- No foreshortening
- No vanishing point

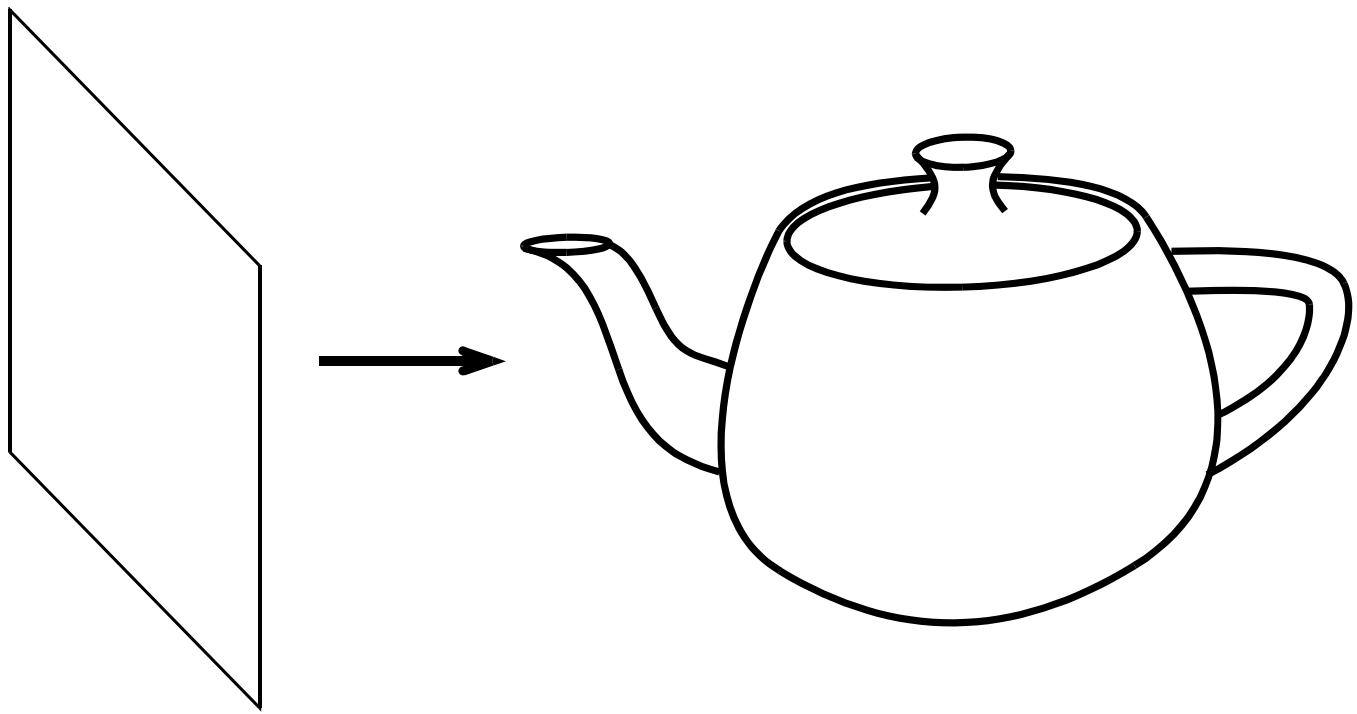


perspective



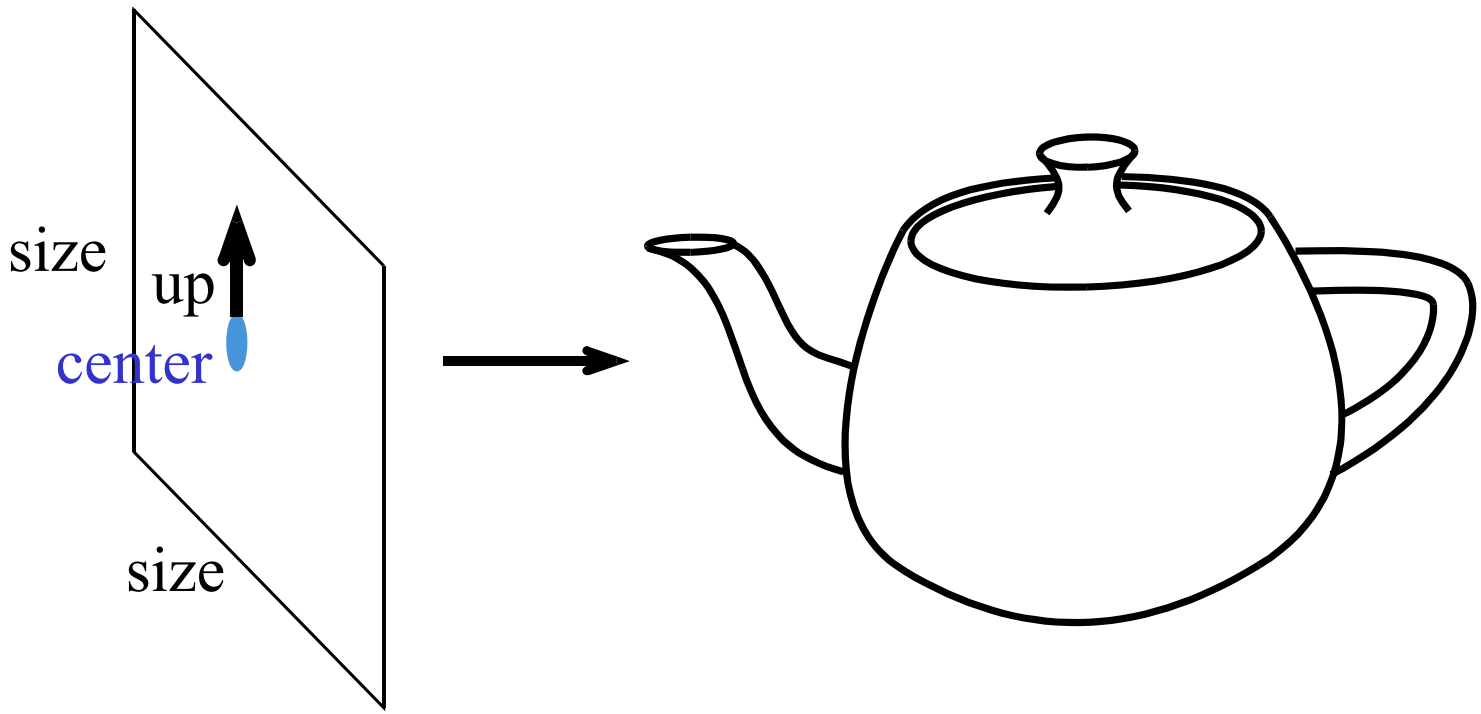
orthographic

Orthographic camera description



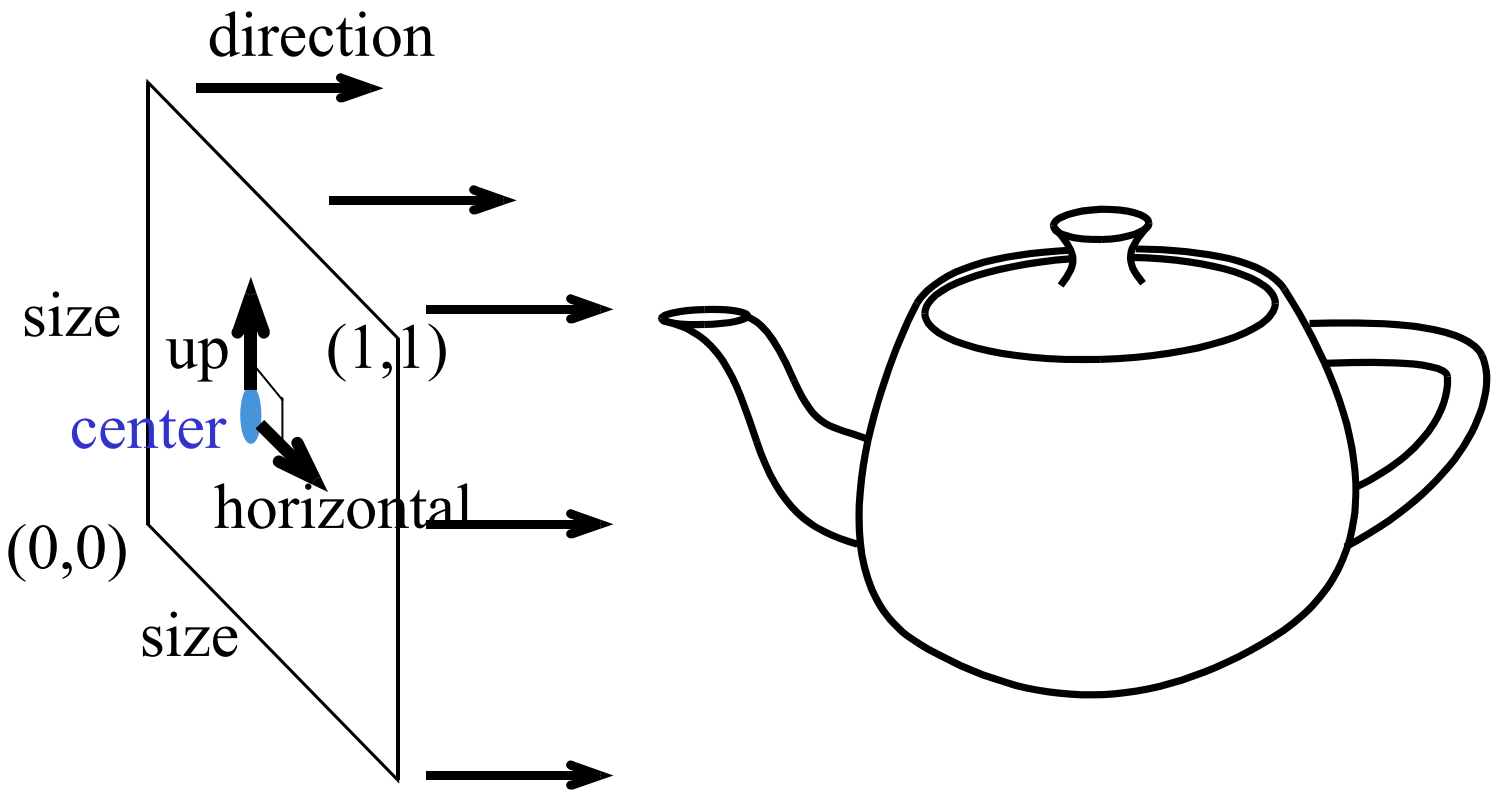
Orthographic camera description

- Direction
- Image center
- Image size
- Up vector



Orthographic ray generation

- Direction is constant
- Origin = center + (x-0.5)*size*up + (y-0.5)*size*horizontal



Other weird cameras

- E.g. fish eye, omnimax, panorama

Overview of today

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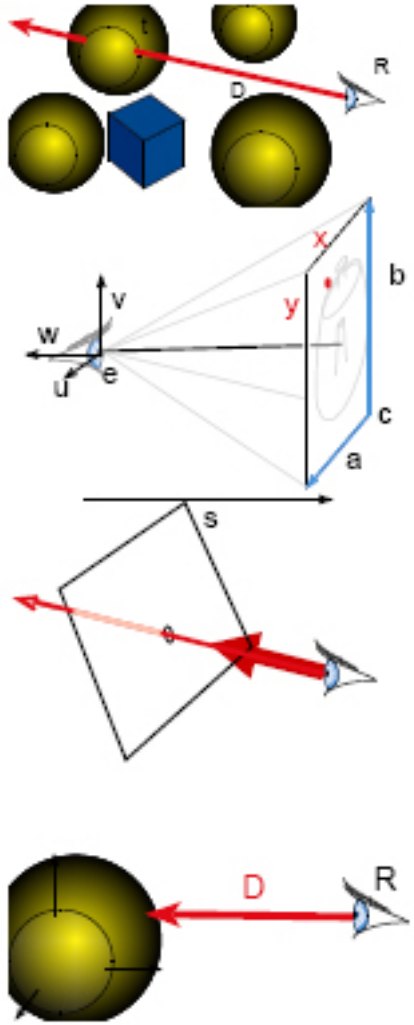
- Ray-plane intersection
- Ray-sphere intersection



Ray Casting

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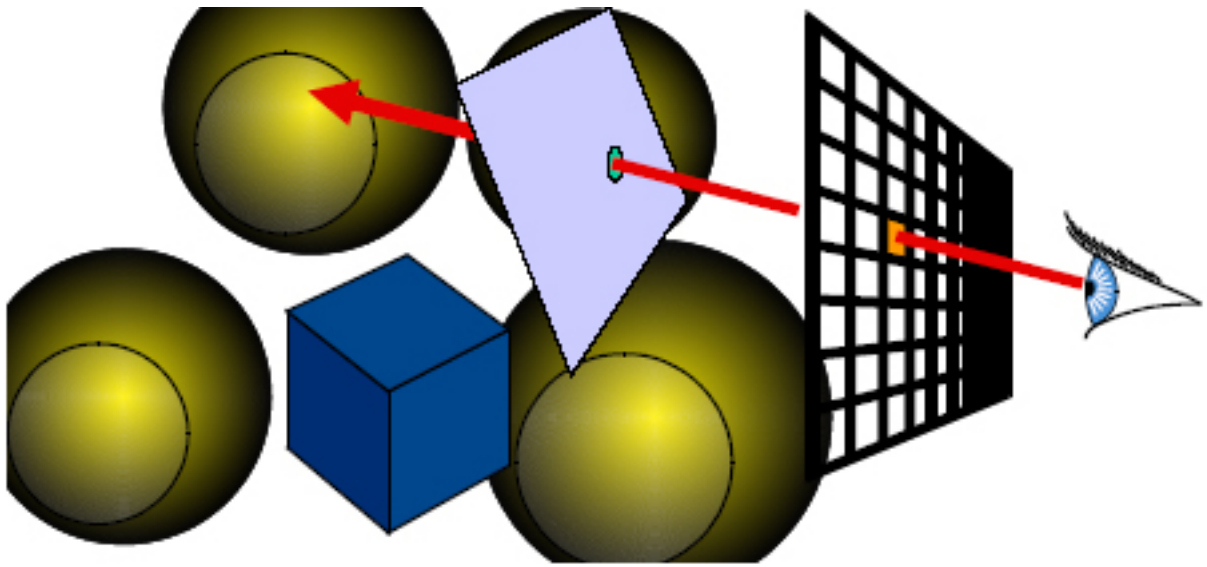
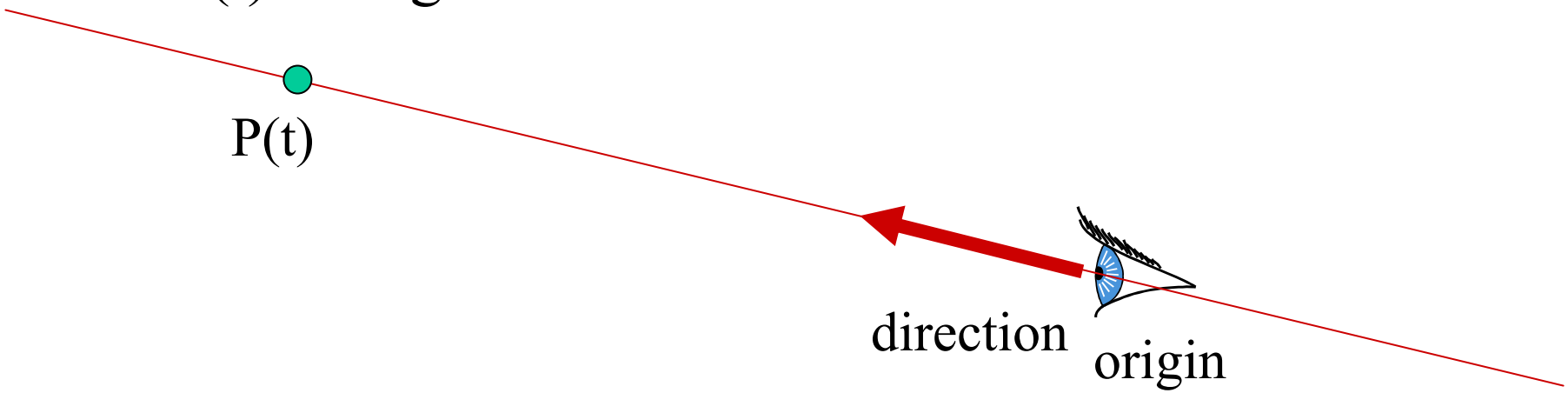
First we will study ray-plane intersection



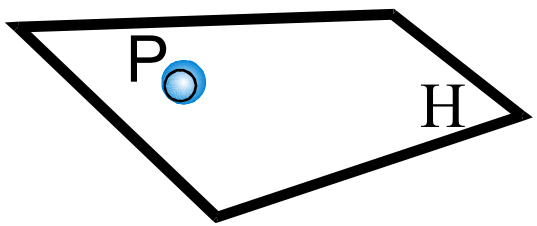
Recall: Ray representation

- Two vectors:
  - Origin
  - Direction (normalized)
- Parametric line
  - P(t) = origin + t * direction



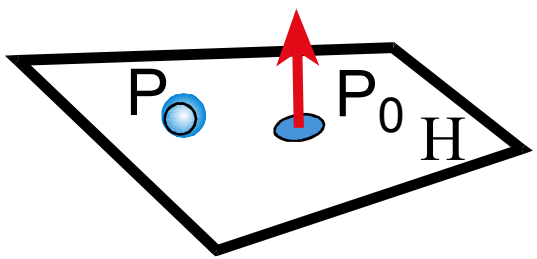
3D plane equation

- Implicit plane equation
  $H(p) = Ax+By+Cz+D = 0$
- Gradient of H?



3D plane equation

- Implicit plane equation
  $H(p) = Ax+By+Cz+D = 0$
- Gradient of H?
- Plane defined by
  - P0(x,y,z,1)
  - n(A, B, C, 1)

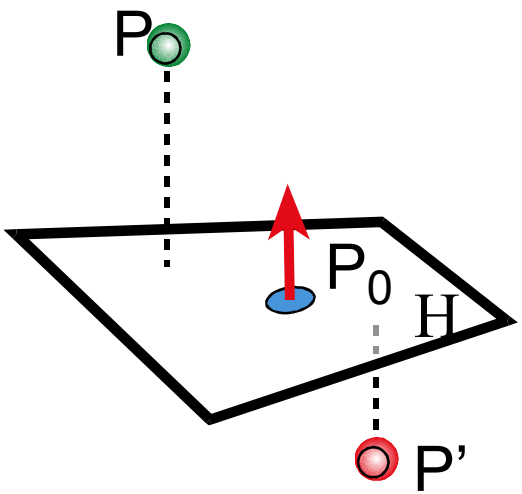


Explicit vs. implicit?

- Plane equation is implicit
  - Solution of an equation
  - Does not tell us how to generate a point on the plane
  - Tells us how to check that a point is on the plane
- Ray equation is explicit
  - Parametric
  - How to generate points
  - Harder to verify that a point is on the ray

Plane-point distance

- Plane Hp=0
- If n is normalized
  d=HP
- Signed distance!



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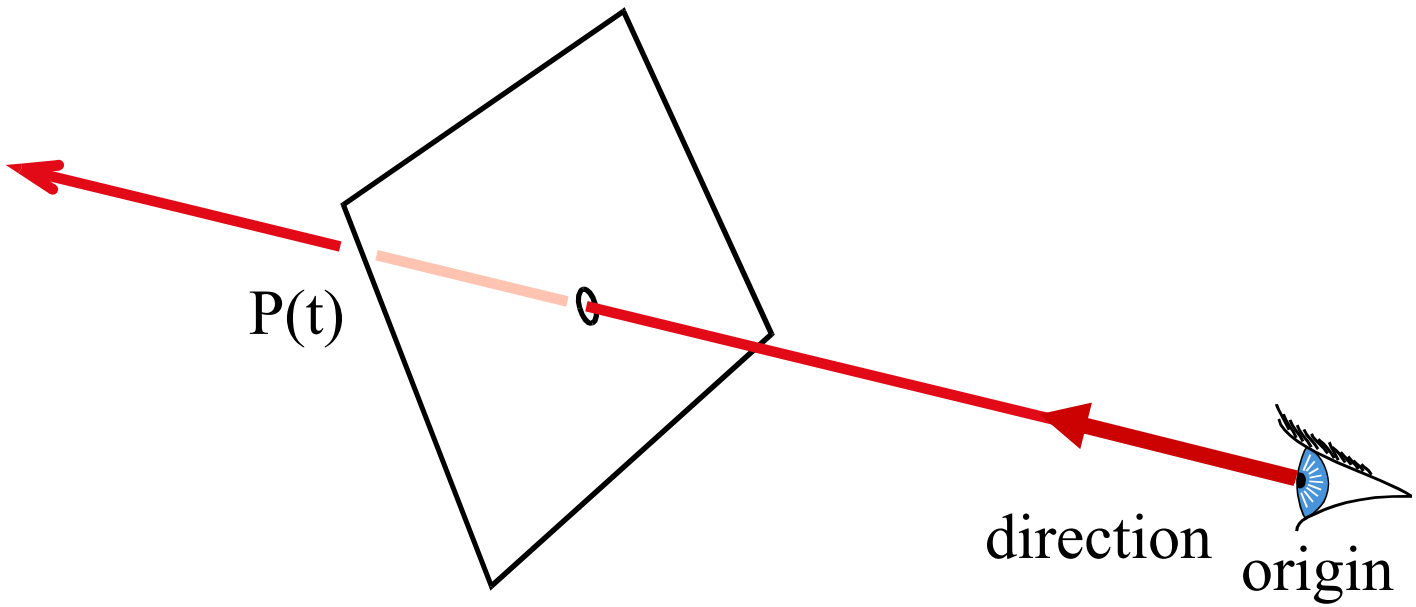
- Ray equation is explicit
  - Parametric
  - How to generate points
  - Harder to verify that a point is on the ray
- Exercise: explicit plane and implicit ray

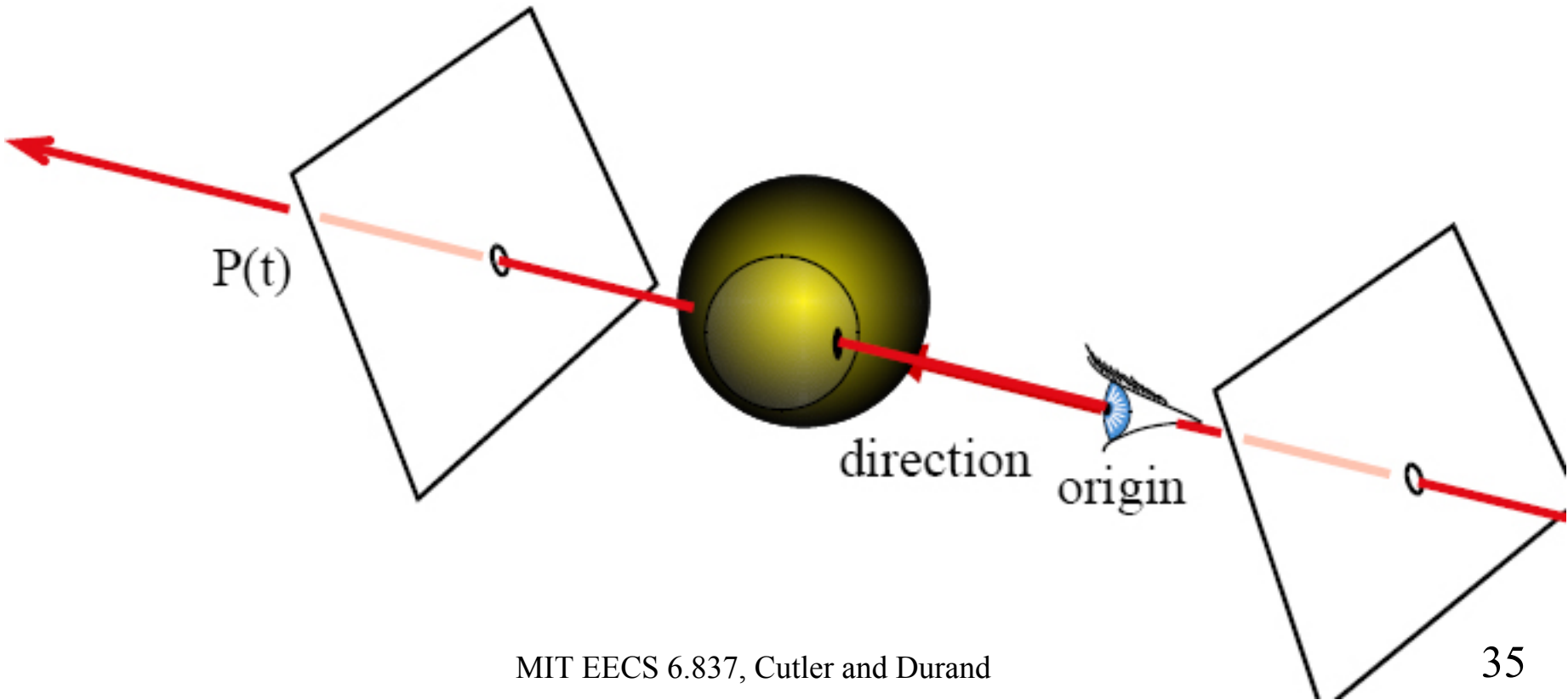
Line-plane intersection

- Insert explicit equation of line into implicit equation of plane



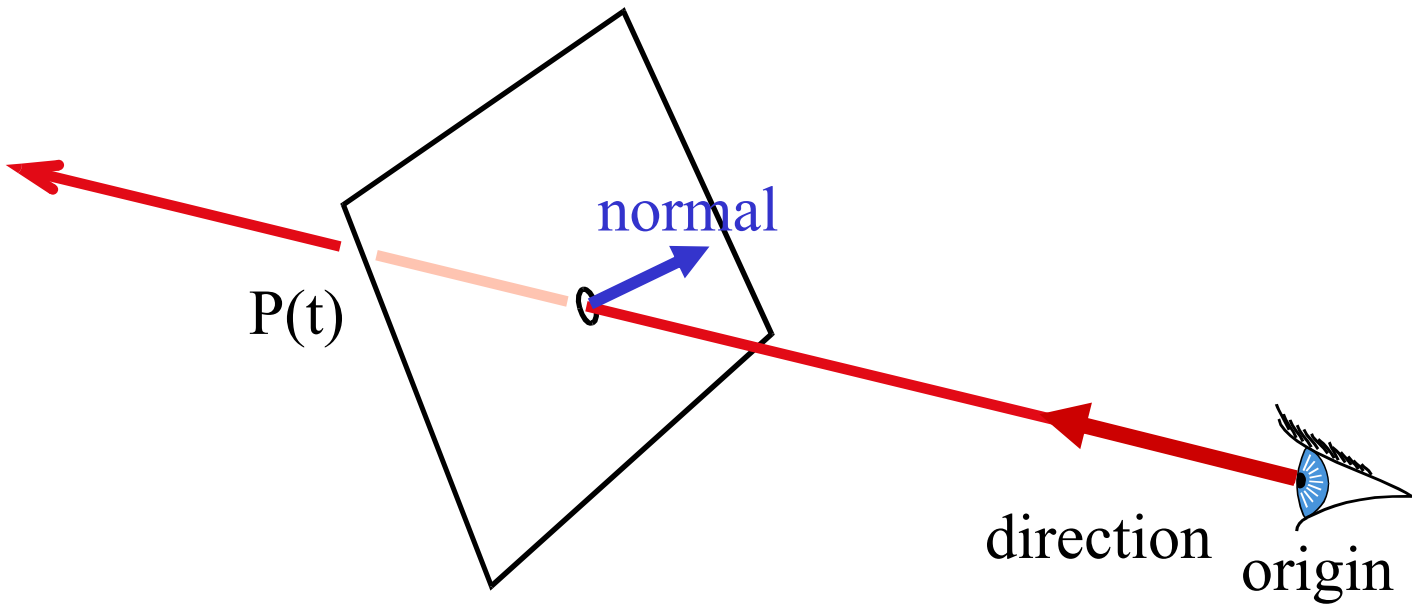
Additional house keeping

- Verify that intersection is closer than previous
- Verify that it is in the allowed range
  (in particular not behind the camera, t<0)



Normal

- For shading (recall, diffuse: dot product between light and normal)
- Simply the normal to the plane



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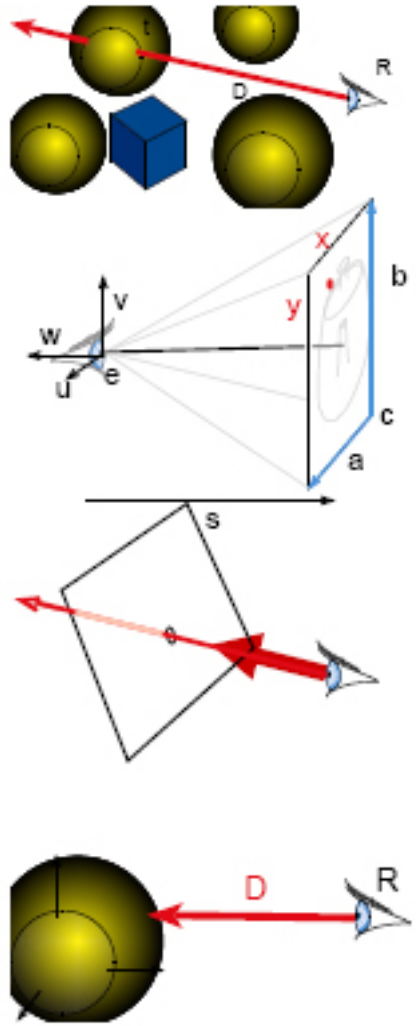
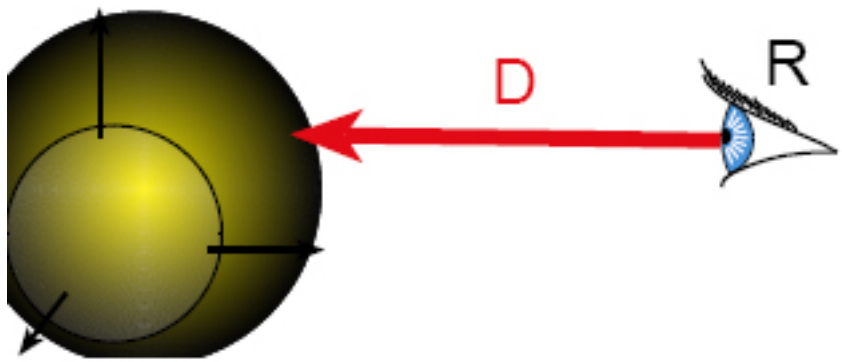
- Ray-sphere intersection



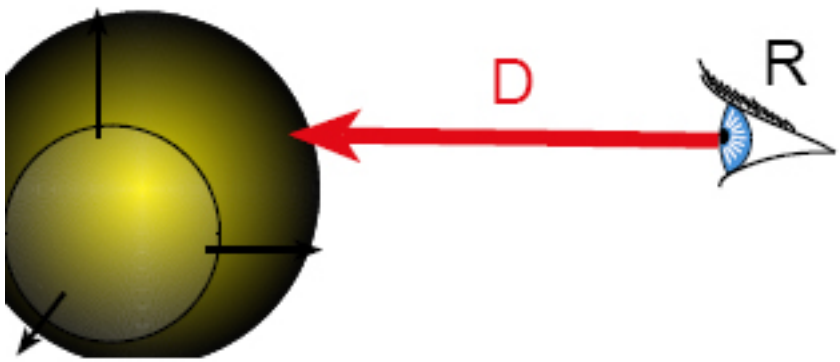
Sphere equation

- Sphere equation (implicit): $\|\mathbf{P}\overline{}^2 = r^2$
- (assume centered at origin, easy to translate)



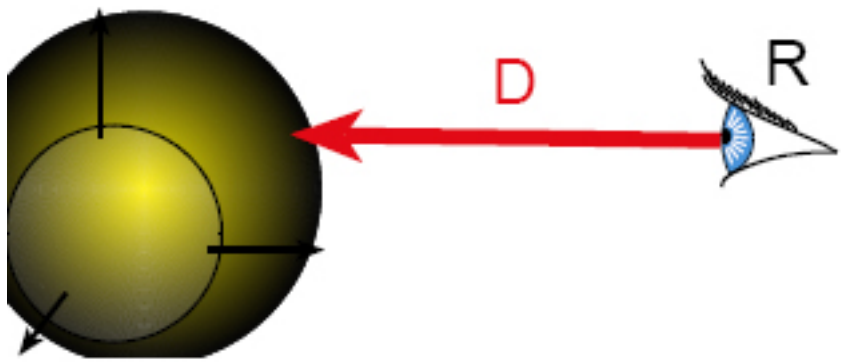
Ray-Sphere Intersection

- Sphere equation (implicit): $||\mathbf{P}-\mathbf{C}||^2 = r^2$
- Ray equation (explicit): $\mathbf{P}(t) = \mathbf{R}+t\mathbf{D}$ with $||\mathbf{D}|| = 1$
- Intersection means both are satisfied



Ray-Sphere Intersection

$$
\begin{aligned}
0 &= \mathbf{P} \cdot \mathbf{P} - r^2 \\
&= (\mathbf{R} + t\mathbf{D}) \cdot (\mathbf{R} + t\mathbf{D}) - r^2 \\
&= \mathbf{R} \cdot \mathbf{R} + 2t\mathbf{D} \cdot \mathbf{R} + t^2\mathbf{D}^2 - r^2 \\
&= t^2 + 2t\mathbf{D} \cdot \mathbf{R} + \mathbf{R} \cdot \mathbf{R} - r^2
\end{aligned}
$$



Ray-Sphere Intersection

- This is just a quadratic $at^2 + bt + c = 0$, where

  $a = 1$

  $b = 2\mathbf{D}.\mathbf{R}$

  $c = \mathbf{R}.\mathbf{R} - \mathbf{r}^2$

- With discriminant

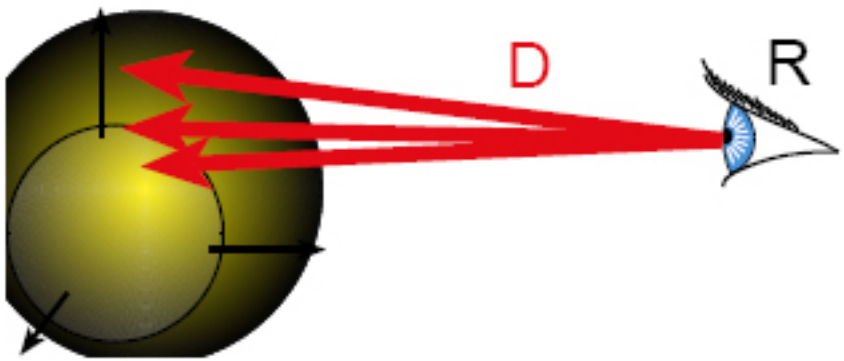
$$d = \sqrt{b^2 - 4ac}$$

- and solutions

$$t_{\pm} = \frac{-b \pm d}{2a}$$

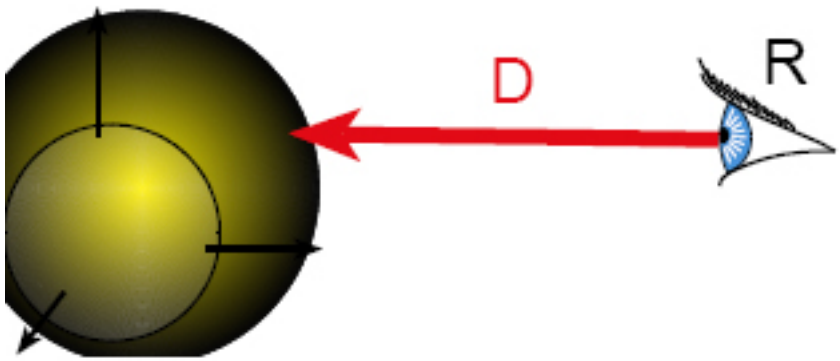
Ray-Sphere Intersection

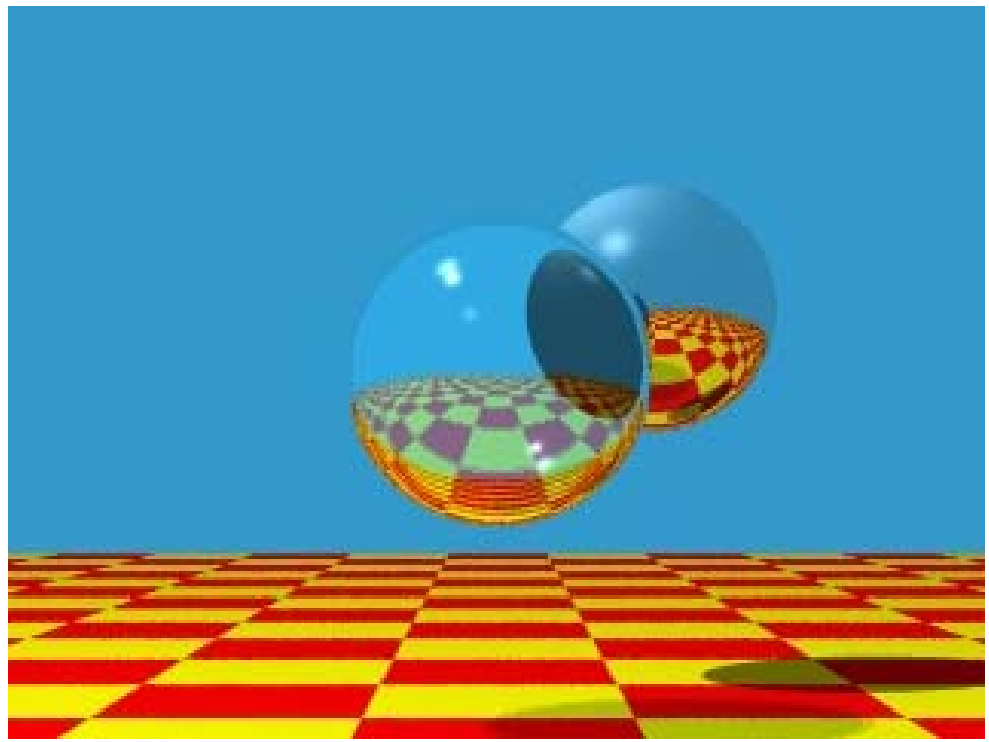
- Discriminant $d = \sqrt{b^2 - 4ac}$
- Solutions $t_{\pm} = \dfrac{-b \pm d}{2a}$
- Three cases, depending on sign of $b^2 - 4ac$
- Which root ($t+$ or $t-$) should you choose?
  - Closest positive! (usually t-)



Ray-Sphere Intersection

- So easy that all ray-tracing images have spheres!

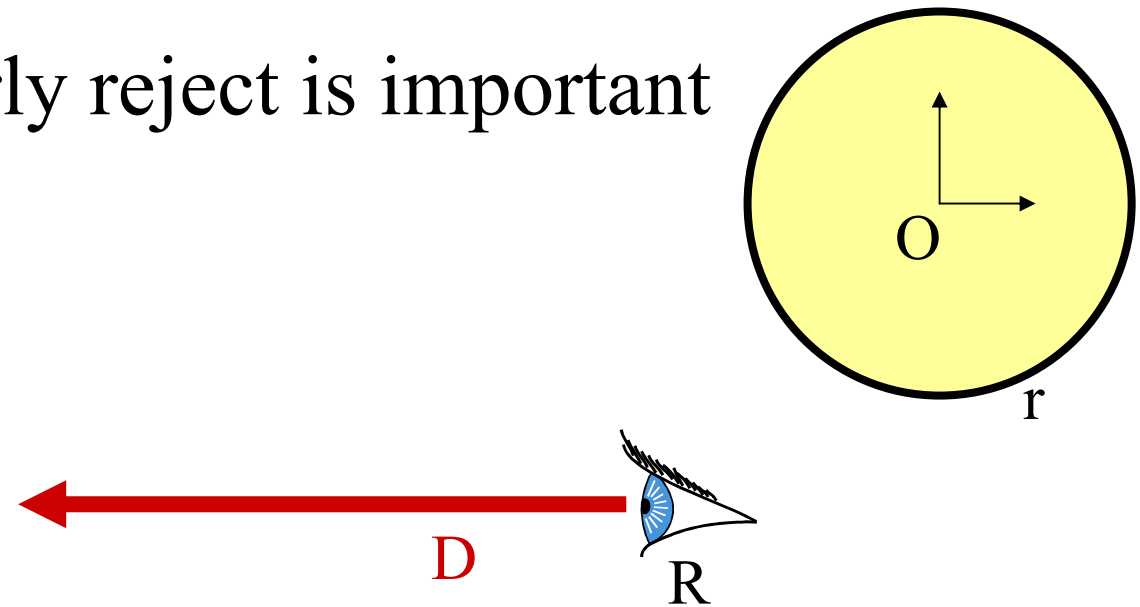




Geometric ray-sphere intersection

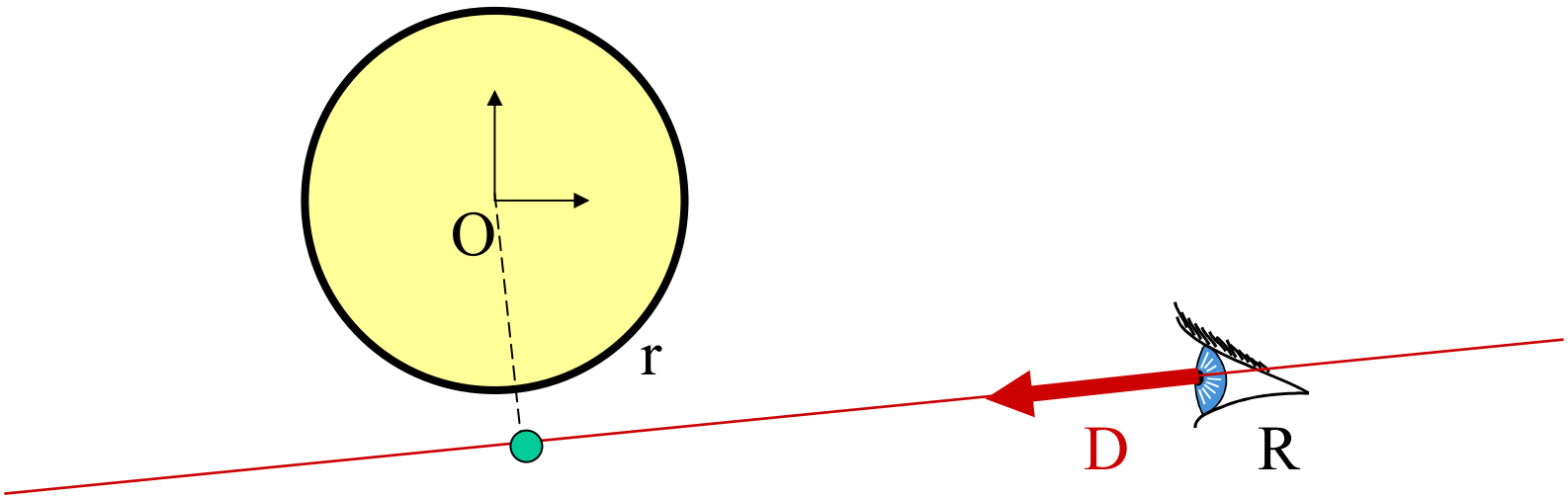
- Try to shortcut (easy reject)
- e.g.: if the ray is facing away from the sphere
- Geometric considerations can help

- In general, early reject is important



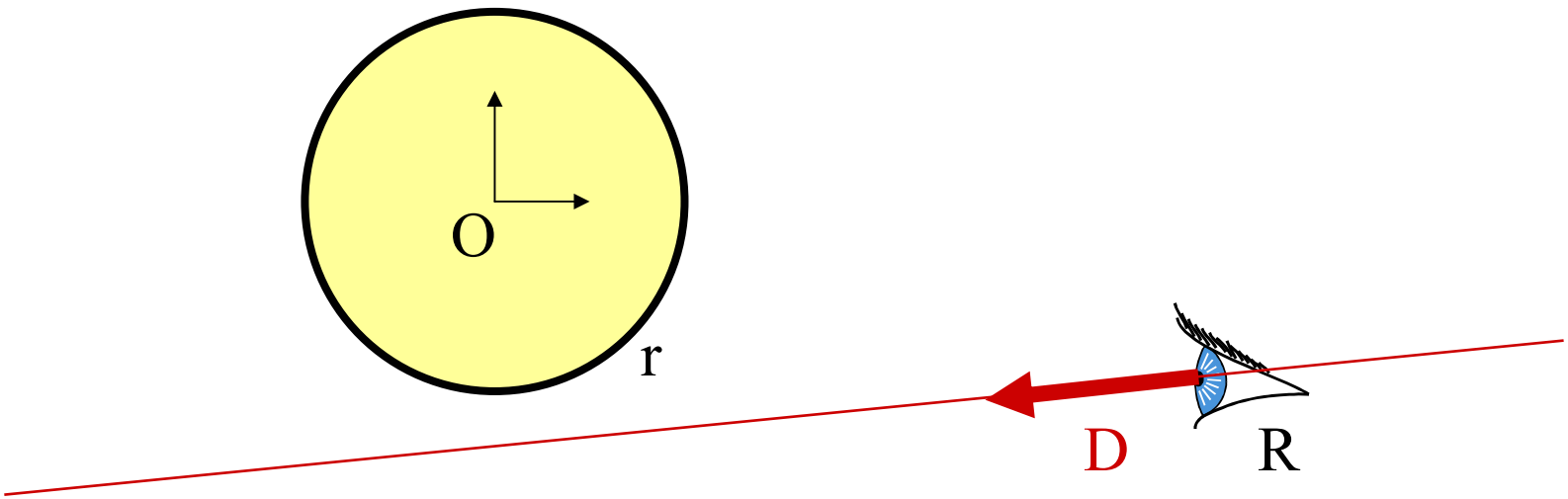
Geometric ray-sphere intersection

- What geometric information is important?
  - Inside/outside
  - Closest point
  - Direction



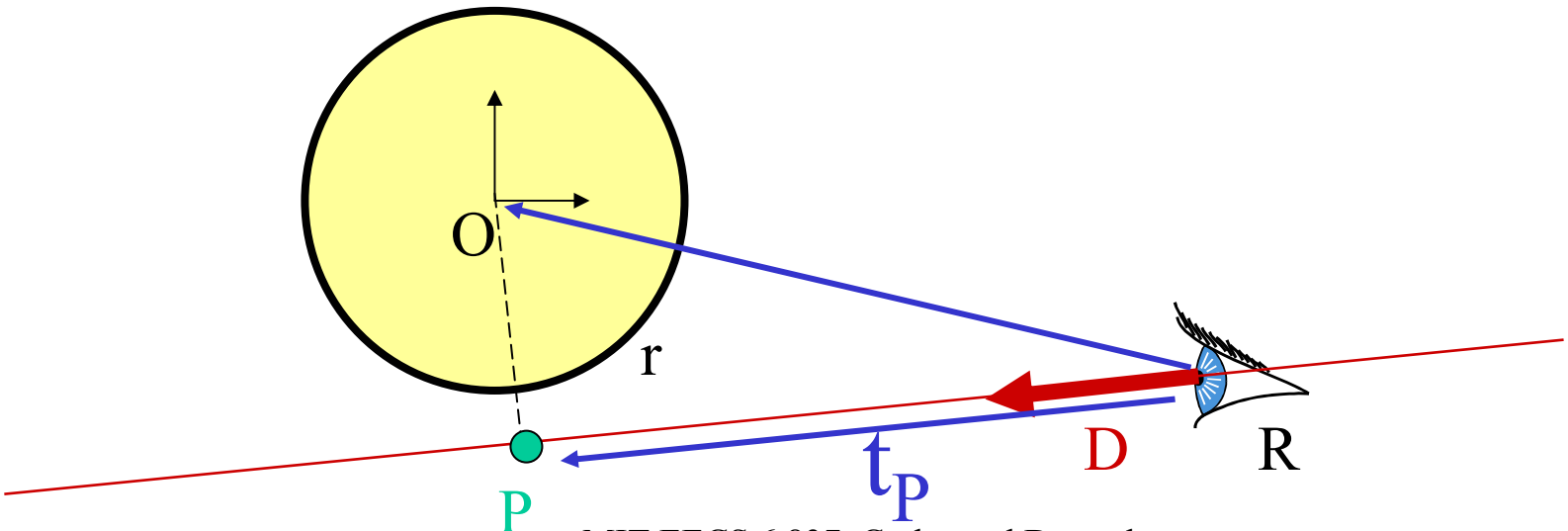
Geometric ray-sphere intersection

- Find if the ray's origin is outside the sphere
  - $R^2 > r^2$
  - If inside, it intersects
  - If on the sphere, it does not intersect (avoid degeneracy)



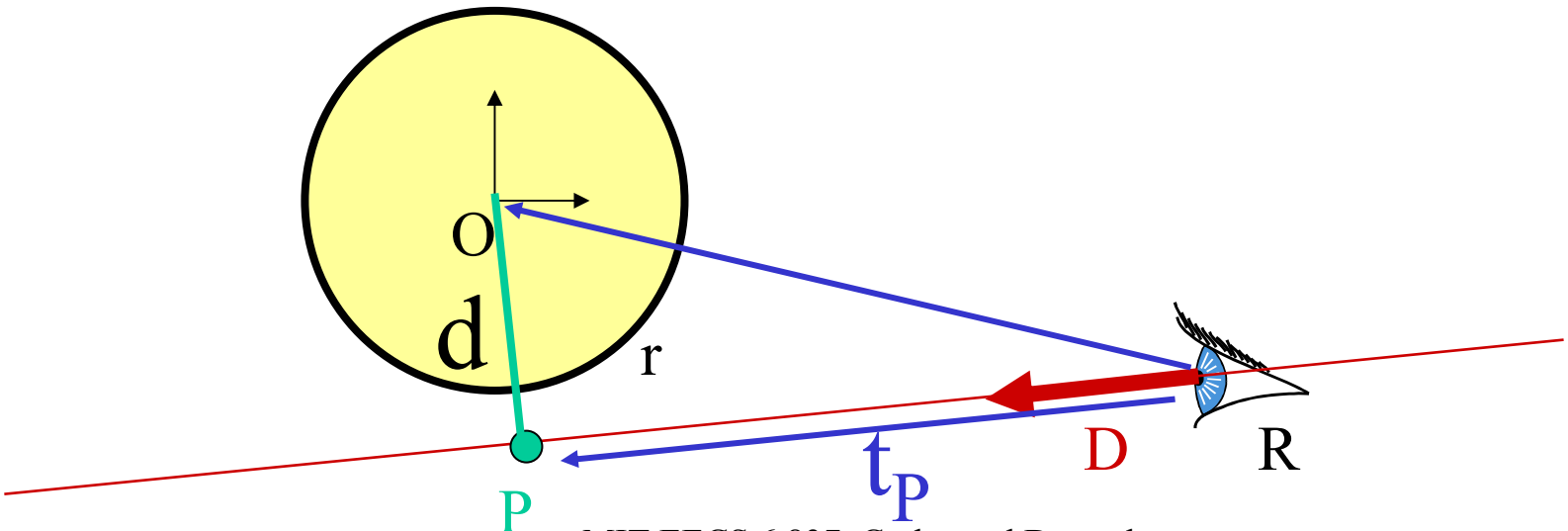
Geometric ray-sphere intersection

- Find if the ray's origin is outside the sphere
- Find the closest point to the sphere center
  - t_P=RO.D
  - If t_P<0, no hit



Geometric ray-sphere intersection

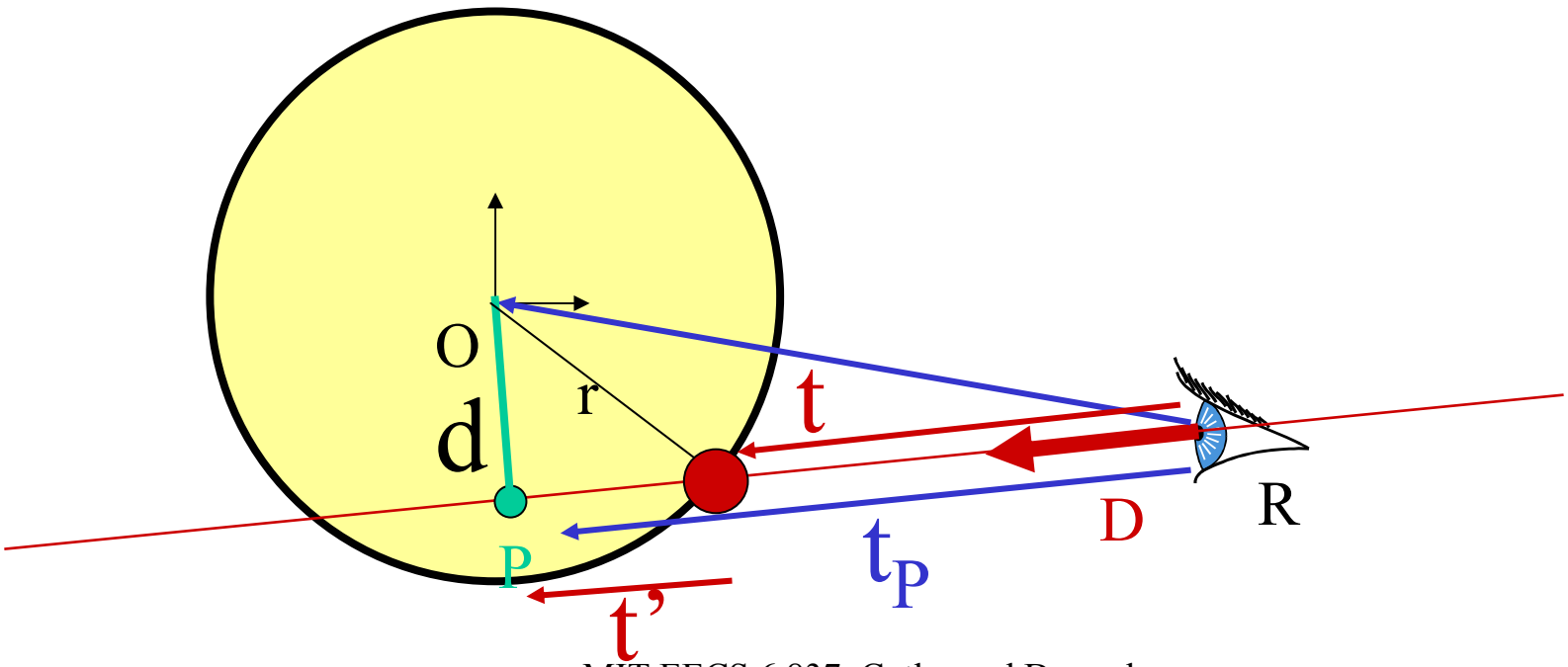
- Find if the ray's origin is outside the sphere
- Find the closest point to the sphere center
  - If $t_P<0$, no hit
- Else find squared distance d^2
  - Pythagoras: $d^2=R^2-t_P^2$
  - … if $d^2> r^2$ no hit



Geometric ray-sphere intersection

- Find if the ray's origin is outside the sphere
- Find the closest point to the sphere center
  - If $t_P<0$, no hit
- Else find squared distance d^2
  - if $d^2 > r^2$ no hit

- If outside $t = t_P - t'$
  - $t'^2+d^2=r^2$
- If inside $t = t_P + t'$

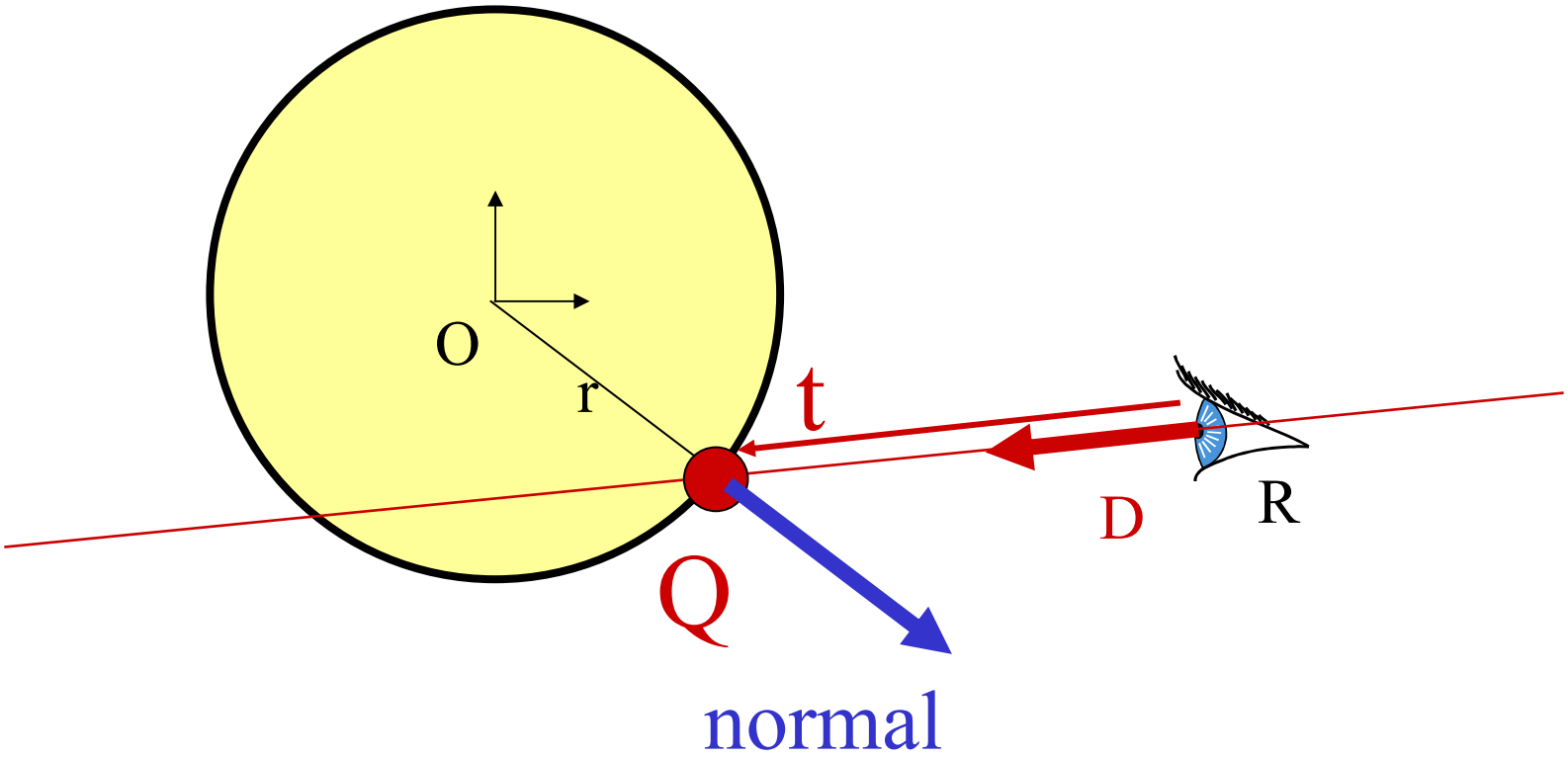


Geometric vs. algebraic

- Algebraic was more simple (and more generic)
- Geometric is more efficient
  - Timely tests
  - In particular for outside and pointing away

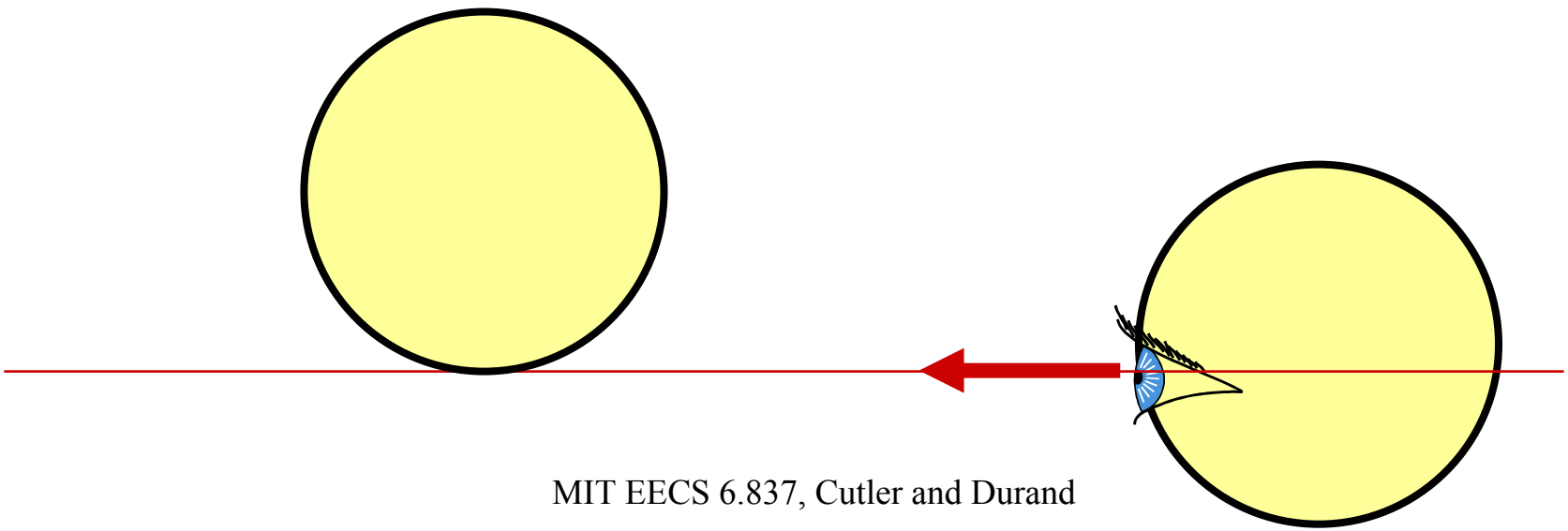
Normal

- Simply Q/||Q||



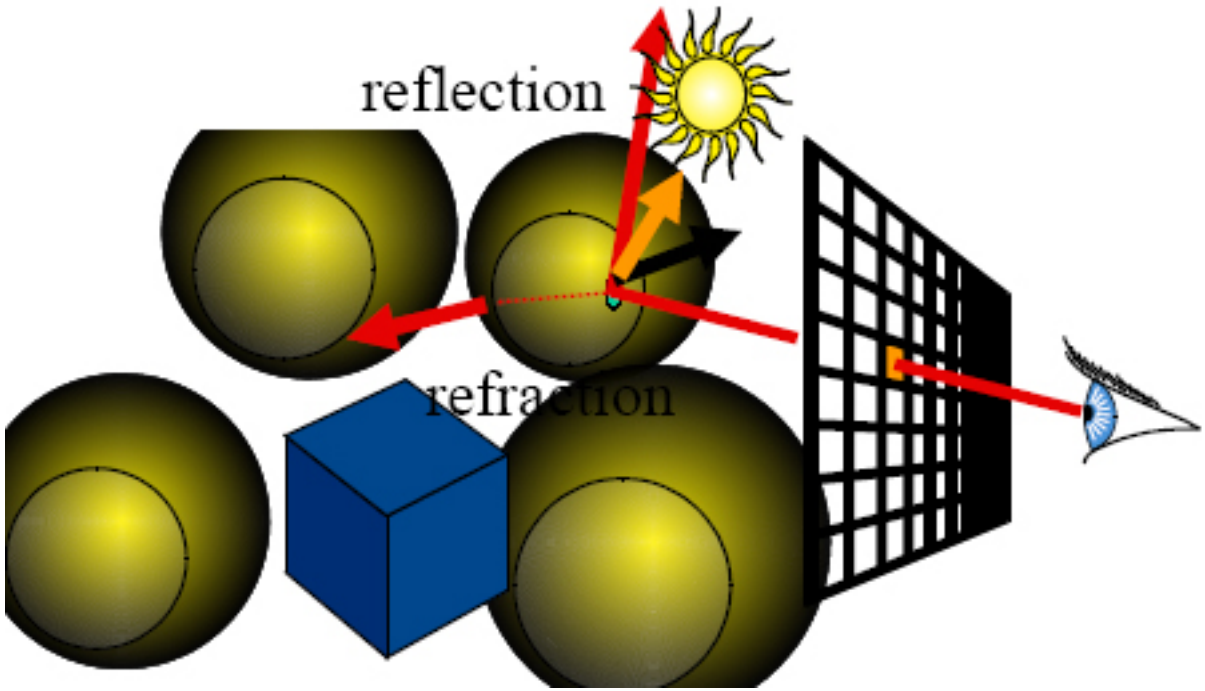
Precision

- What happens when
  - Origin is on an object?
  - Grazing rays?
- Problem with floating-point approximation



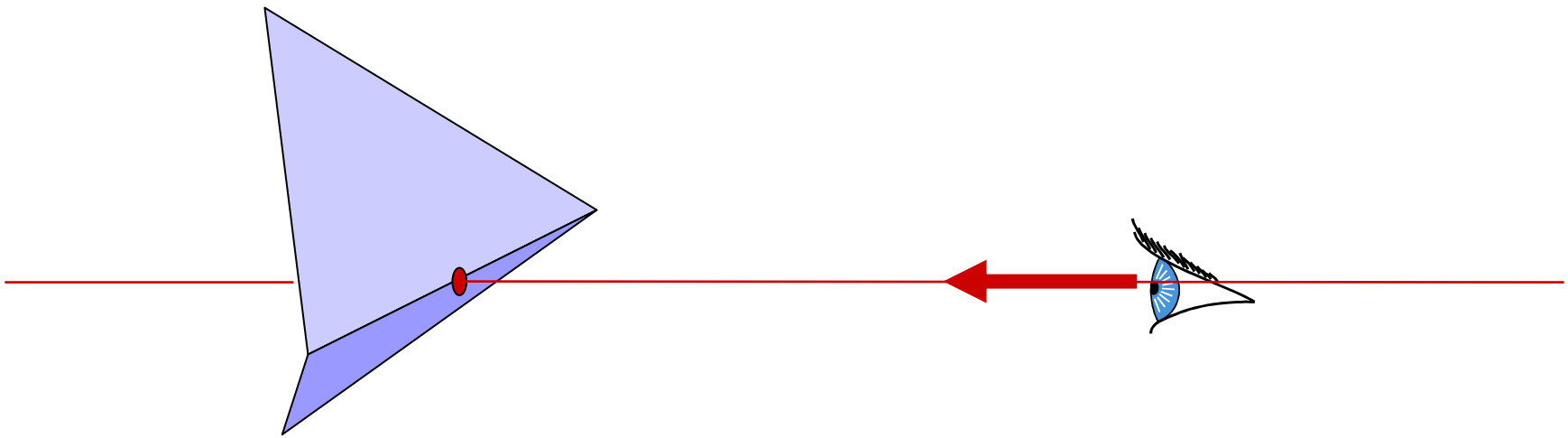
The evil ε

- In ray tracing, do NOT report intersection for rays starting at the surface (no false positive)
  - Because secondary rays
  - Requires epsilons



The evil ε: a hint of nightmare

- Edges in triangle meshes
  - Must report intersection (otherwise not watertight)
  - No false negative

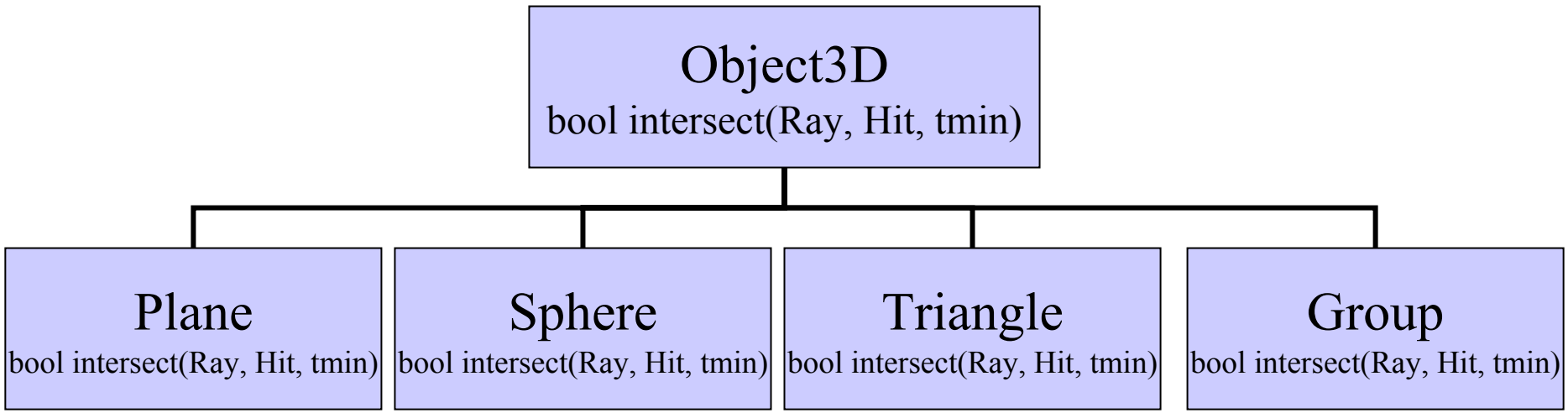


Assignment 1

- Write a basic ray caster
  - Orthographic camera
  - Spheres
  - Display: constant color and distance
- We provide
  - Ray
  - Hit
  - Parsing
  - And linear algebra, image

Object-oriented design

- We want to be able to add primitives easily
  - Inheritance and virtual methods
- Even the scene is derived from Object3D!



Ray

```
//////////
class Ray {
//////////

  Ray () {}
  Ray (const Vec3f &dir, const Vec3f &orig)
  {_dir =dir; _orig=orig;}
  Ray (const Ray& r) {*this=r;}

  const Vec3f &origin() {return _orig;}
  const Vec3f &direction() {return &dir;}
  Vec3f pointAtParameter (float t) {return _orig+t*_dir;}

private:
  Vec3f _dir;
  Vec3f _orig;

};
```

Hit

- Store intersection point & various information

```
/////////
class Hit {
/////////

  float _t;
  Vec3f _color;
  //Material *_material;
  //Vec3f _normal;
};
```

Tasks

- Abstract Object3D
- Sphere and intersection
- Scene class
- Abstract camera and derive Orthographic
- Main function

Thursday: More Ray Casting

- Other primitives
  - Boxes
  - Triangles
  - IFS?
- Antialiasing